

Scenario Min-Max Optimization and the Risk of Empirical Costs

Algo Carè

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^aPolitecnico di Milano ^bUniversity of Brescia

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Convex problem

$$\min_{\theta} \ell(\theta)$$

Convex problem

$$\min_{\theta} \ell(\theta)$$

θ design parameter(s)

Convex problem

$$\min_{\theta} \ell(\theta, \delta)$$

θ design parameter(s)

Convex problem

$$\min_{\theta} \ell(\theta, \delta)$$

θ design parameter(s)

δ uncertain parameter

Convex problem

$$\min_{\theta} \ell(\theta, \delta)$$

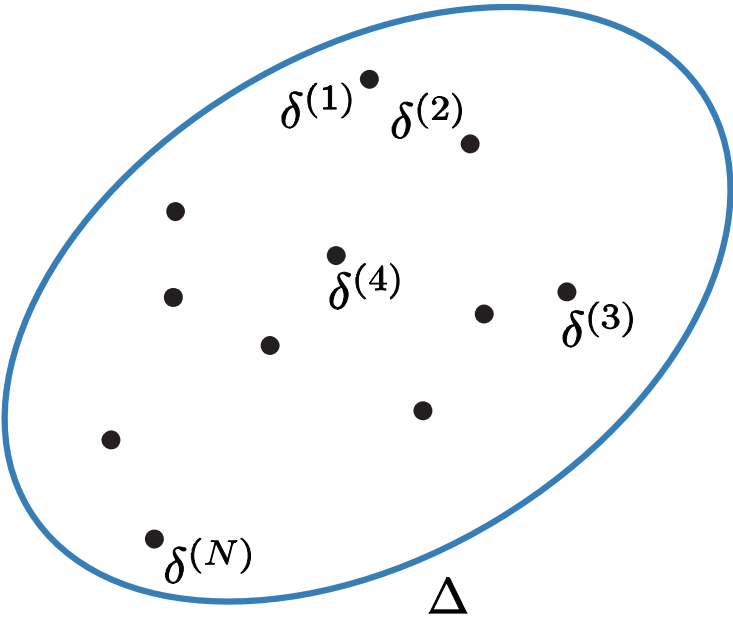
θ design parameter(s)

δ uncertain parameter

Uncertain problem!

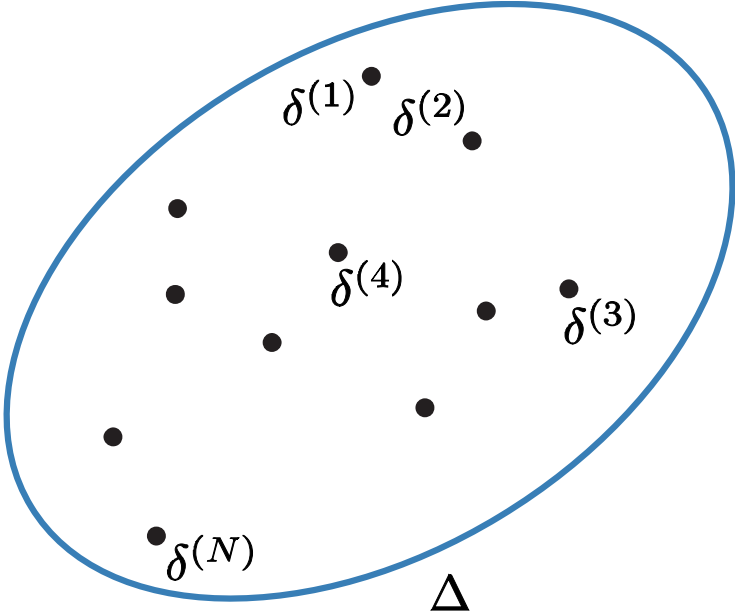
The Scenario Approach

Scenario Approach



Scenario Approach

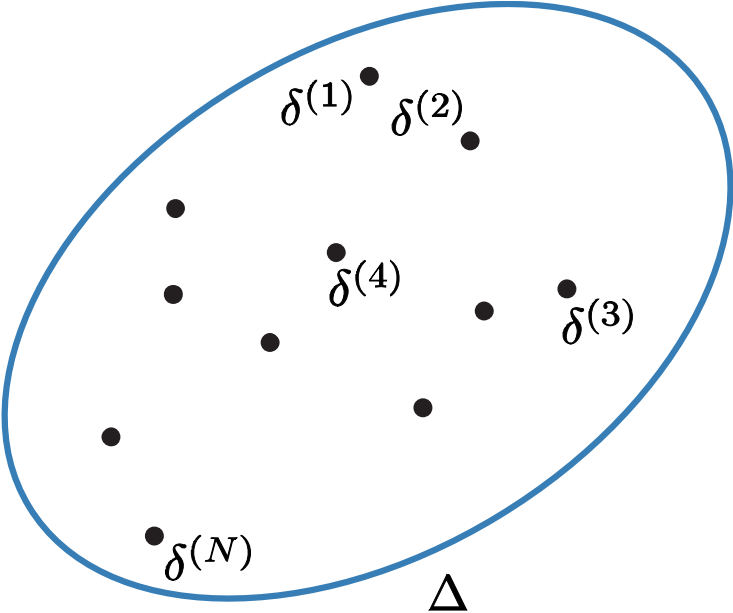
\mathbb{P}



Scenario Approach

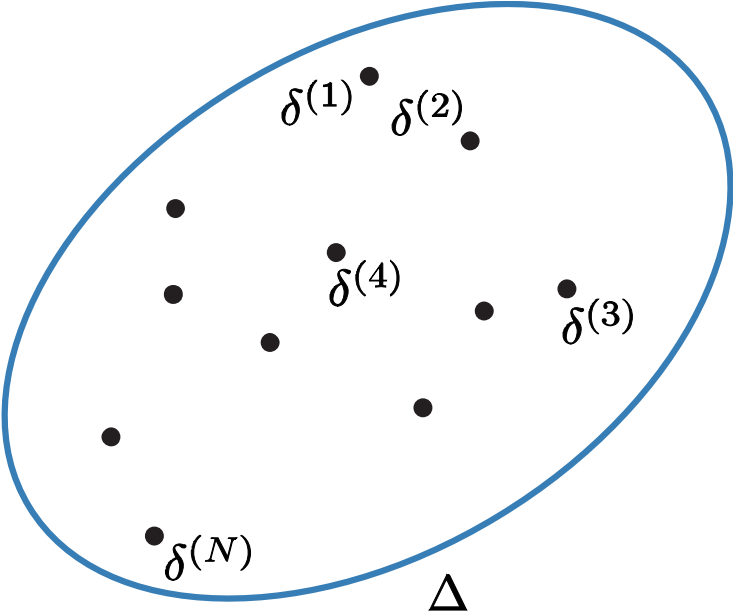


unknown



Scenario Approach

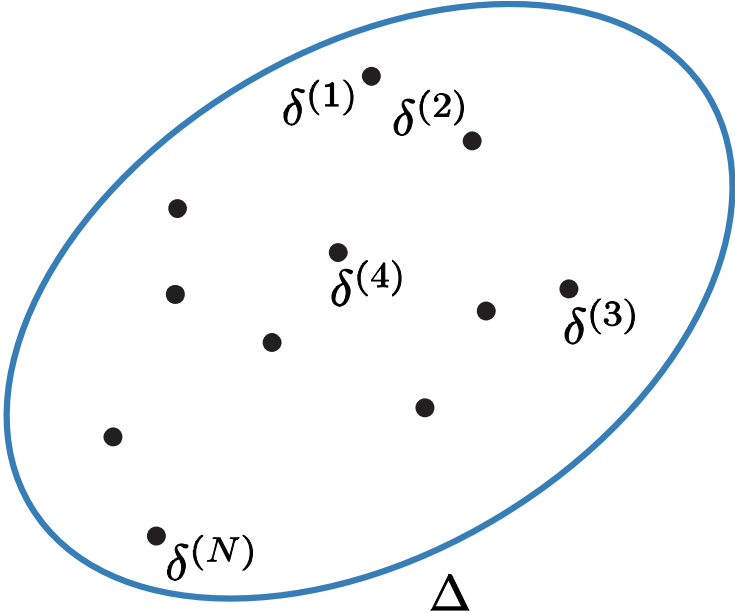
\mathbb{P} unknown



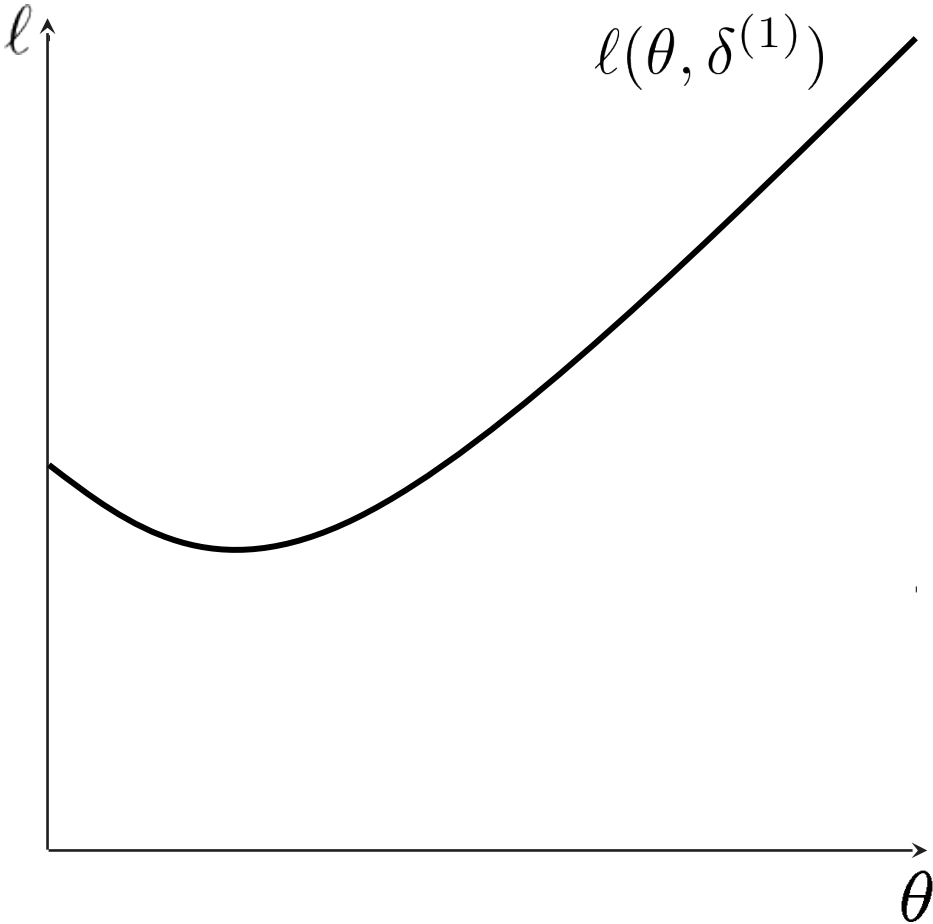
$$\delta^{(1)} \rightarrow \ell(\theta, \delta^{(1)})$$

Scenario Approach

\mathbb{P} unknown

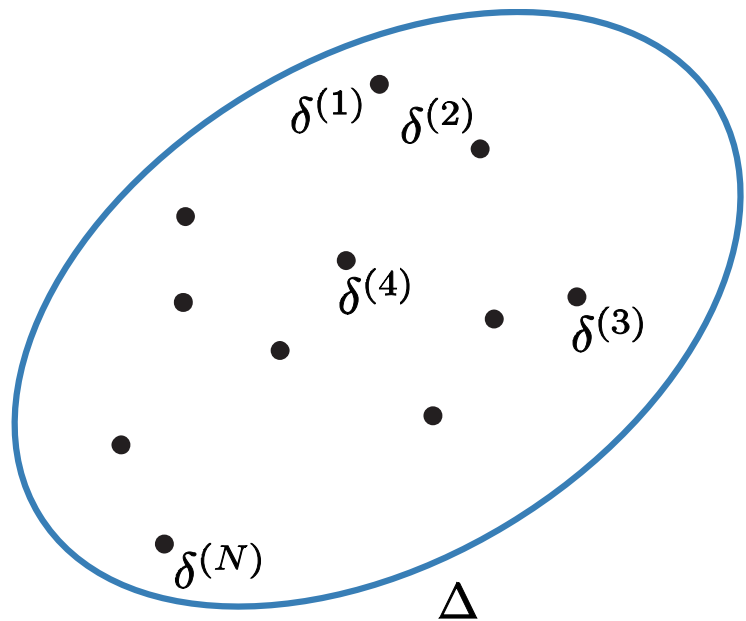


$$\delta^{(1)} \rightarrow \ell(\theta, \delta^{(1)})$$



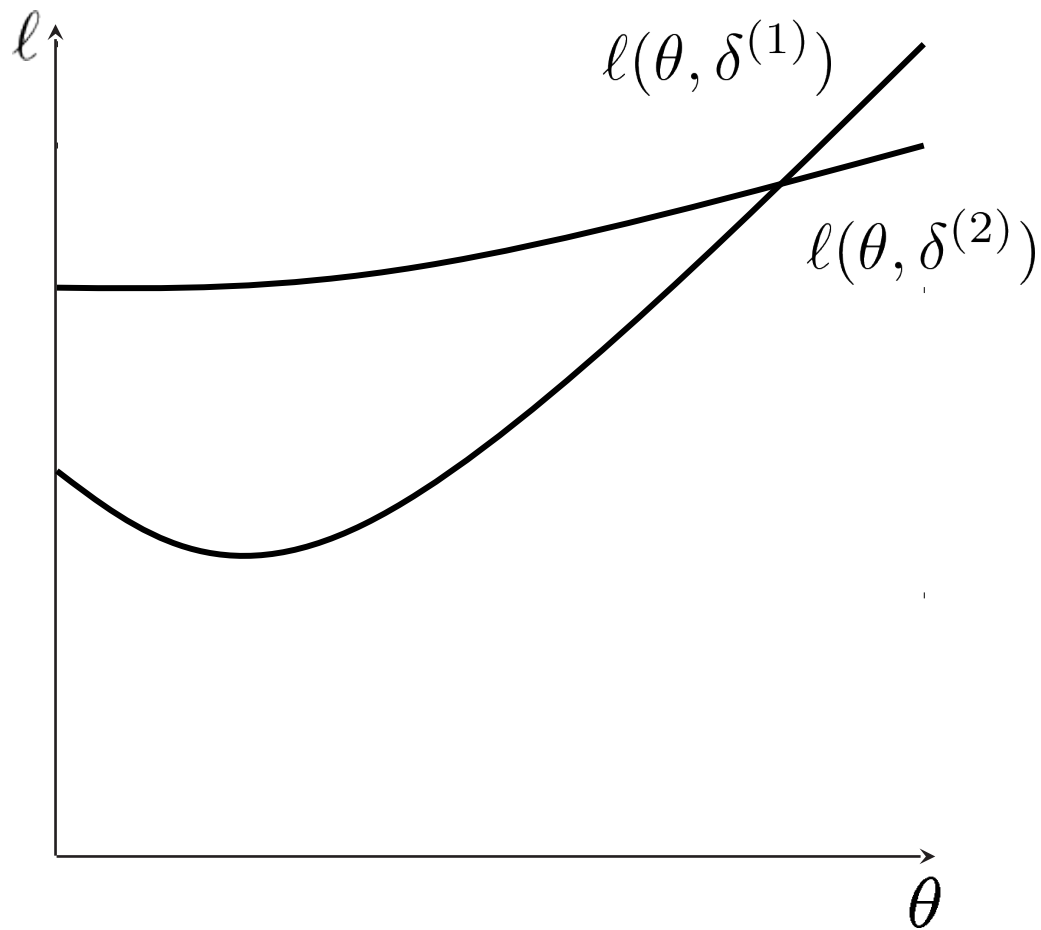
Scenario Approach

\mathbb{P} unknown



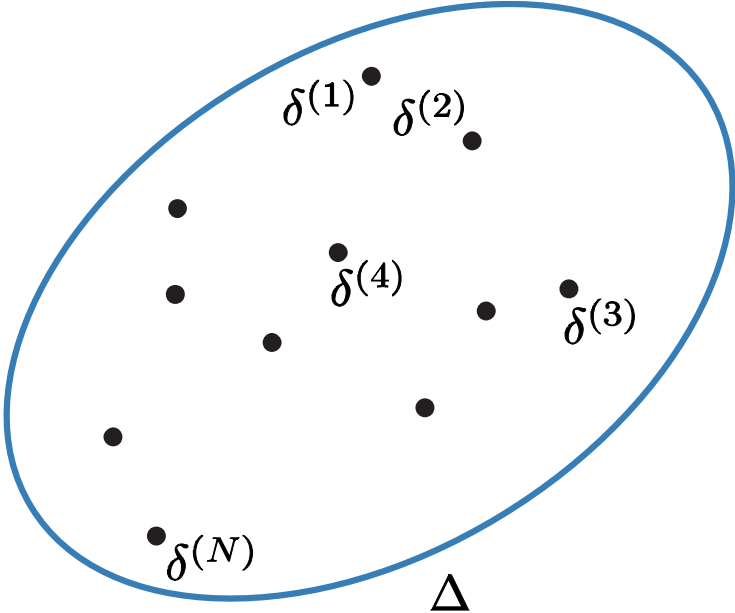
$$\delta^{(1)} \rightarrow \ell(\theta, \delta^{(1)})$$

$$\delta^{(2)} \rightarrow \ell(\theta, \delta^{(2)})$$

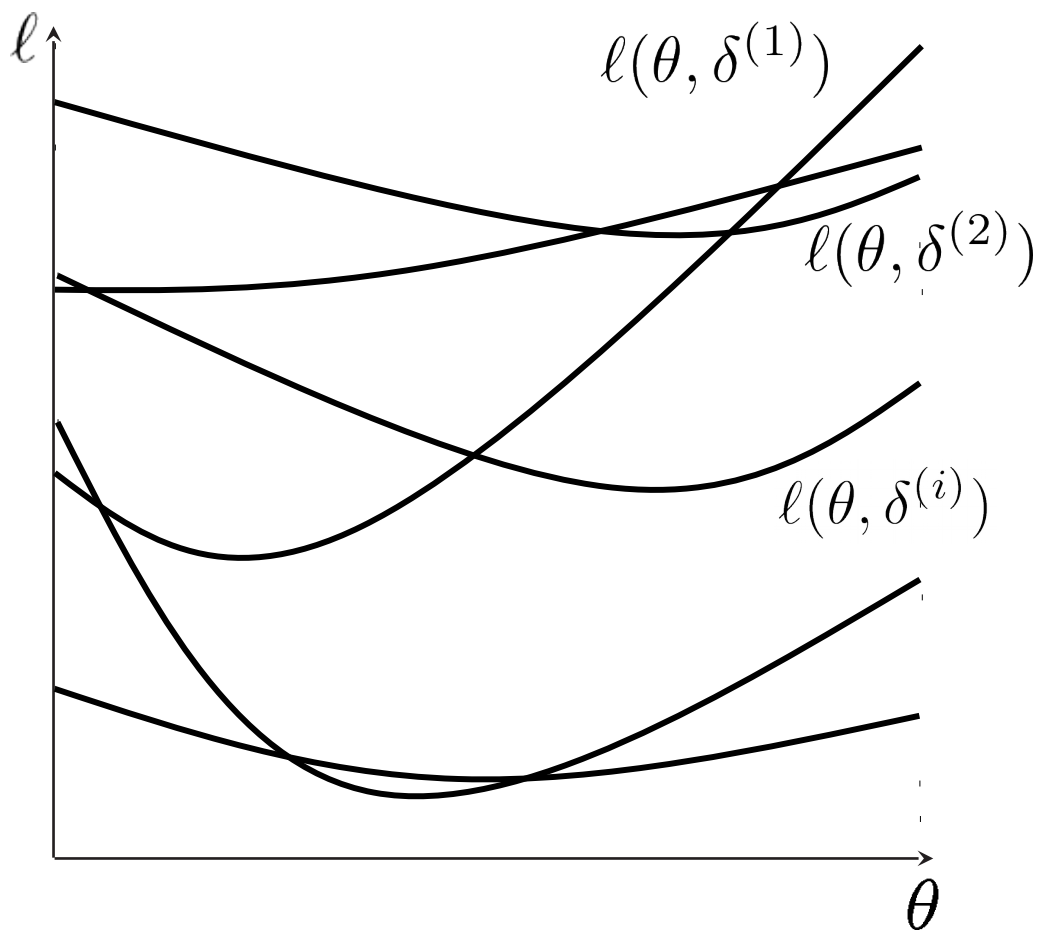


Scenario Approach

\mathbb{P} unknown

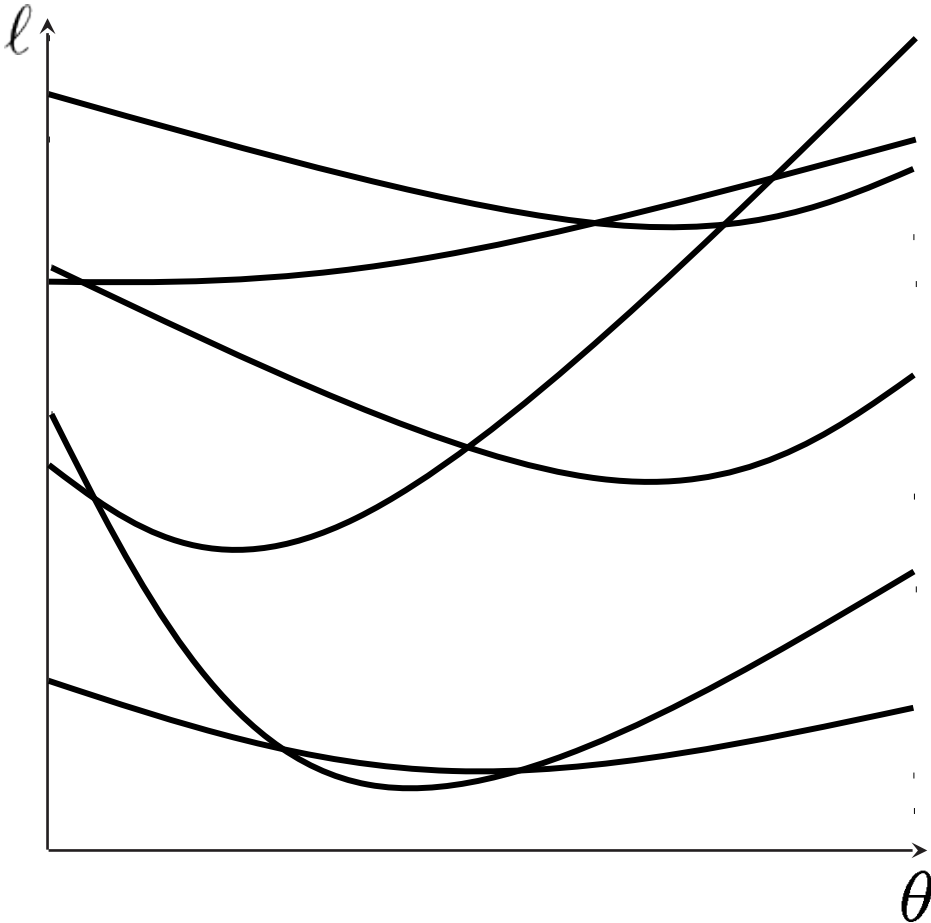
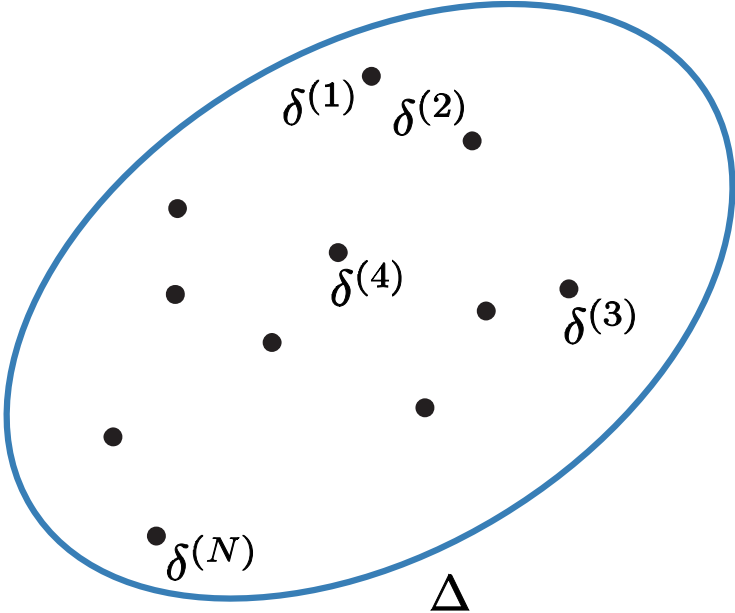


$$\begin{aligned} \delta^{(1)} &\rightarrow \ell(\theta, \delta^{(1)}) \\ \delta^{(2)} &\rightarrow \ell(\theta, \delta^{(2)}) \\ &\vdots \\ \delta^{(N)} &\rightarrow \ell(\theta, \delta^{(N)}) \end{aligned}$$



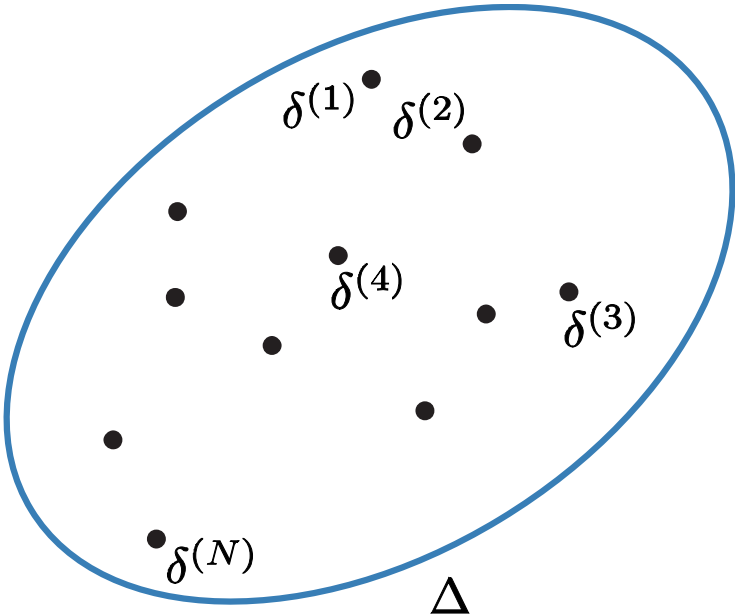
Scenario Approach

\mathbb{P} unknown

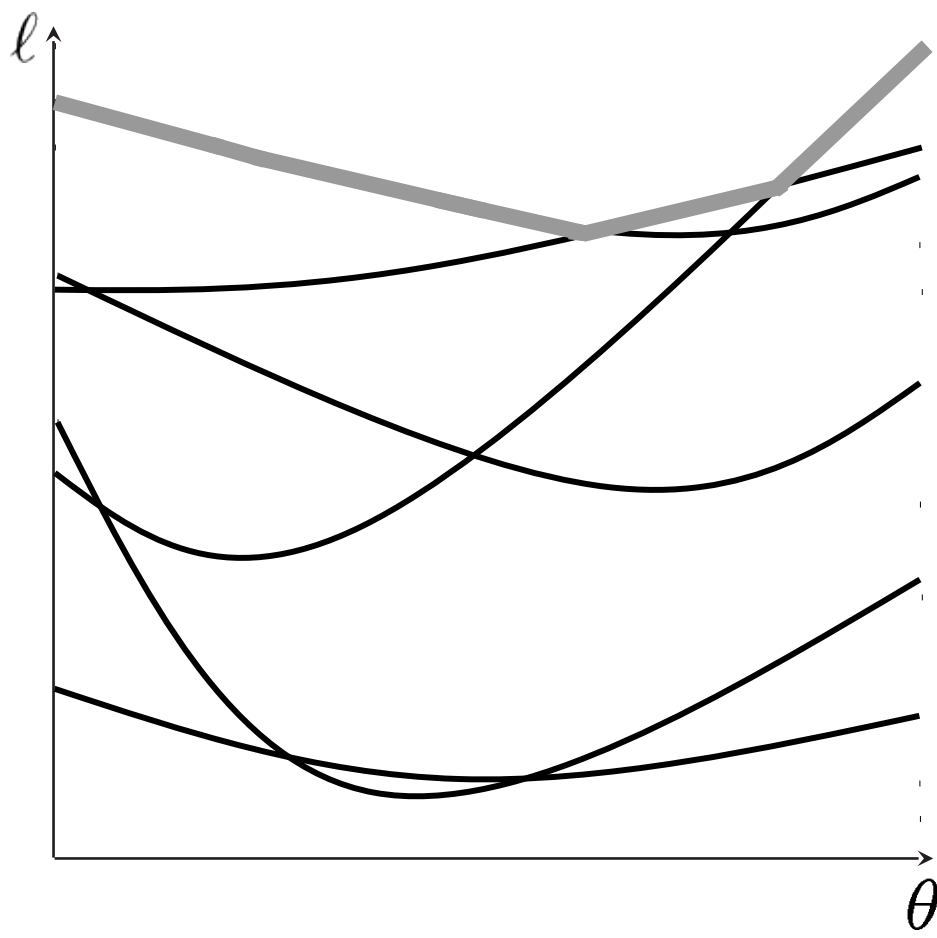


Scenario Approach

\mathbb{P} unknown

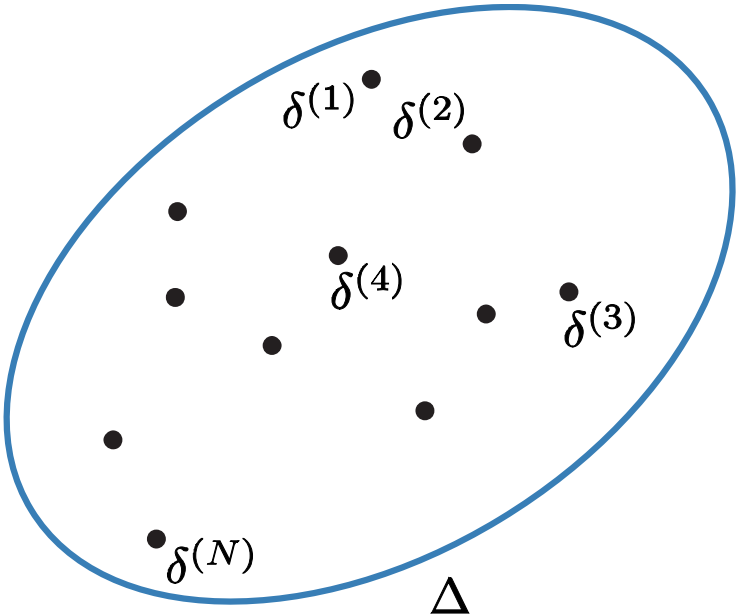


$$\max_{i=1, \dots, N} \ell(\theta, \delta^{(i)})$$

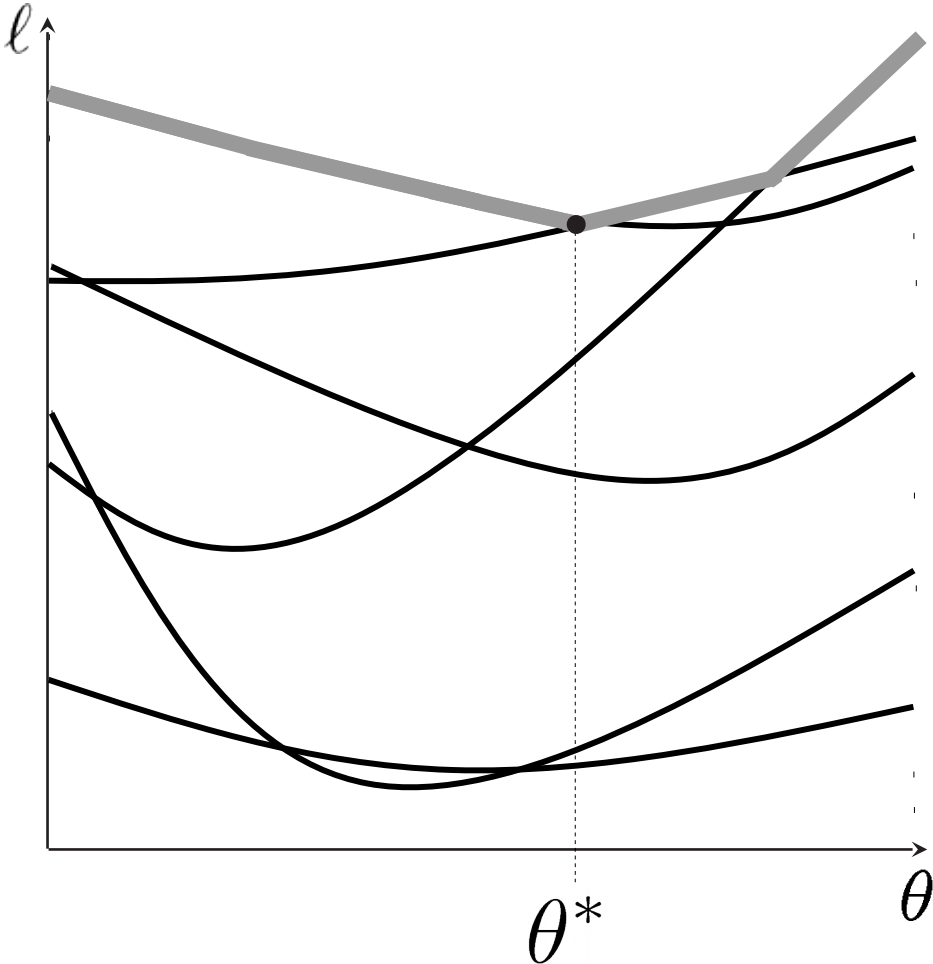


Scenario Approach

\mathbb{P} unknown

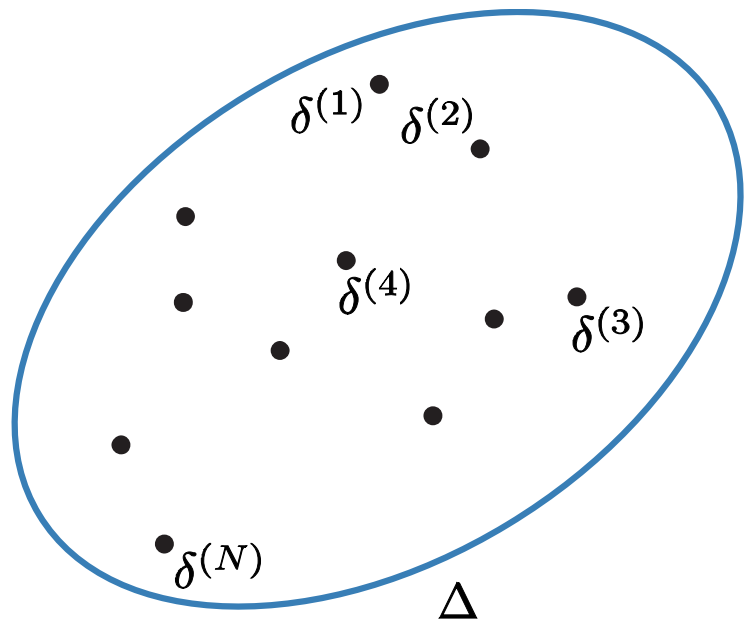


$$\min_{\theta} \max_{i=1, \dots, N} \ell(\theta, \delta^{(i)})$$

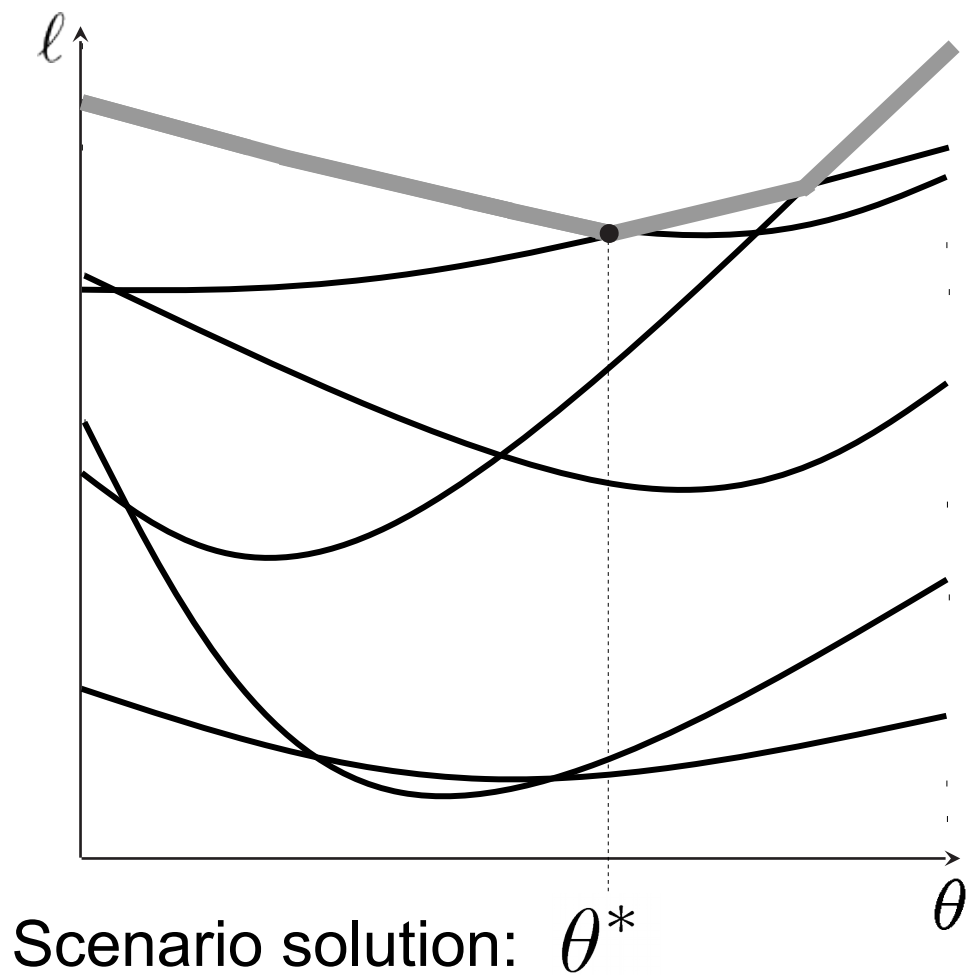


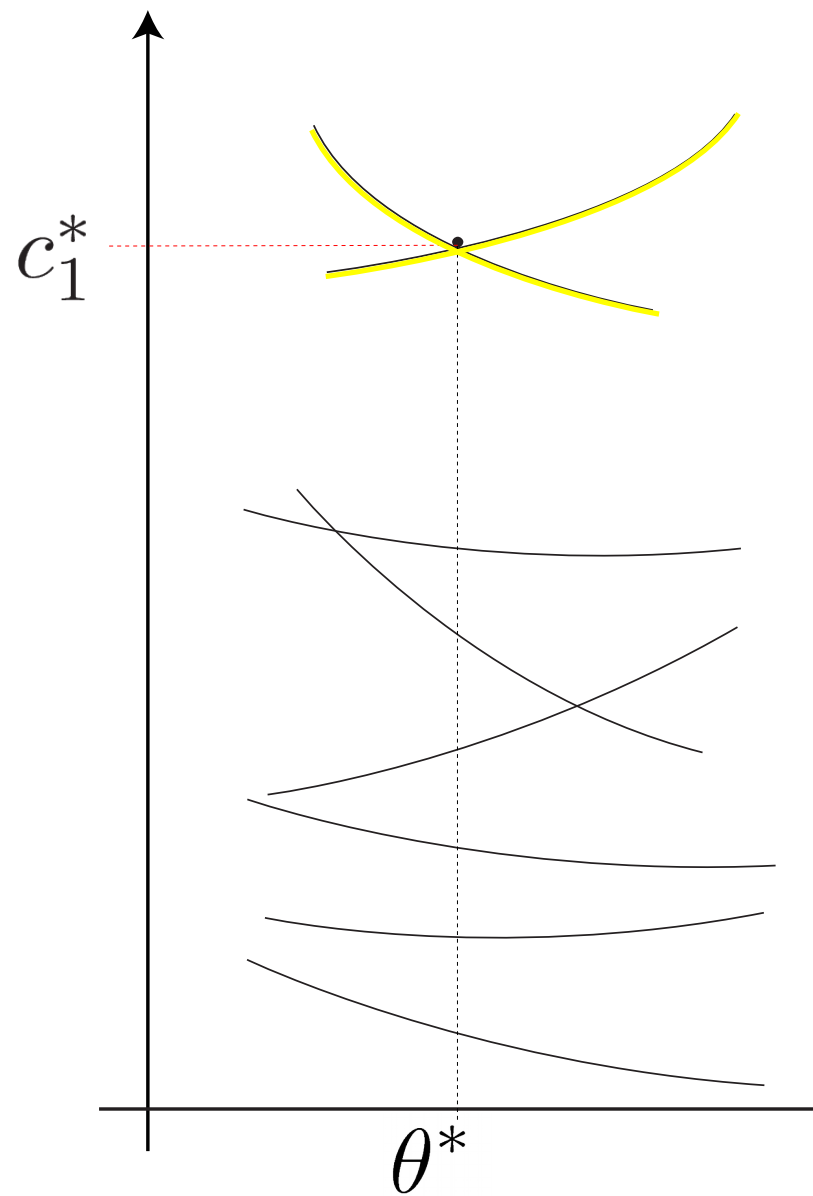
Scenario Approach

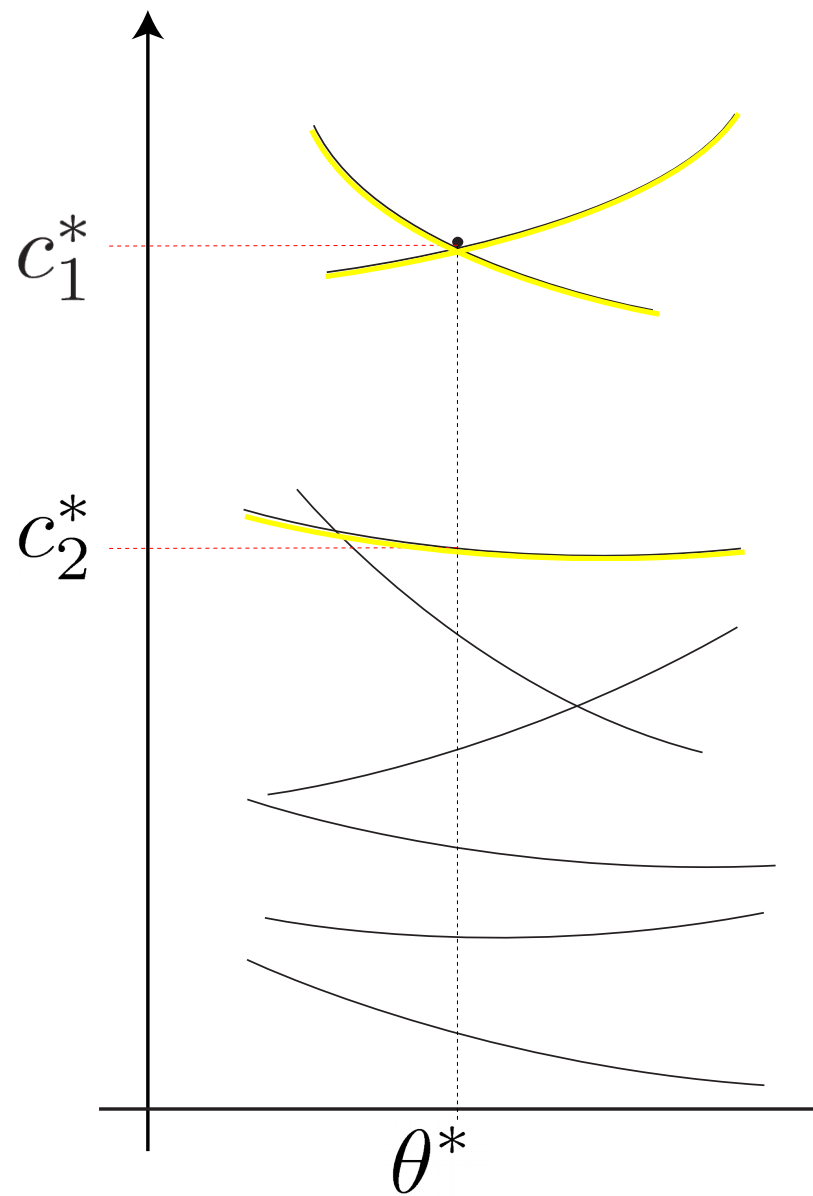
\mathbb{P} unknown

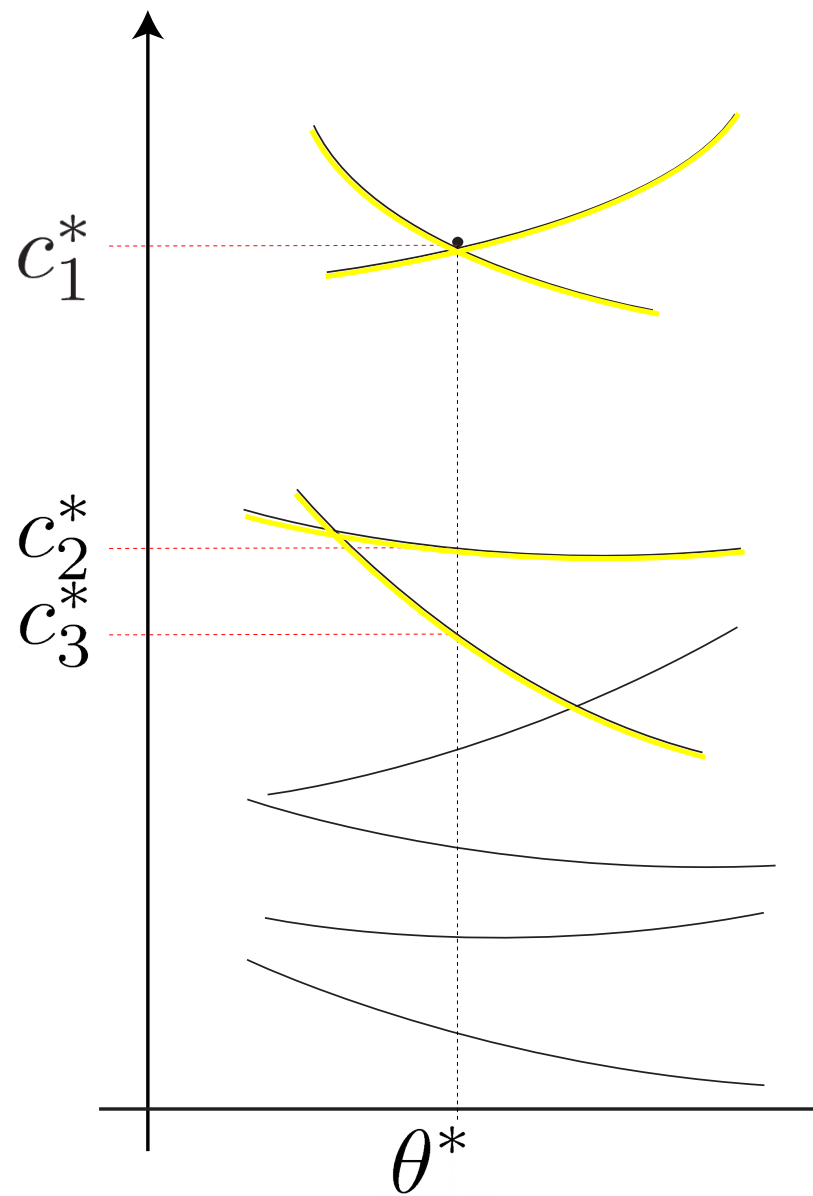


$$\min_{\theta} \max_{i=1, \dots, N} \ell(\theta, \delta^{(i)})$$







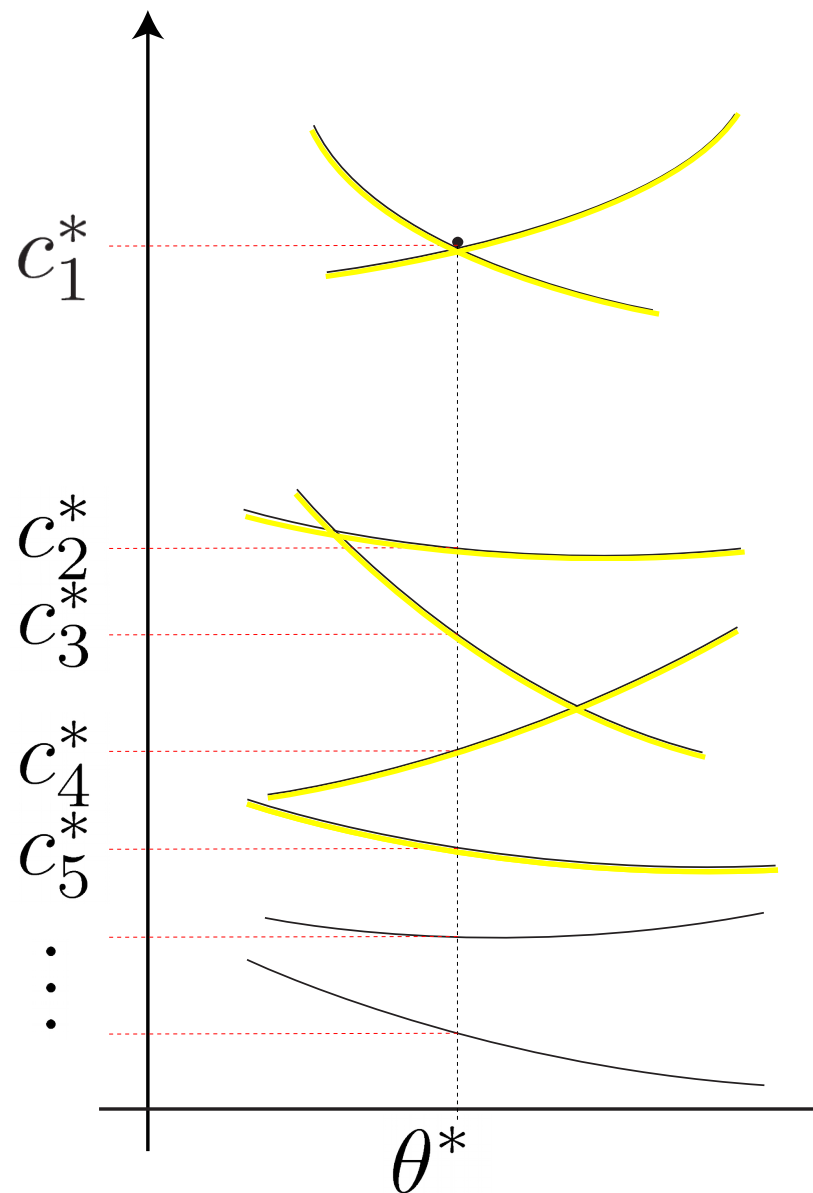


Ordered values of

$$\ell(\theta^*, \delta^{(1)})$$

\vdots

$$\ell(\theta^*, \delta^{(N)})$$



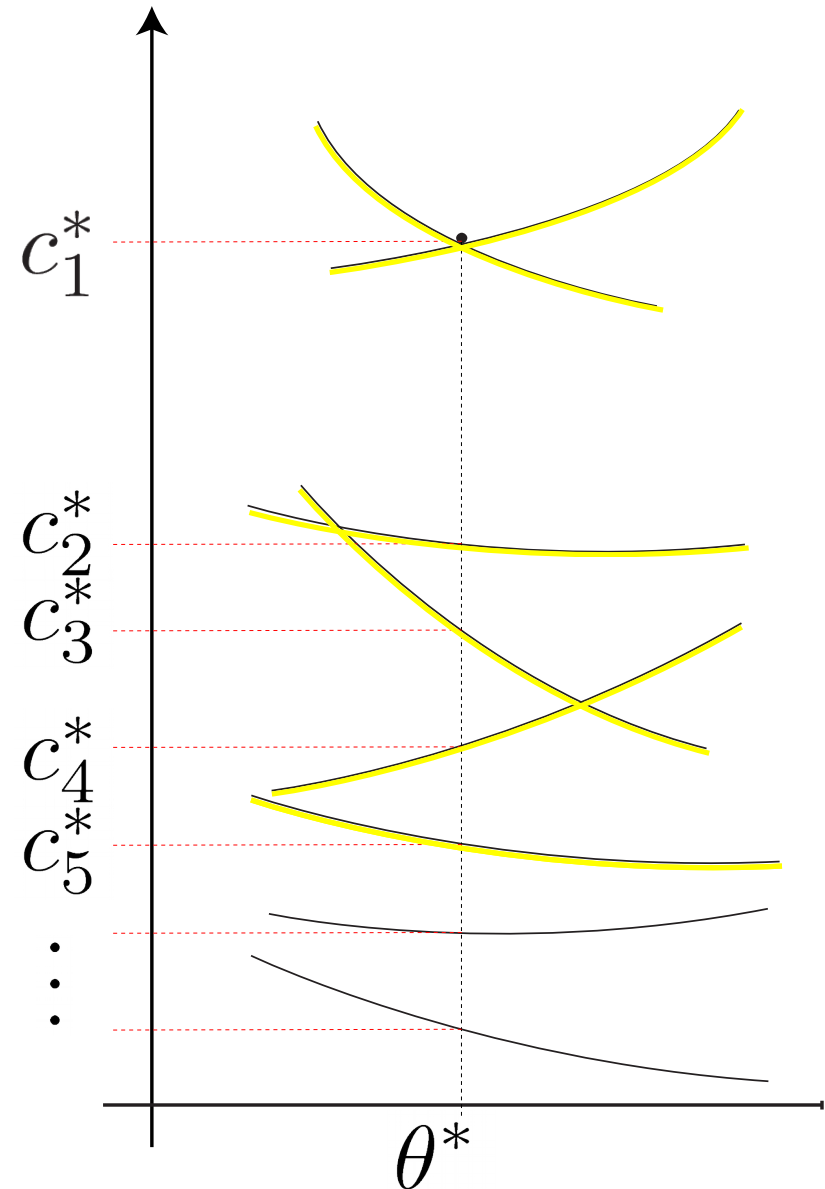
Empirical distribution of $\ell(\theta^*, \delta)$

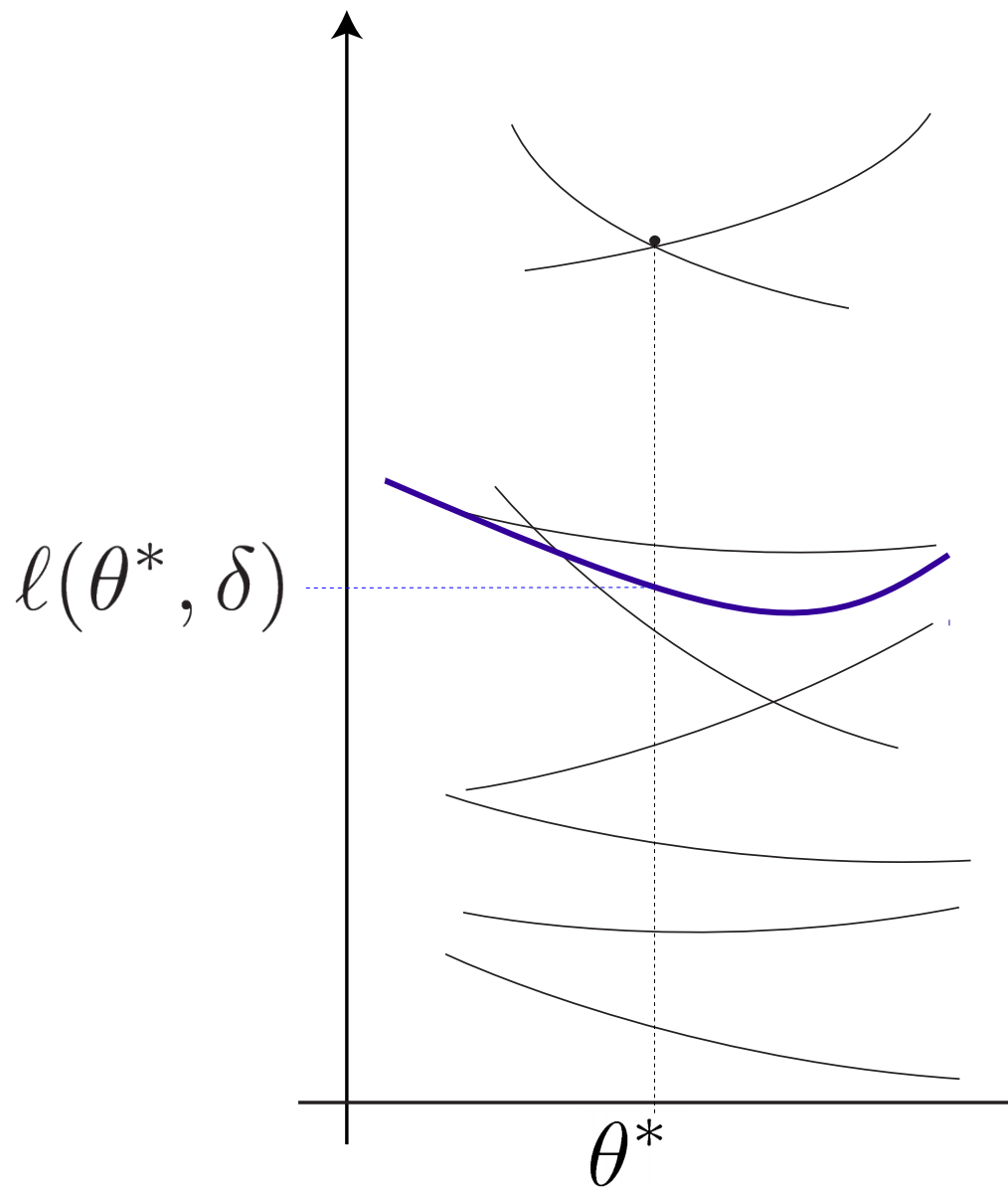
Ordered values of

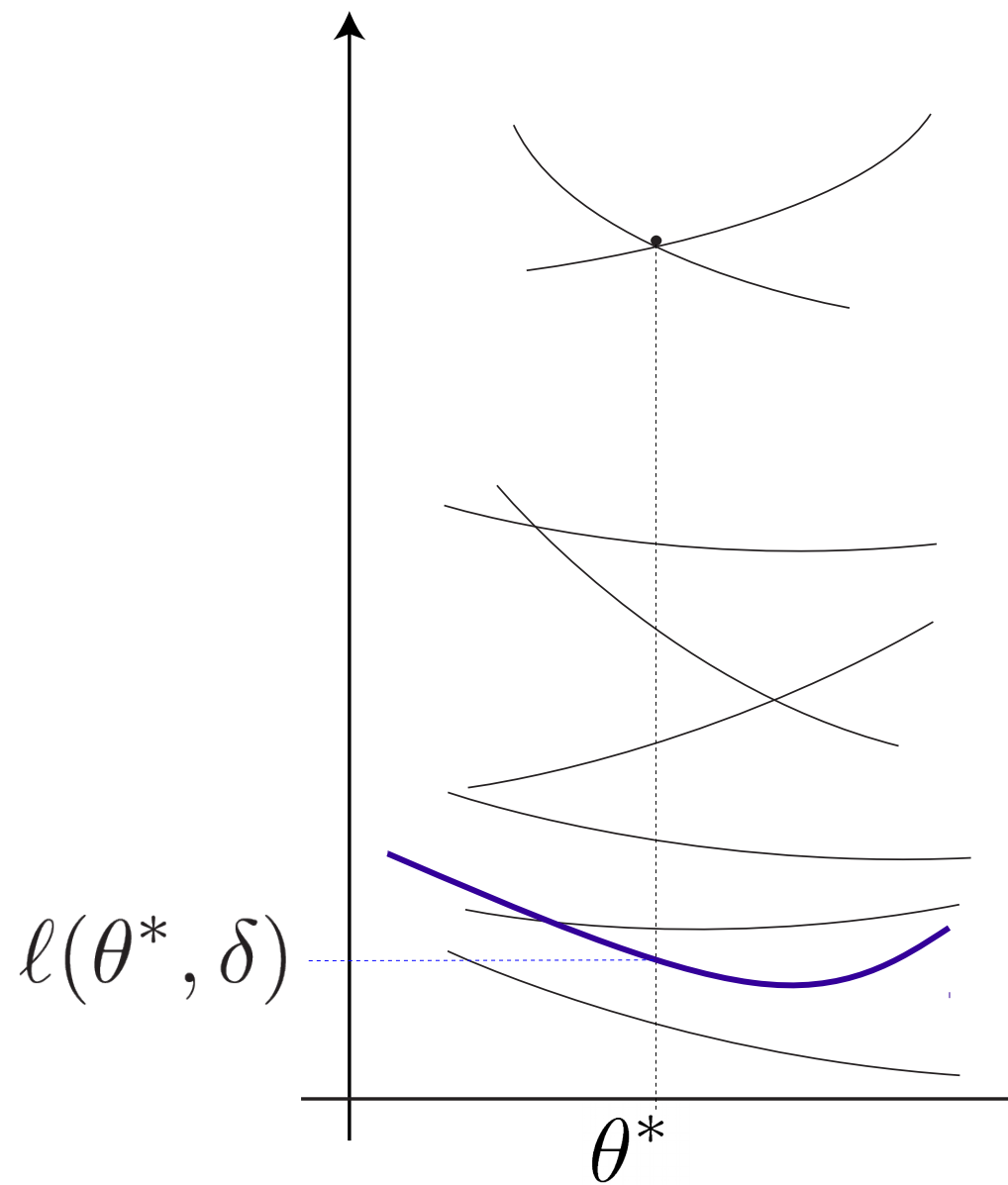
$$\ell(\theta^*, \delta^{(1)})$$

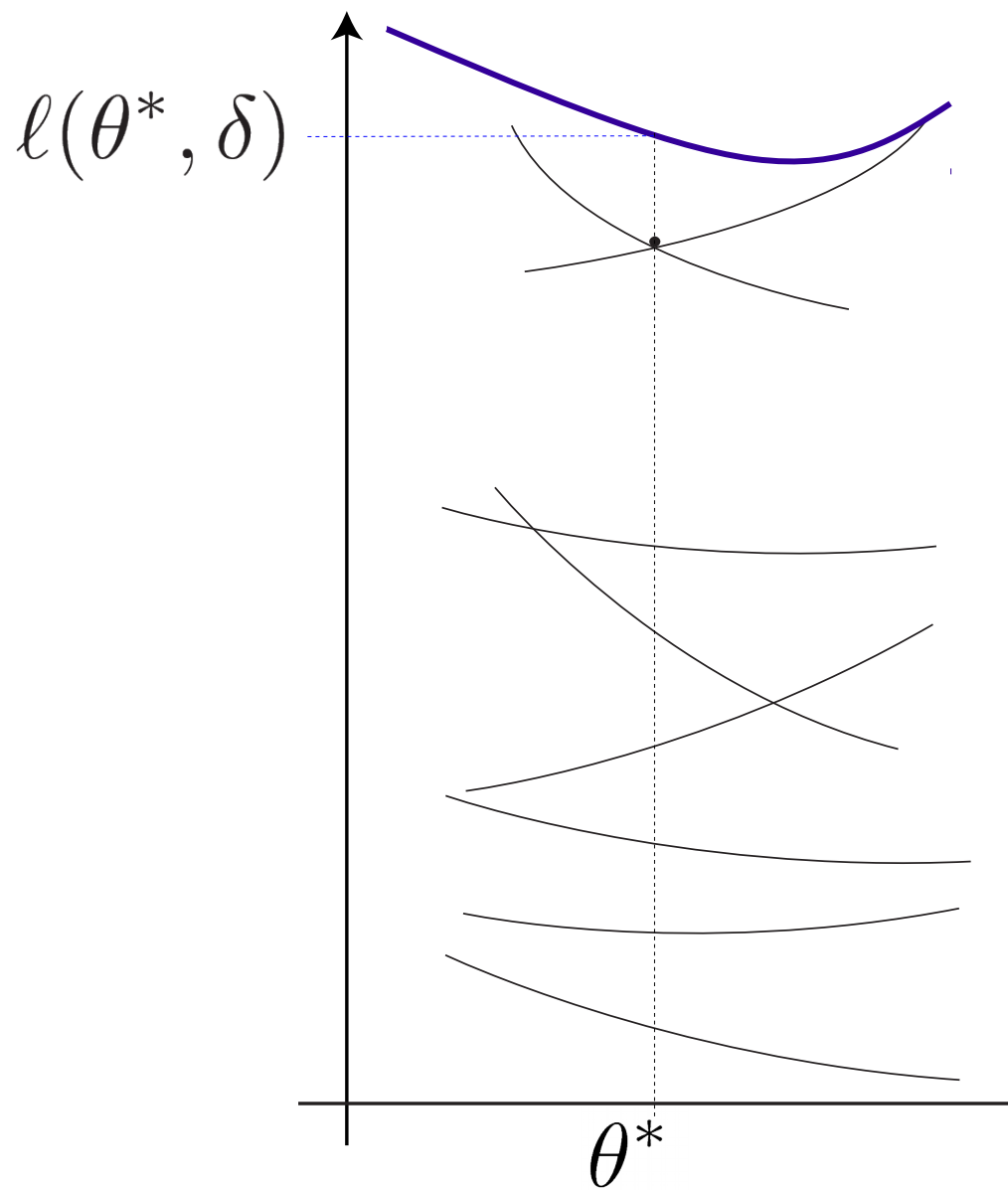
\vdots

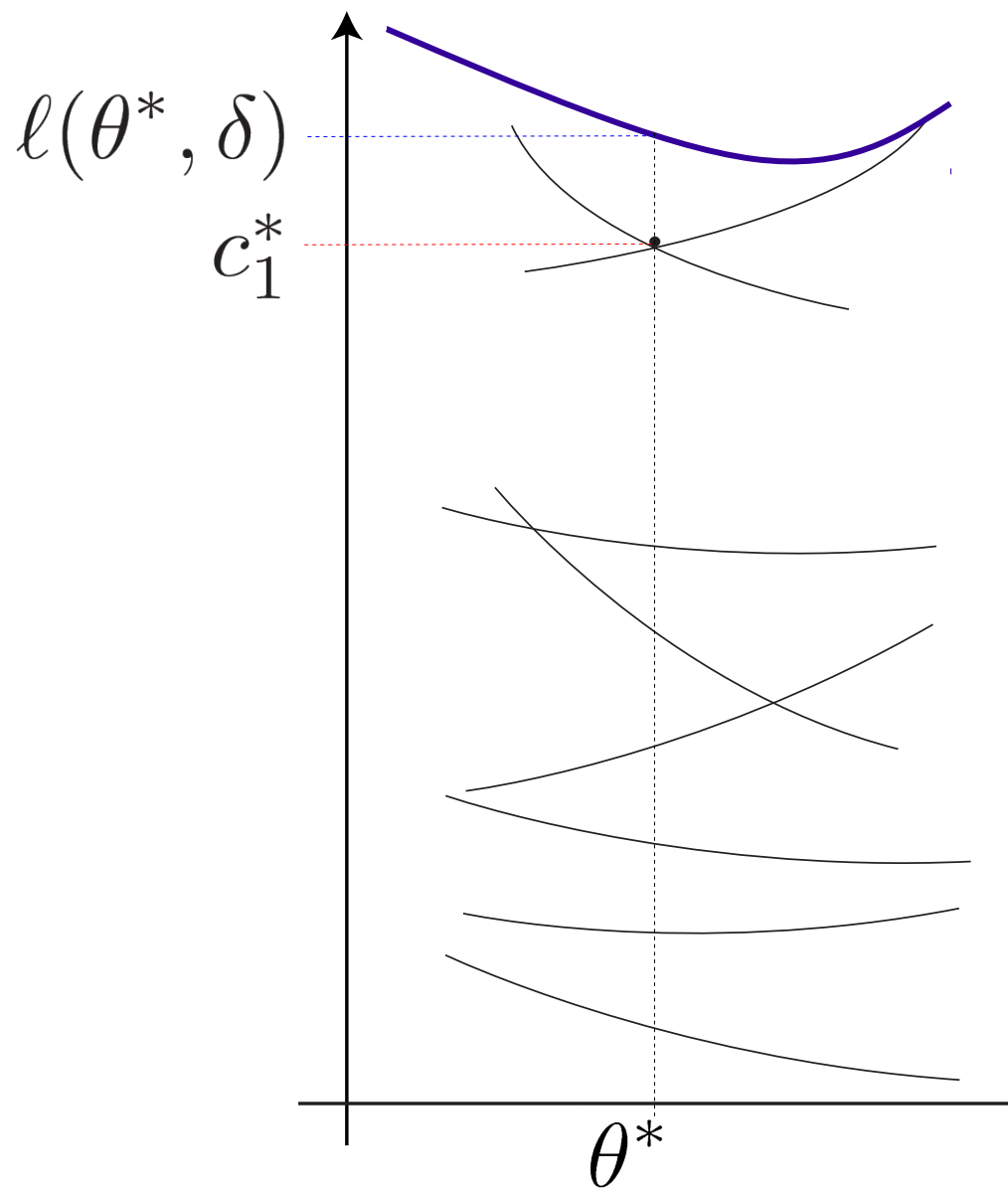
$$\ell(\theta^*, \delta^{(N)})$$

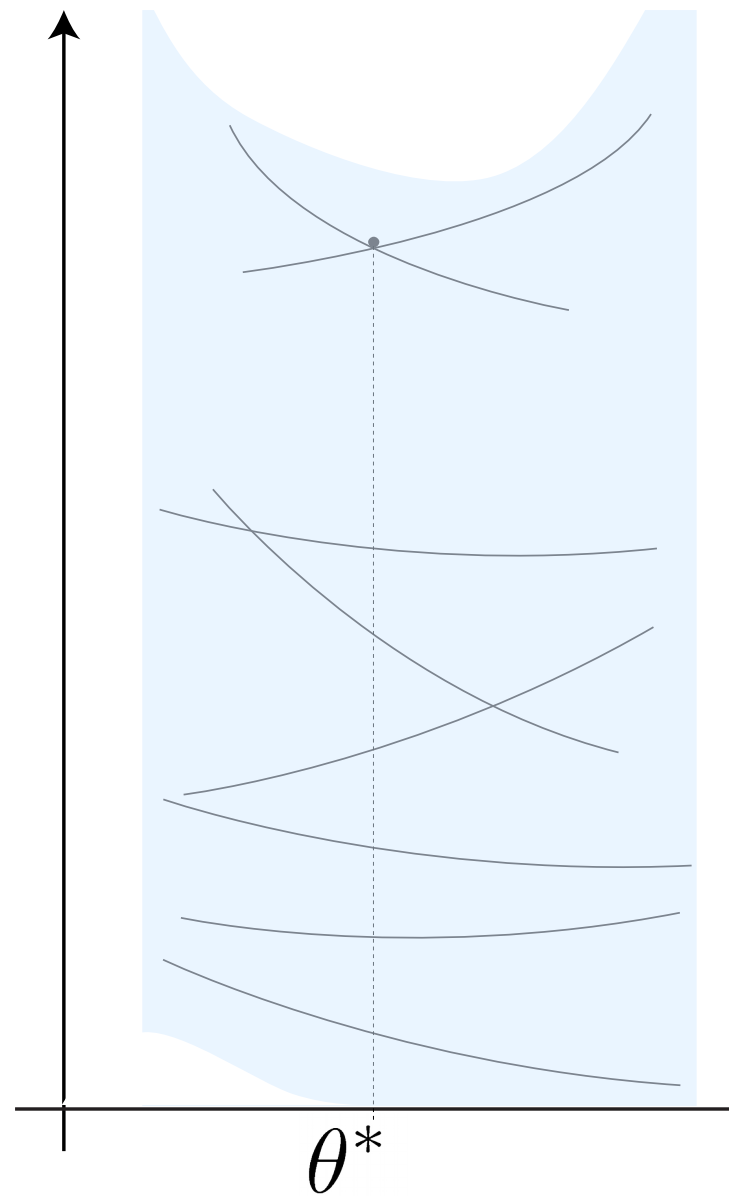




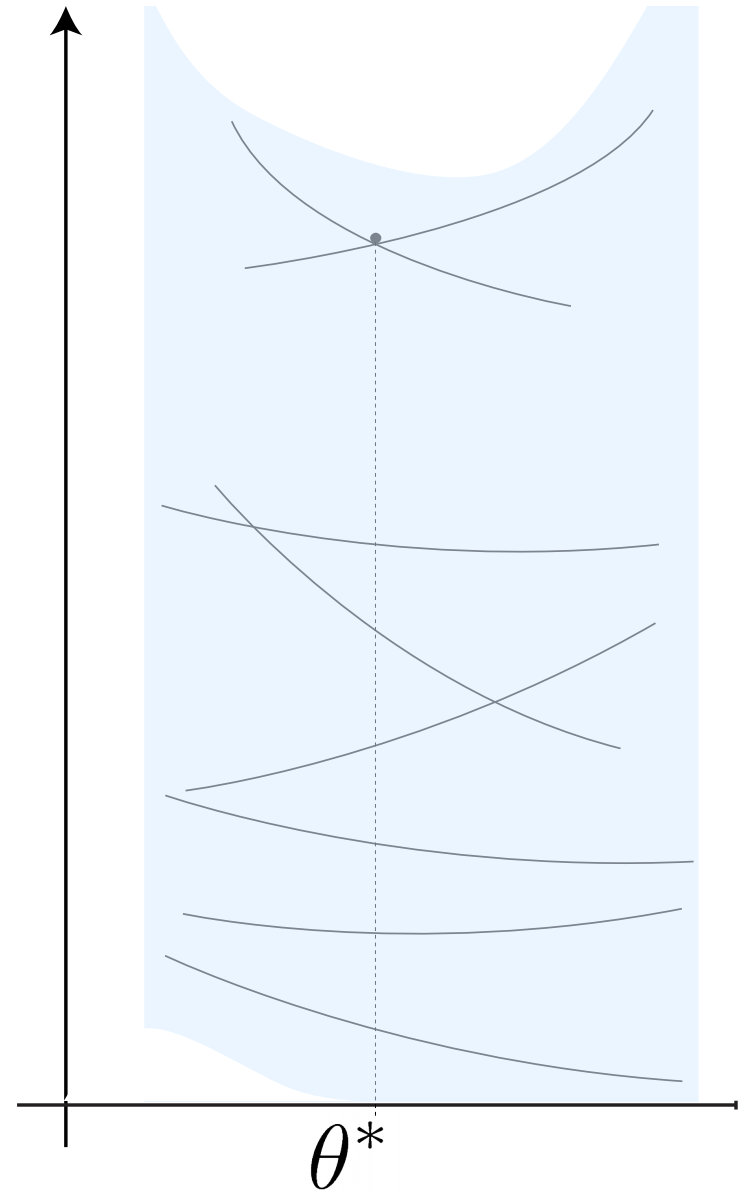




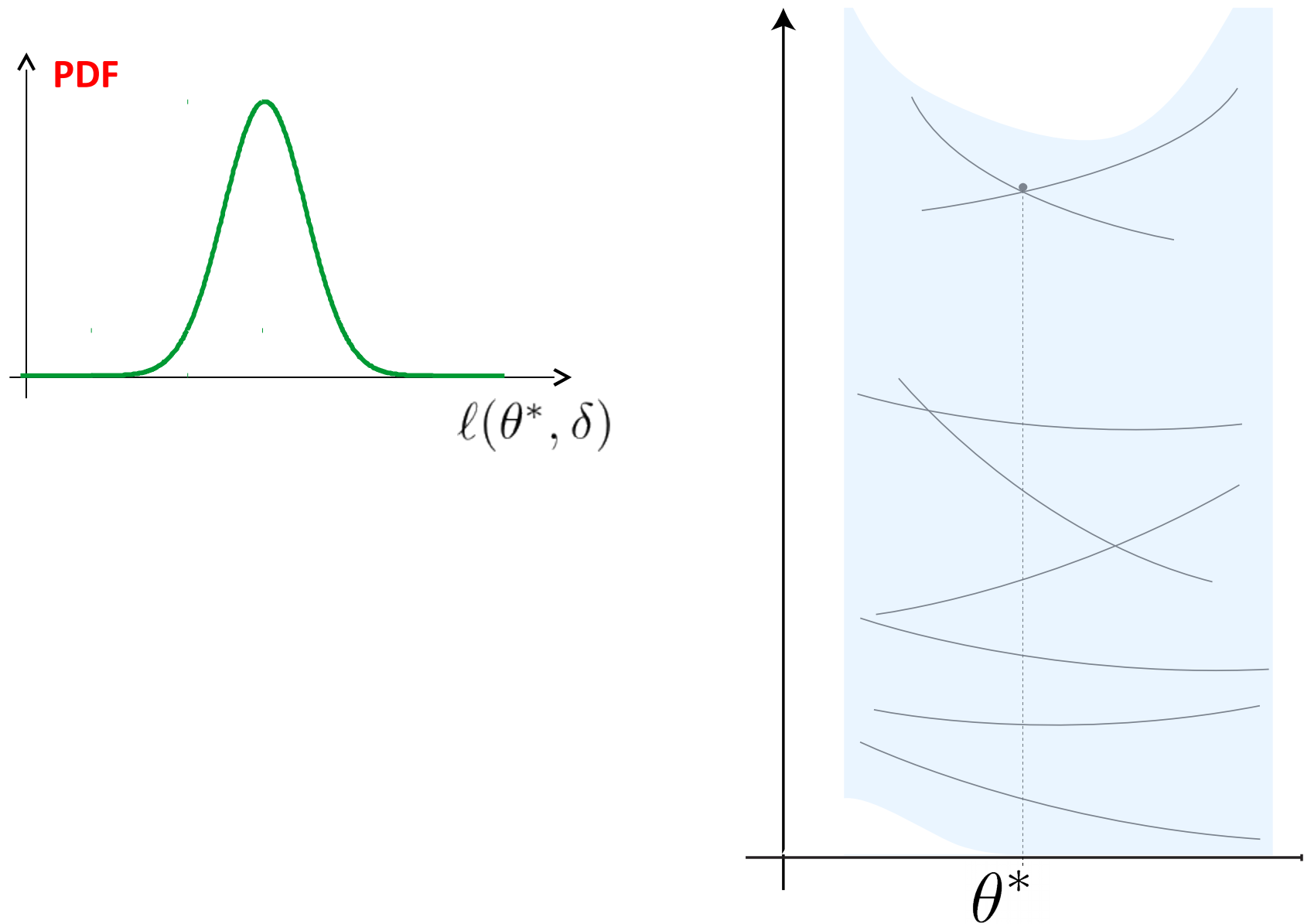




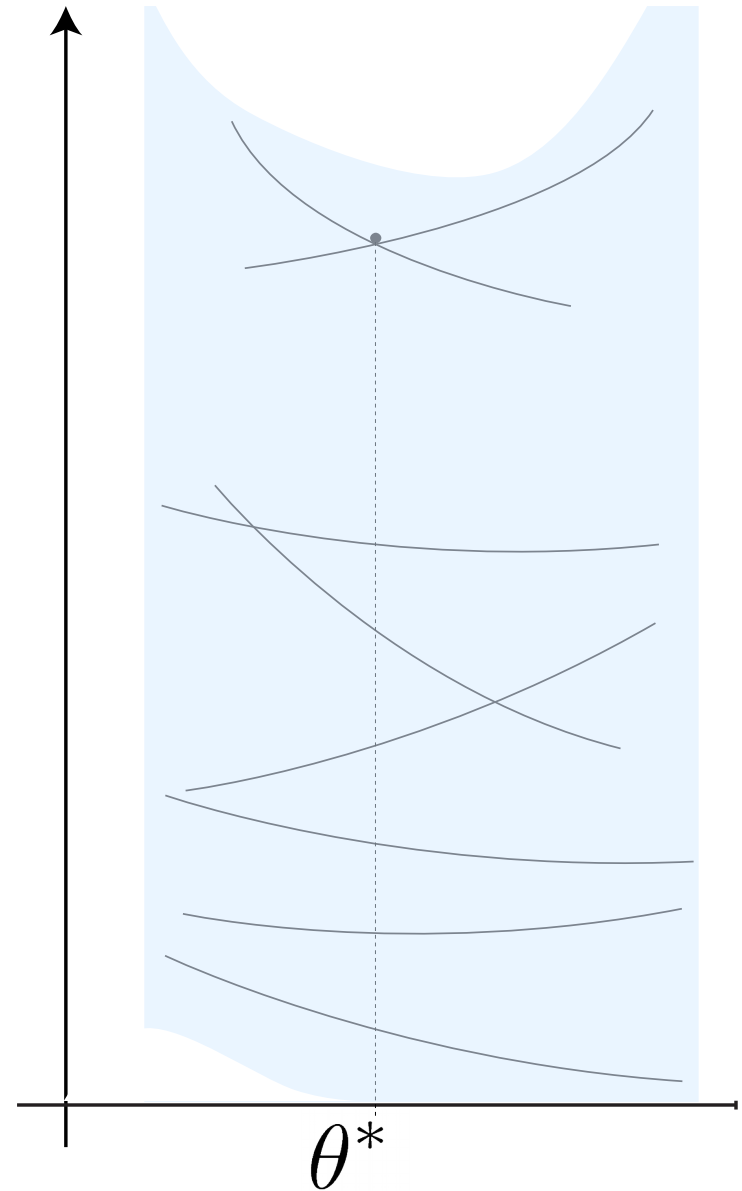
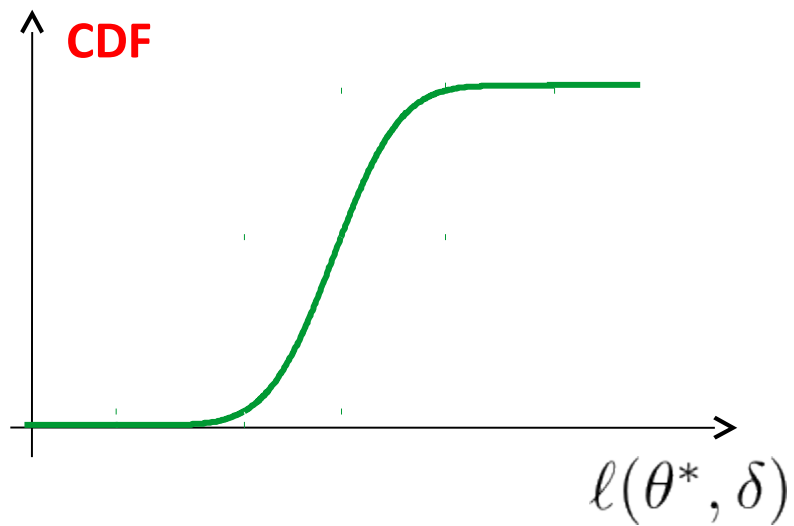
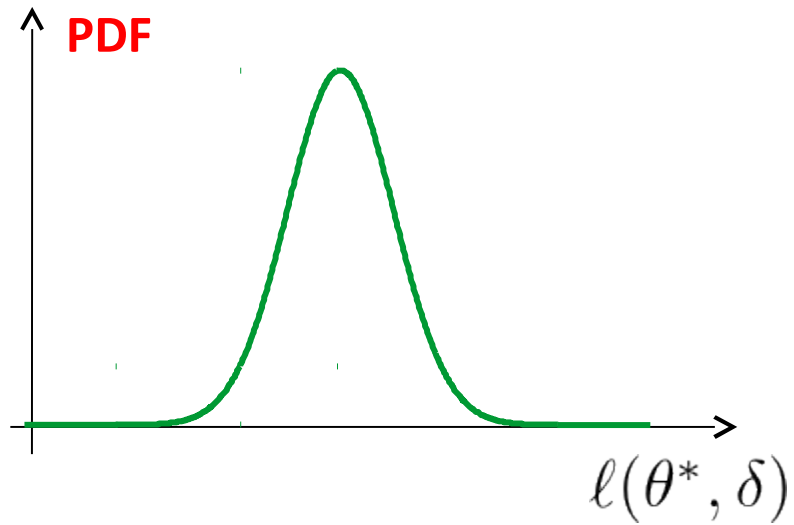
Probability distribution of $\ell(\theta^*, \delta)$



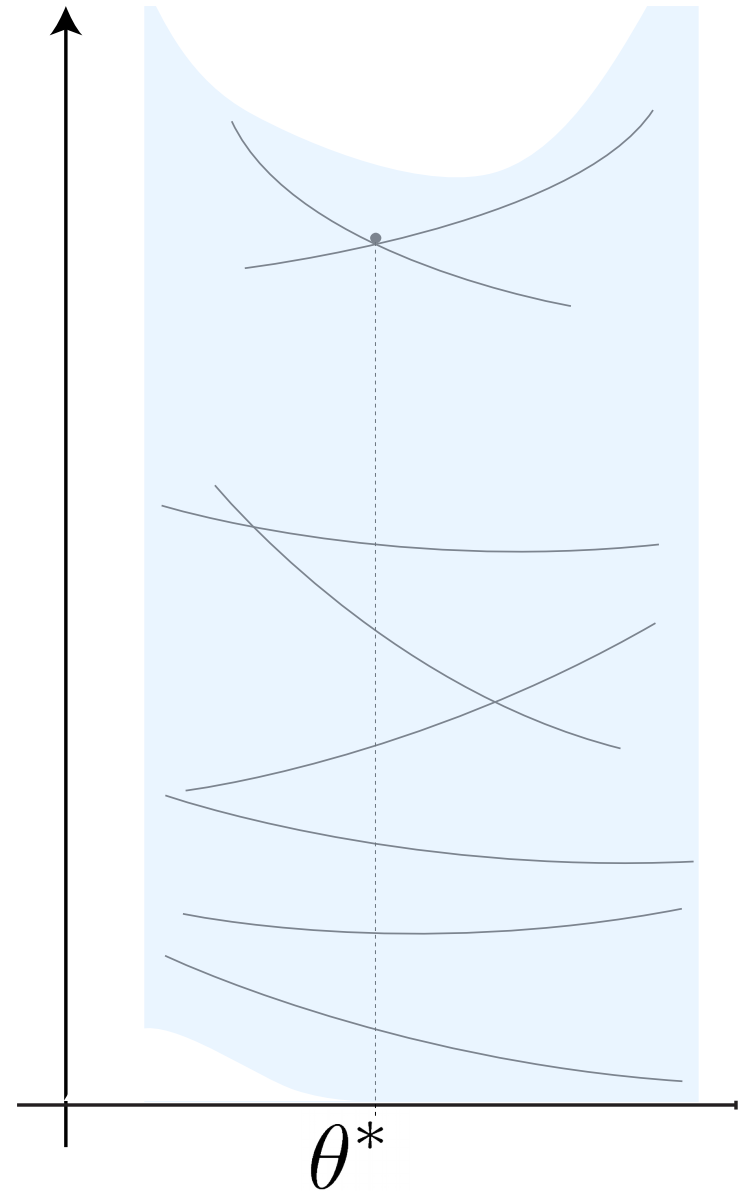
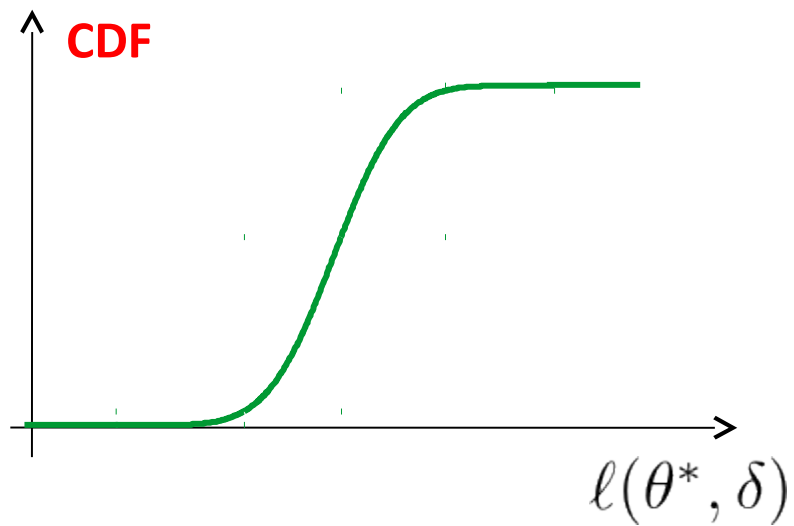
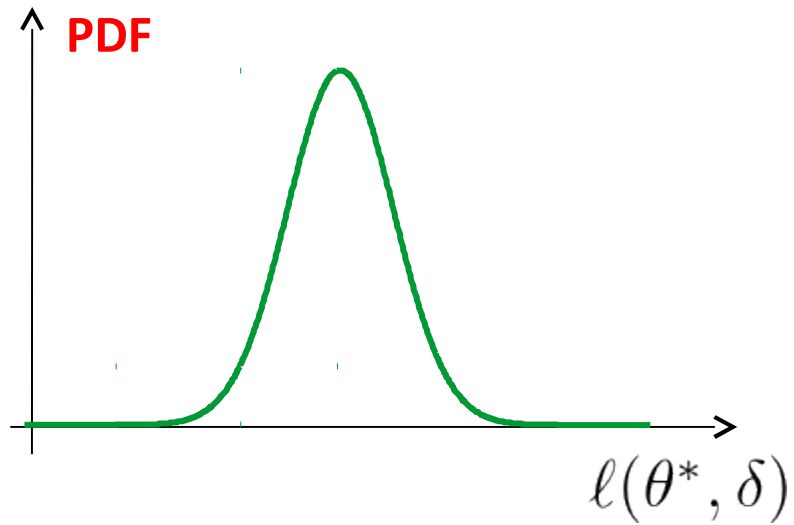
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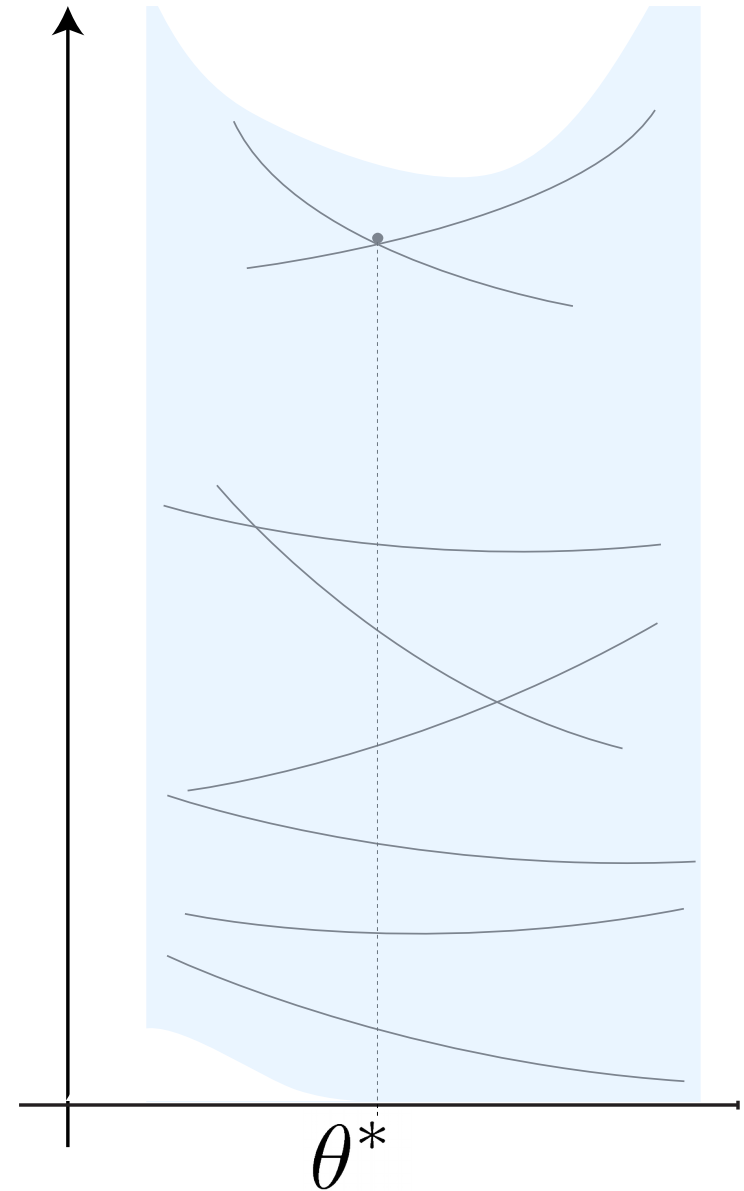
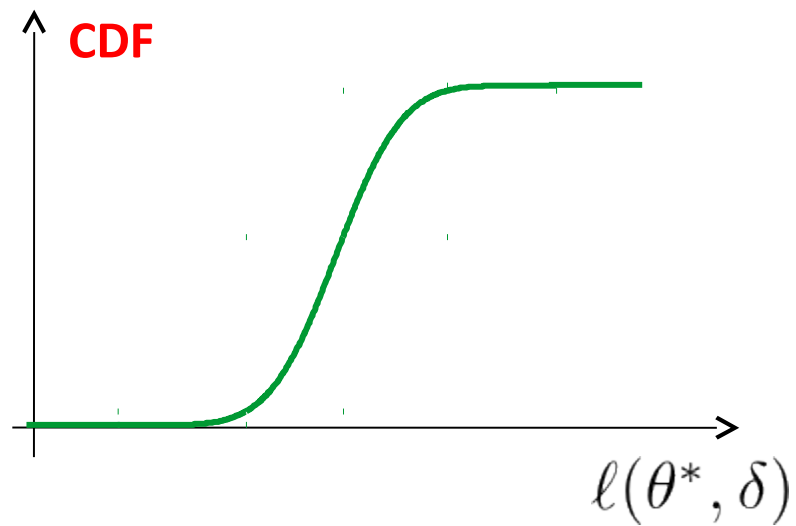
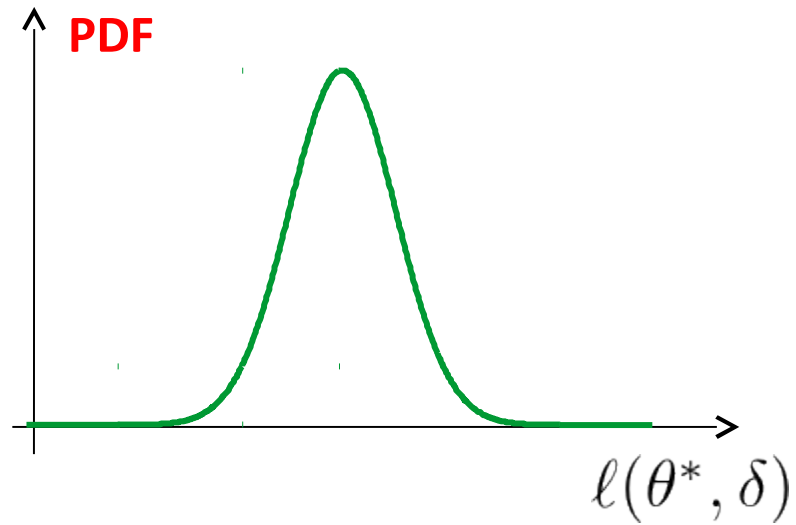
Probability distribution of $\ell(\theta^*, \delta)$



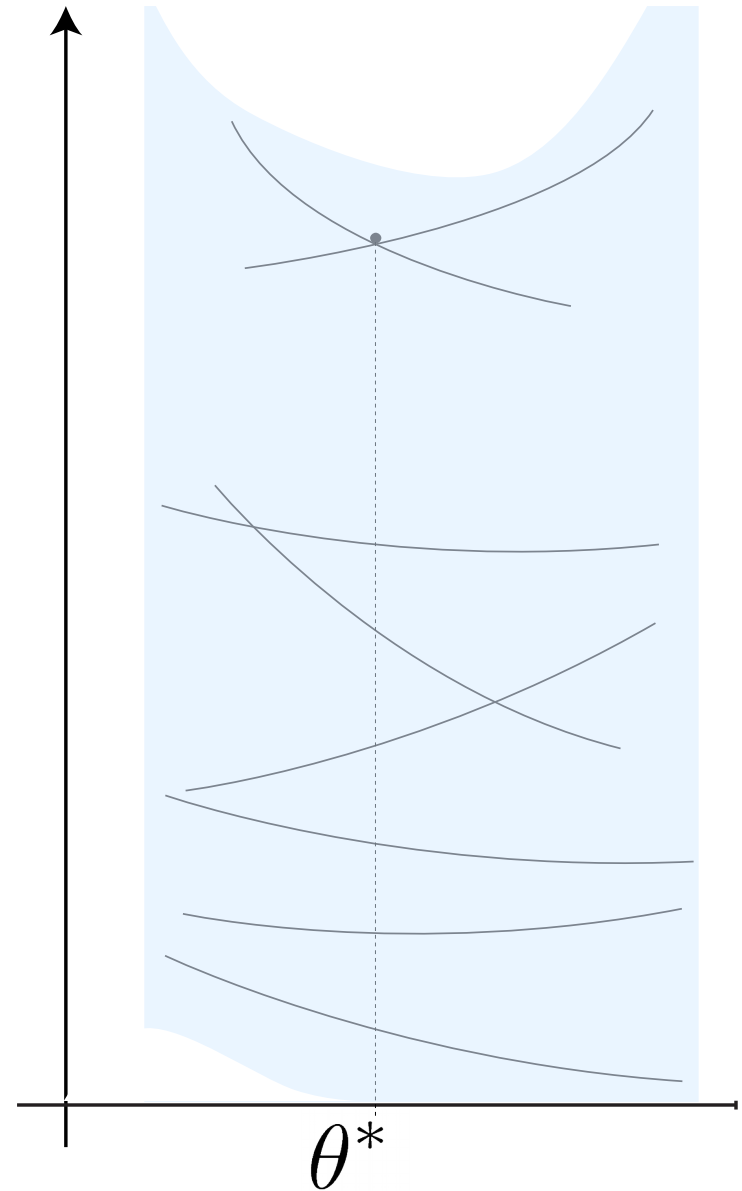
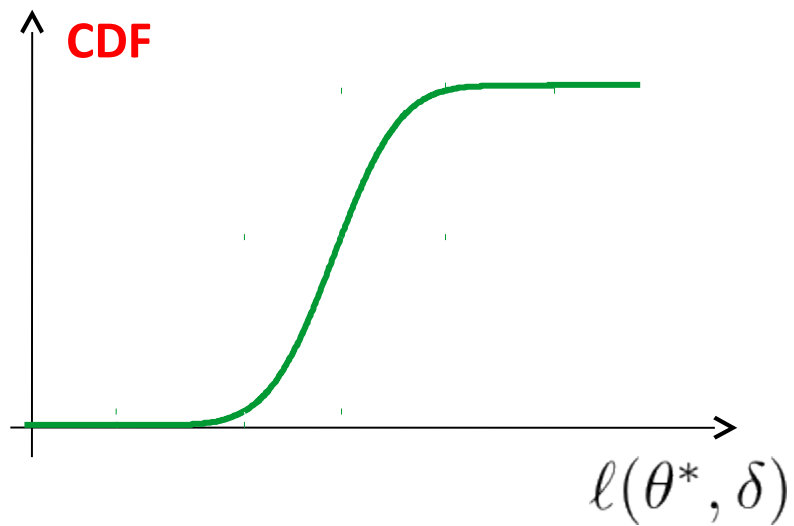
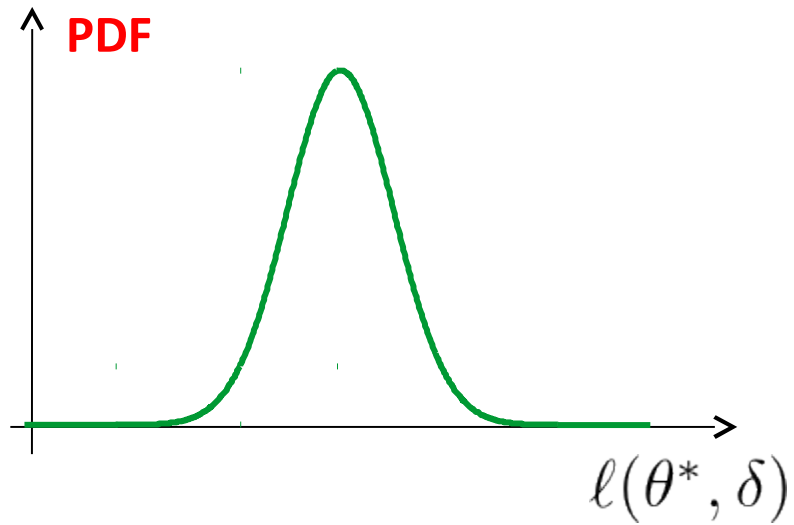
Probability distribution of $\ell(\theta^*, \delta)$



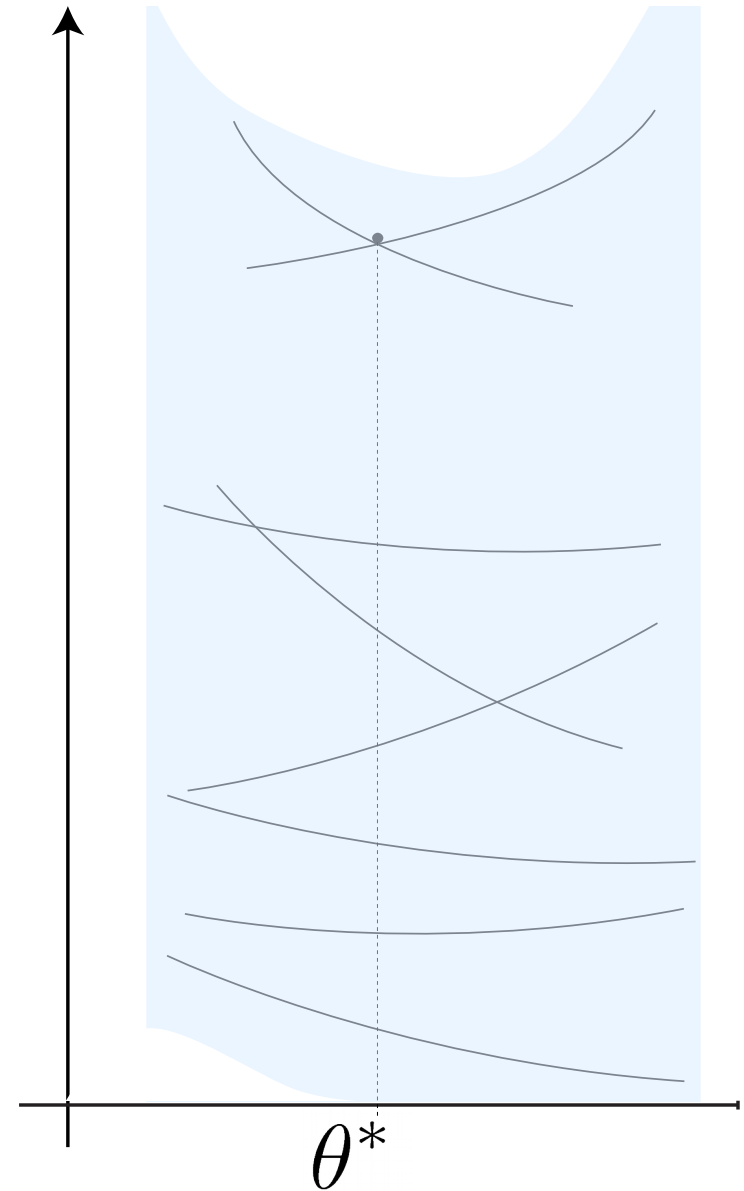
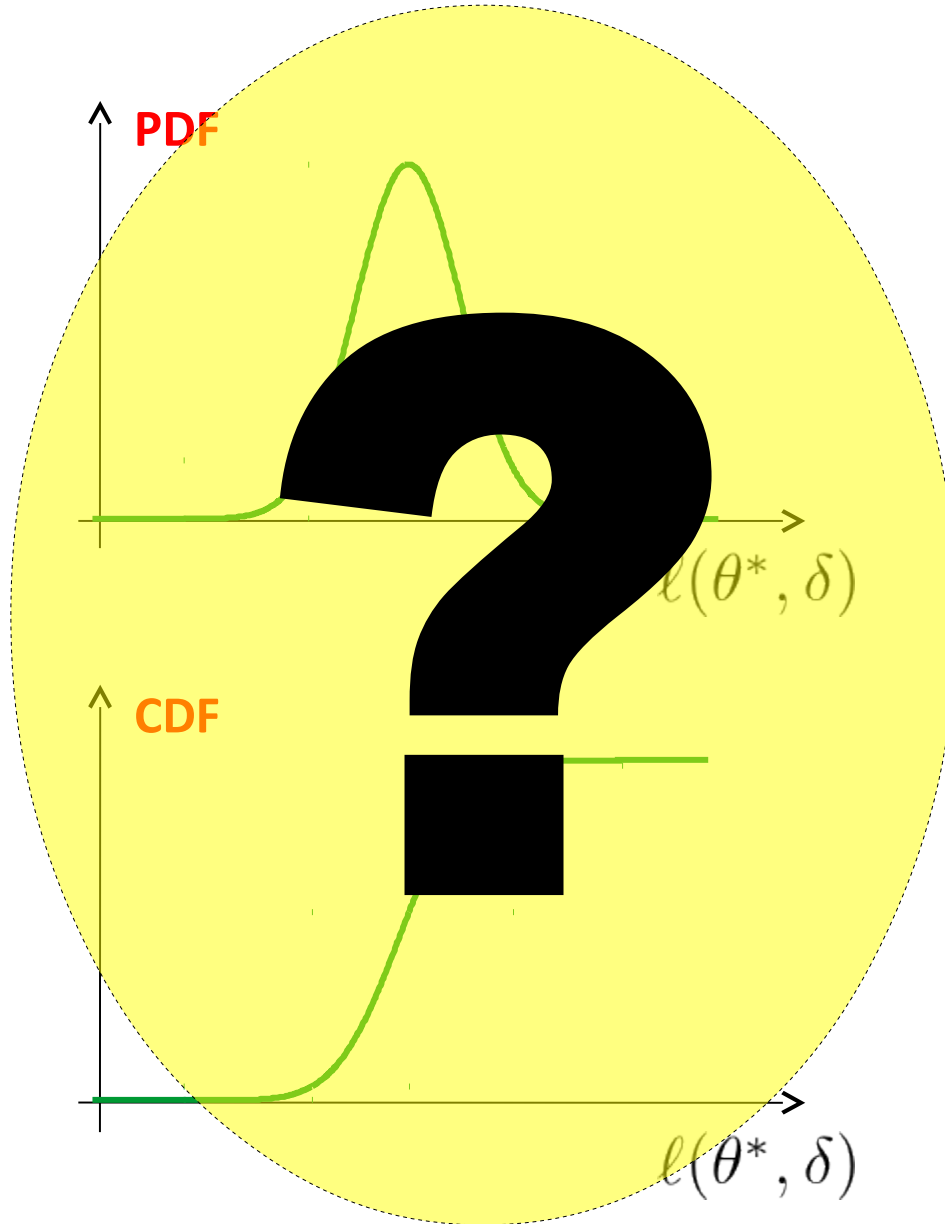
Probability distribution of $\ell(\theta^*, \delta)$ $\delta \sim \mathbb{P}$



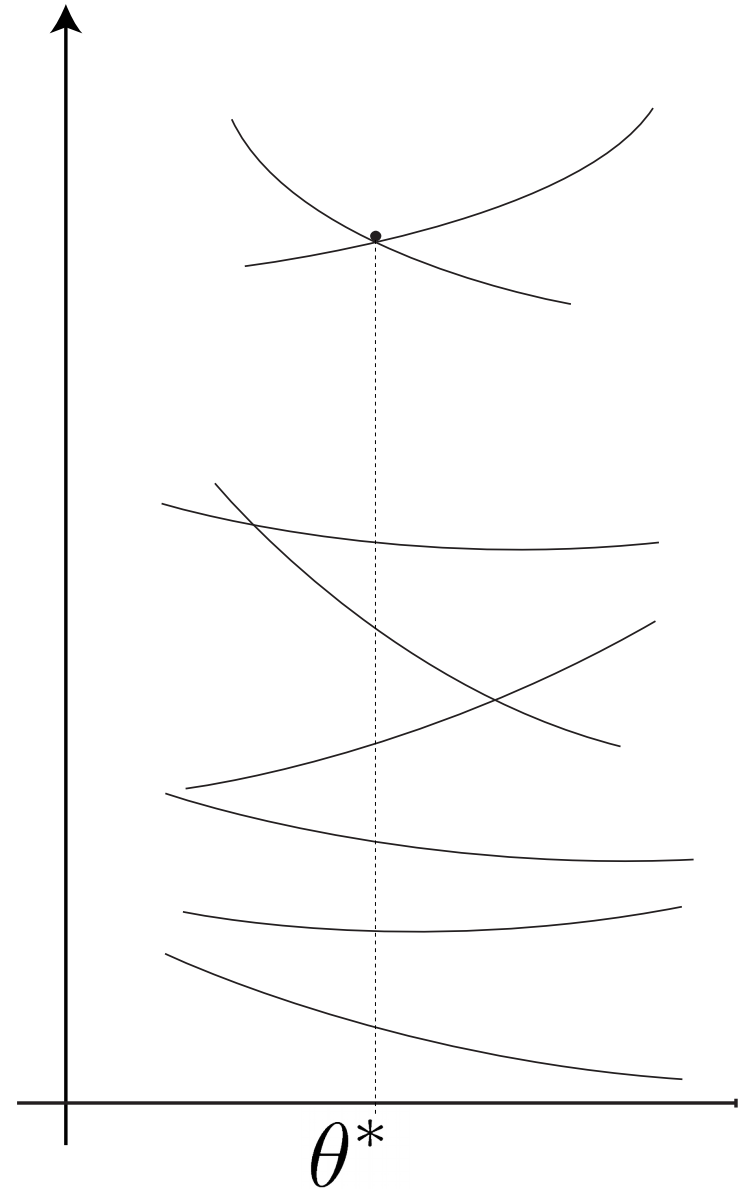
Probability distribution of $\ell(\theta^*, \delta)$ $\delta \sim \mathbb{P}$



Probability distribution of $\ell(\theta^*, \delta)$ $\delta \sim \mathbb{P}$



Probability distribution of $\ell(\theta^*, \delta)$ $\delta \sim \mathbb{P}$



TAKE-HOME MESSAGE:

It is possible to “reconstruct”
the distribution of the cost

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It is possible to “reconstruct” the distribution of the cost by using the sole N scenarios that have been used to compute θ^* .

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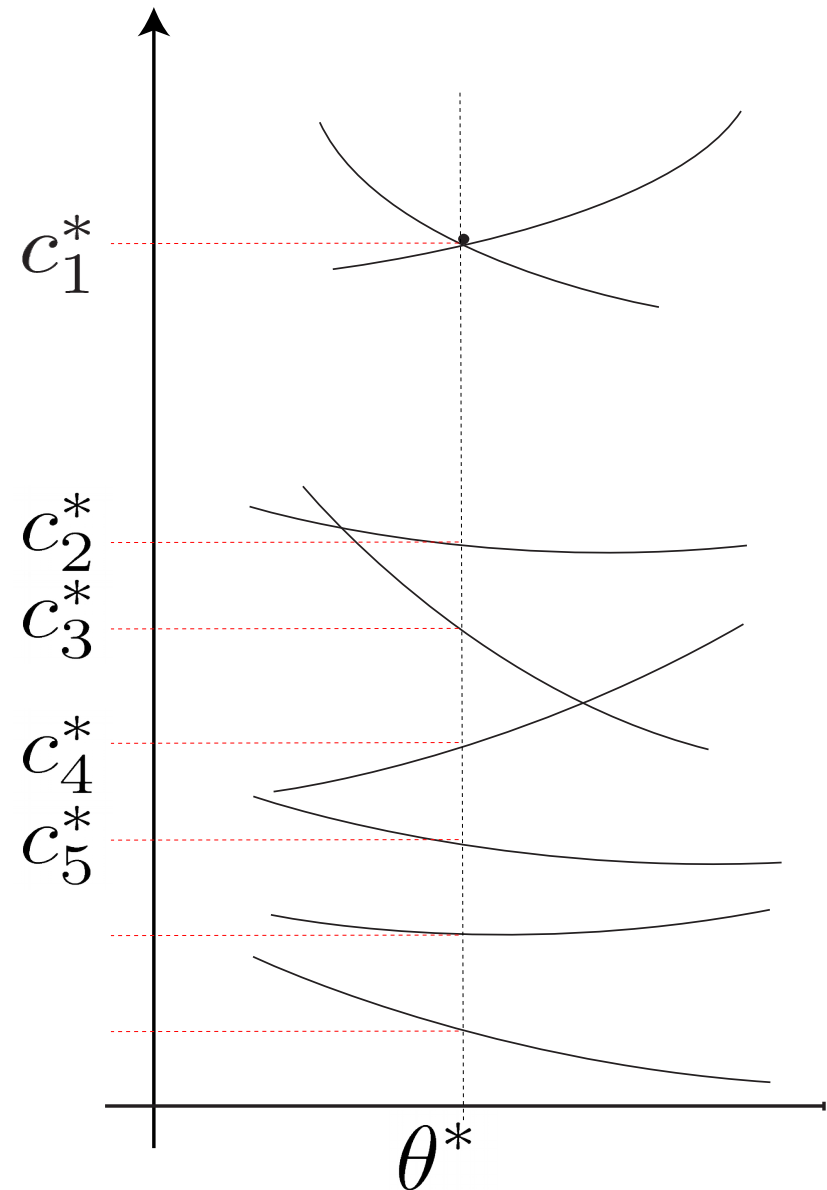
Without using any new observation
nor any specific knowledge of \mathbb{P} .

HOW?

HOW?

By combining a-posteriori knowledge
with distribution-free theorems

Empirical distribution of $\ell(\theta^*, \delta)$



HOW?

By combining a-posteriori knowledge
(the empirical distribution of the cost)

with distribution-free theorems

HOW?

By combining a-posteriori knowledge
(the empirical distribution of the cost)

with distribution-free theorems
(invariant properties of convex problems)

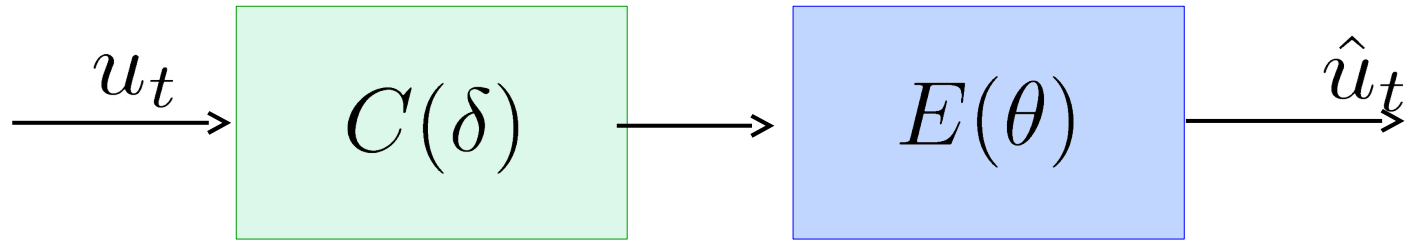
HOW?

By combining a-posteriori knowledge
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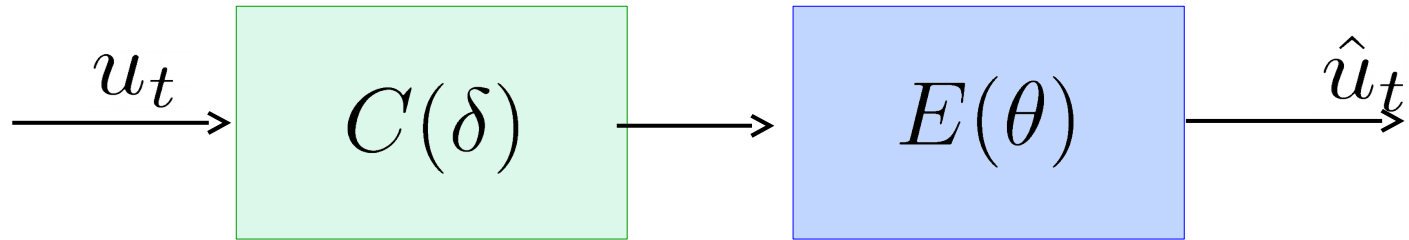
with distribution-free theorems
(invariant properties of convex problems)

*example (and a few technical
details) following...*

Channel equalization example

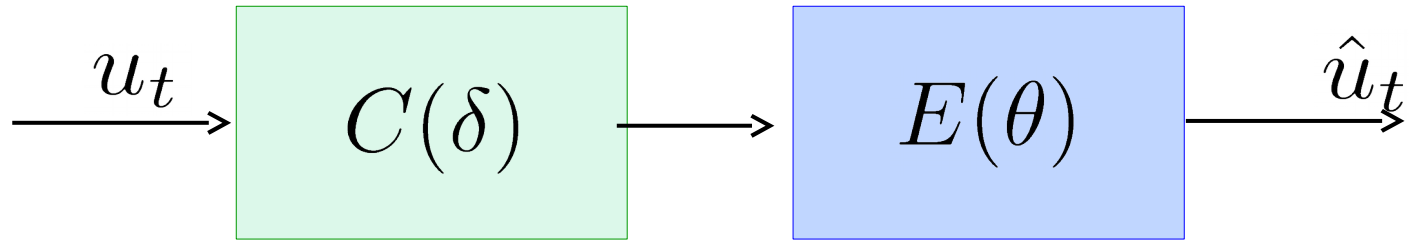


Channel equalization example



$$\ell(\theta, \delta) = \|C(\delta)E(\theta) - \text{IdealChannel}\|$$

Channel equalization example



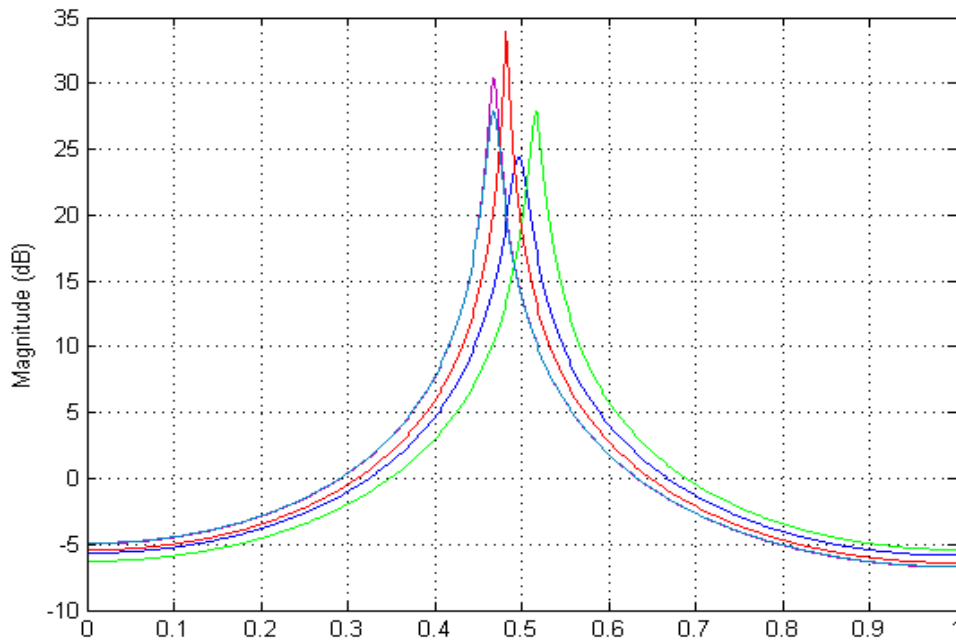
$$\ell(\theta, \delta) = \|C(\delta)E(\theta) - \text{IdealChannel}\|$$

For details: see paper

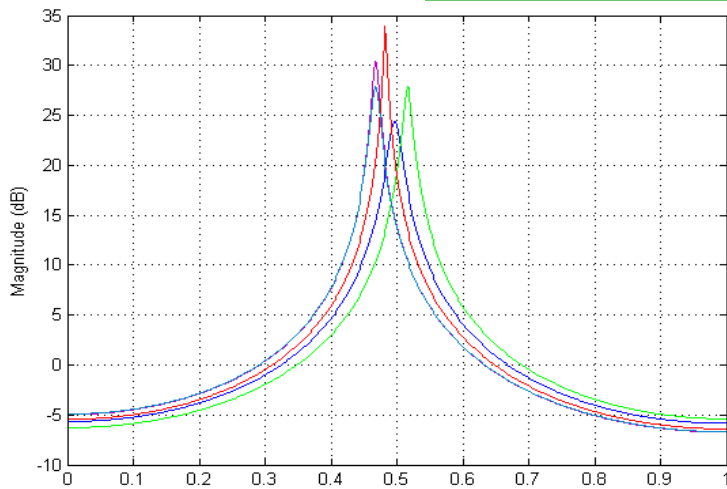
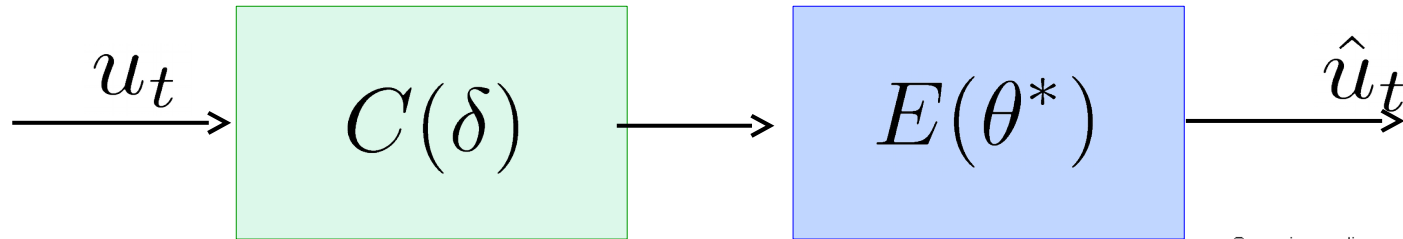
Channel equalization example

$$C(\delta)$$

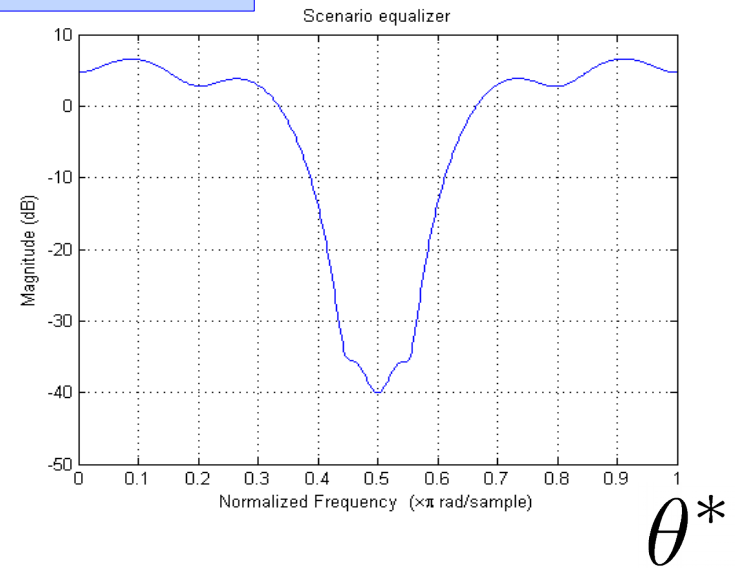
$$\delta^{(1)}, \delta^{(2)}, \dots, \delta^{(N)}$$



Channel equalization example

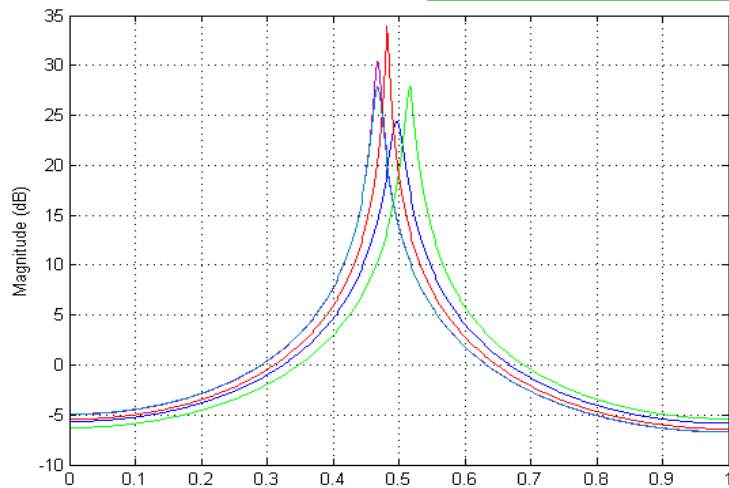
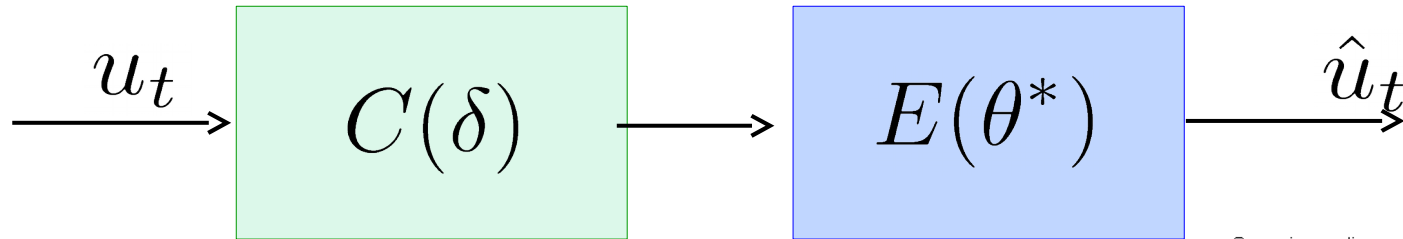


$\delta^{(1)}, \delta^{(2)}, \dots, \delta^{(N)}$

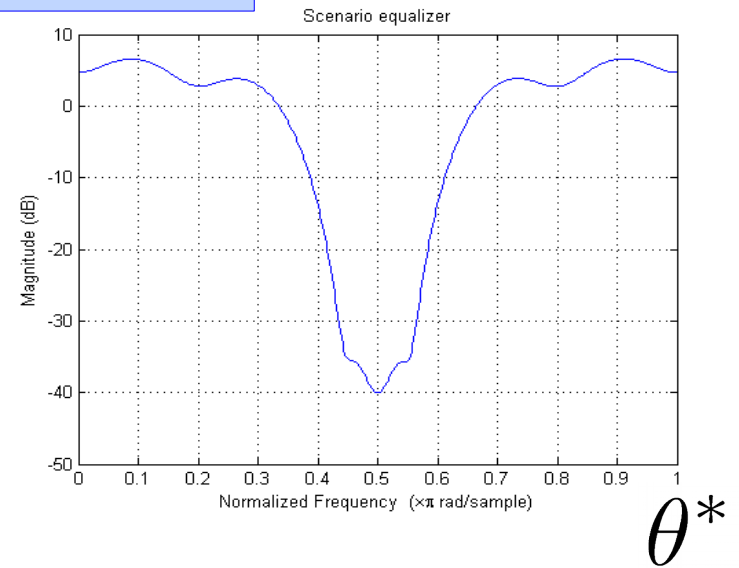


θ^*

Channel equalization example

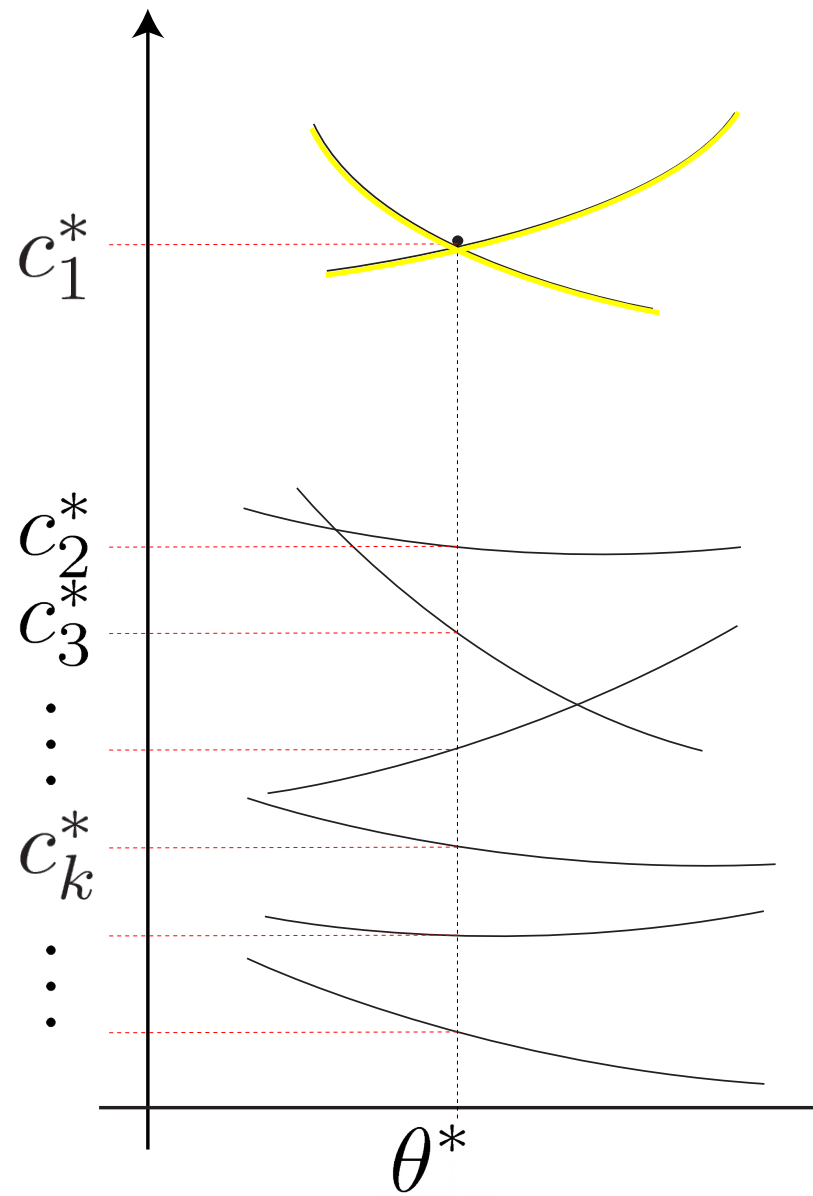


$\delta^{(1)}, \delta^{(2)}, \dots, \delta^{(N)}$

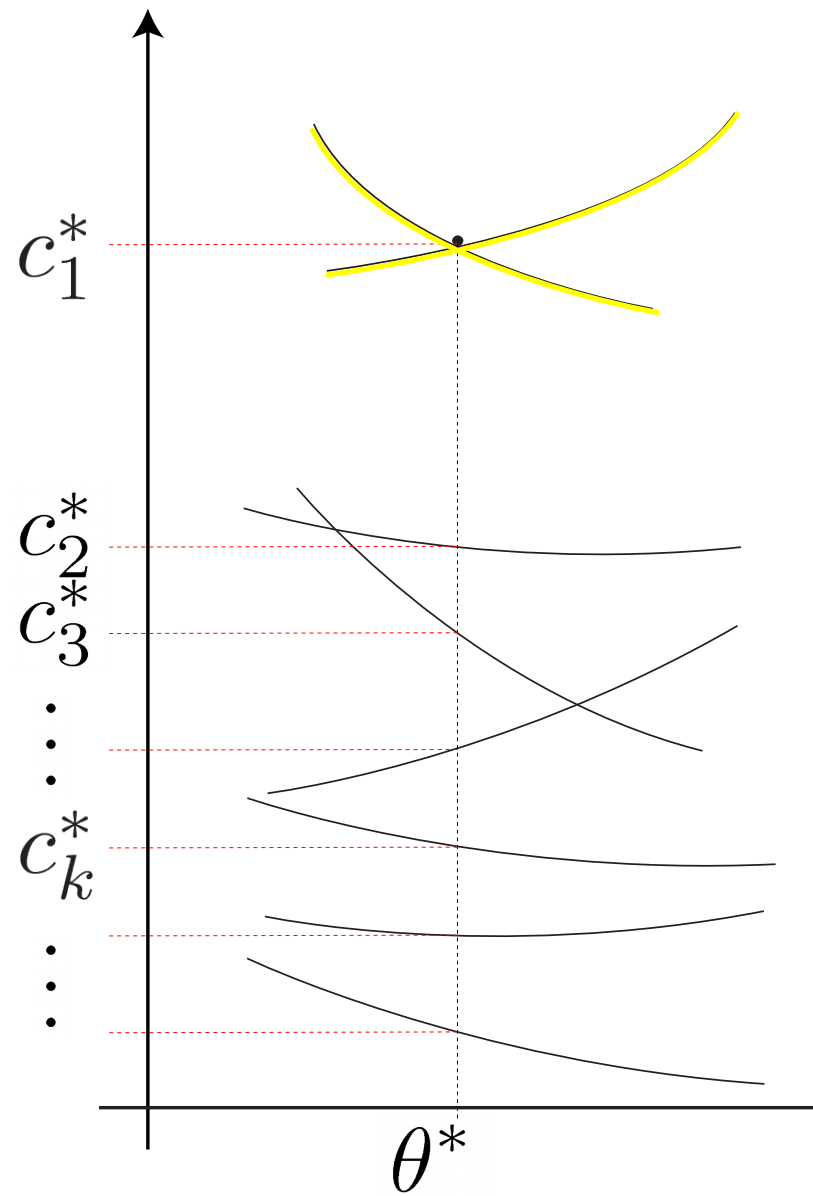


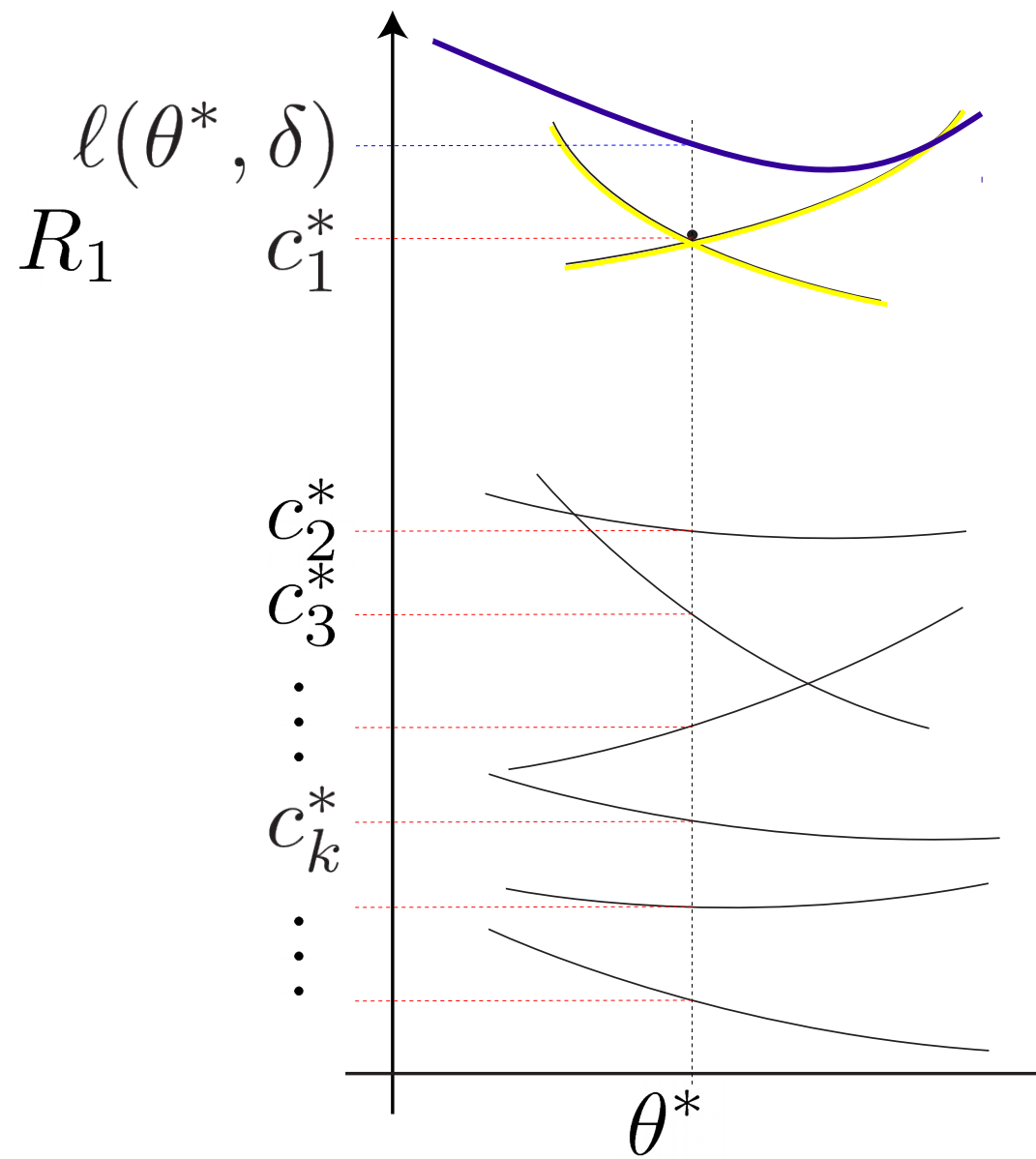
θ^*

$$\ell(\theta^*, \delta^{(1)}), \ell(\theta^*, \delta^{(2)}), \dots, \ell(\theta^*, \delta^{(N)})$$

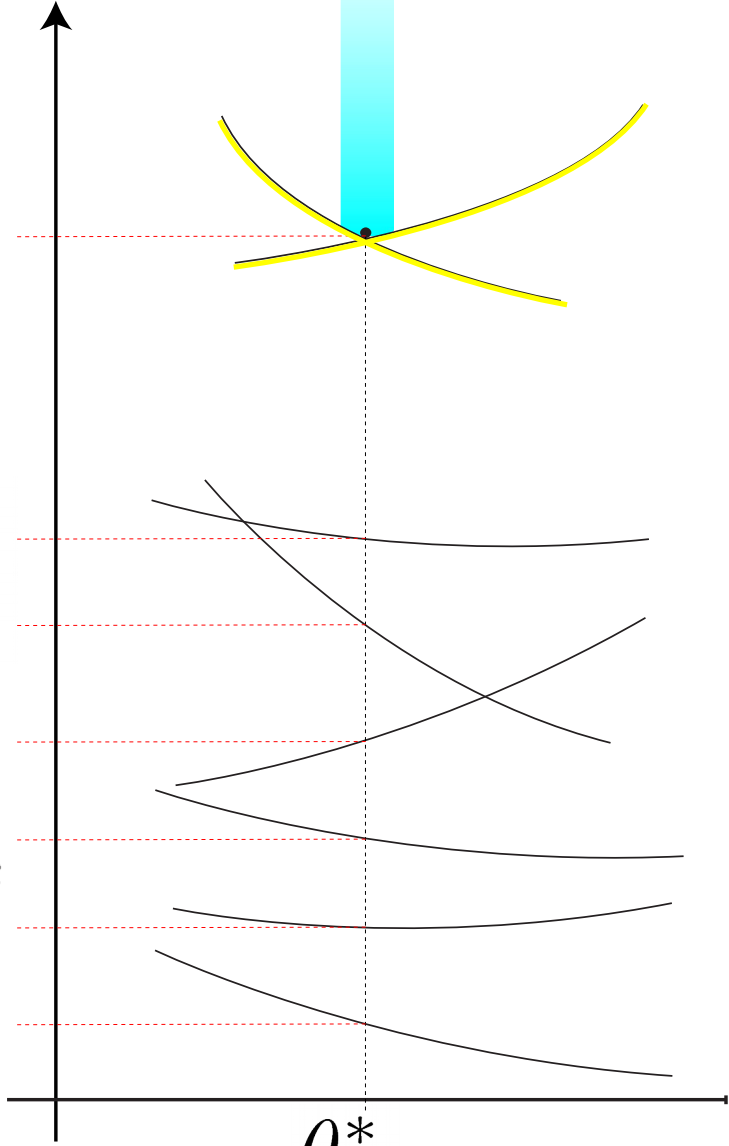


R_1

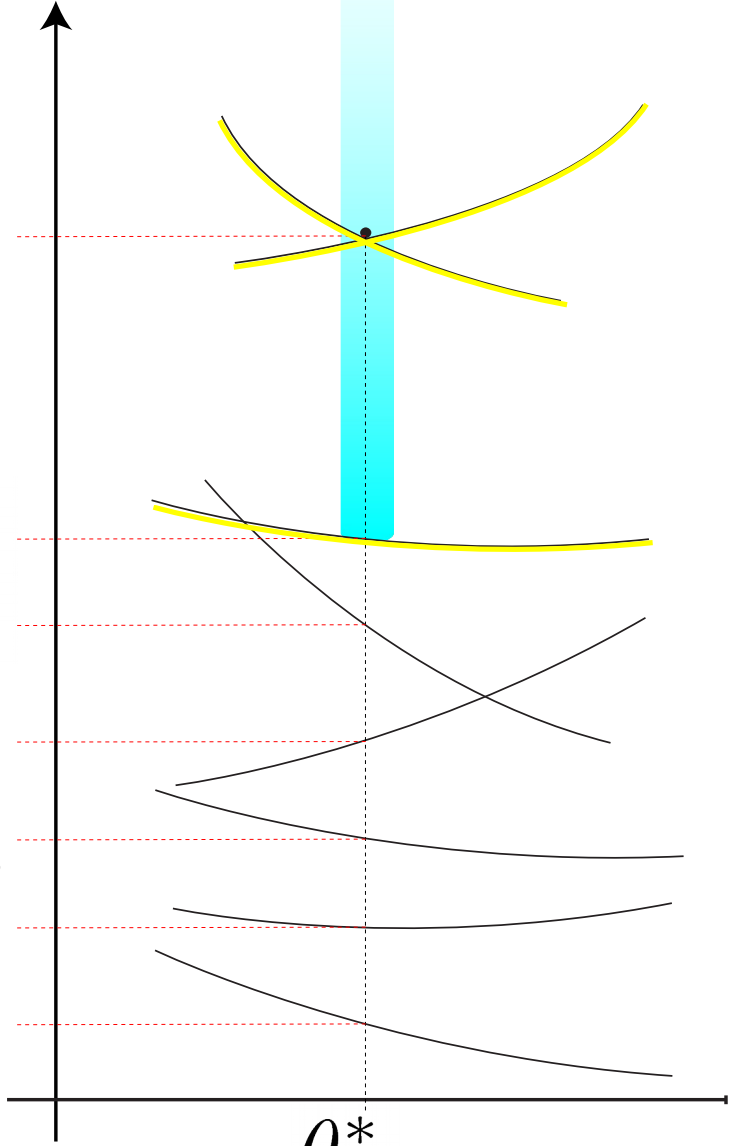




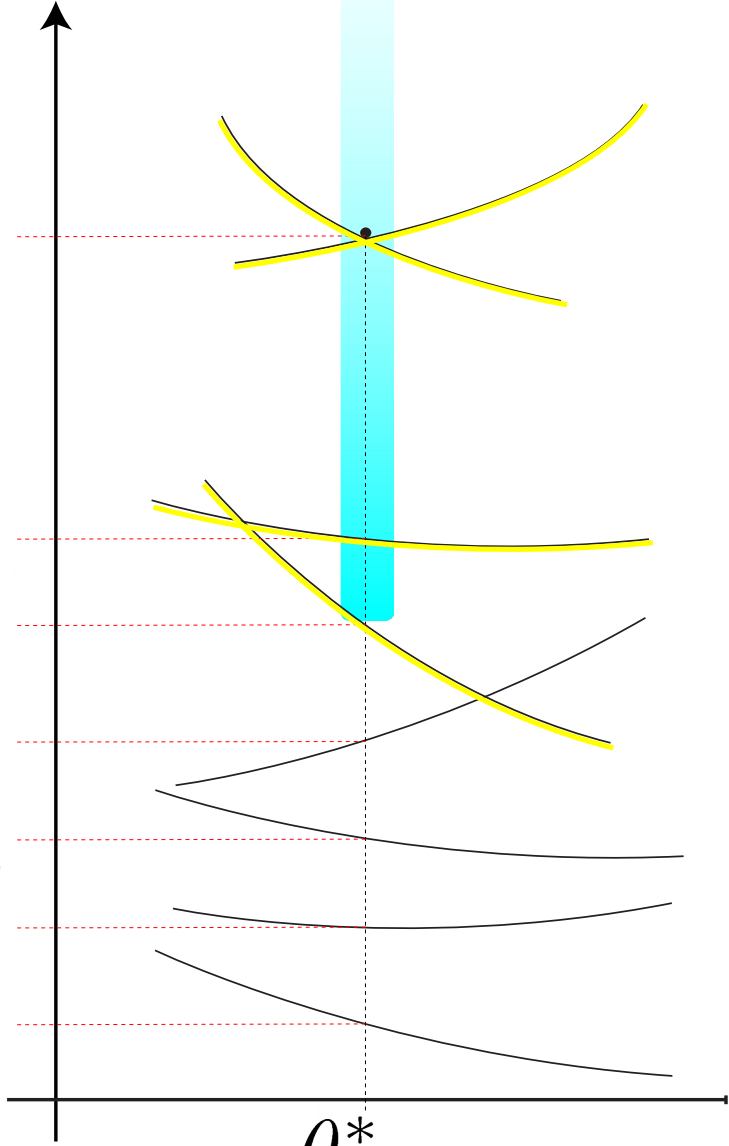
$$R_1 = \mathbb{P}\{\ell(\theta^*, \delta) > c_1^*\}$$

 R_1
 c_1^*
 c_2^*
 c_3^*
 \vdots
 c_k^*
 \vdots
 θ^*


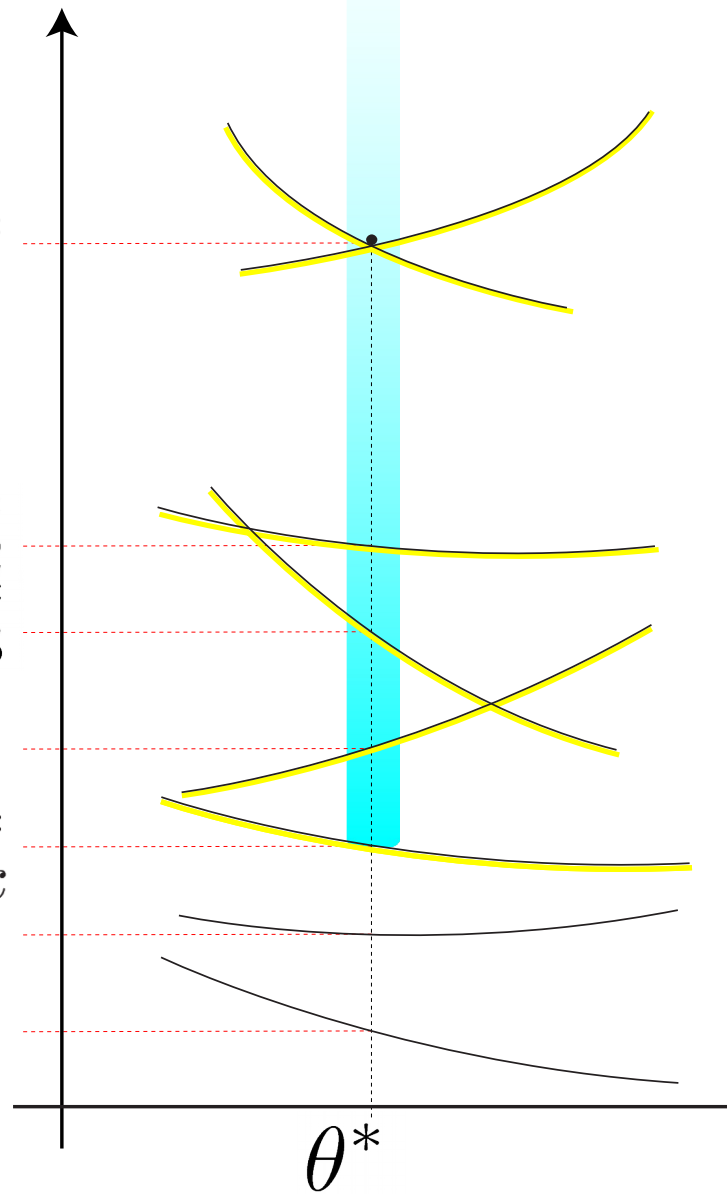
$$R_2 = \mathbb{P}\{\ell(\theta^*, \delta) > c_2^*\}$$

 R_1
 R_2
 c_1^*
 c_2^*
 c_3^*
 \vdots
 c_k^*
 \vdots
 θ^*


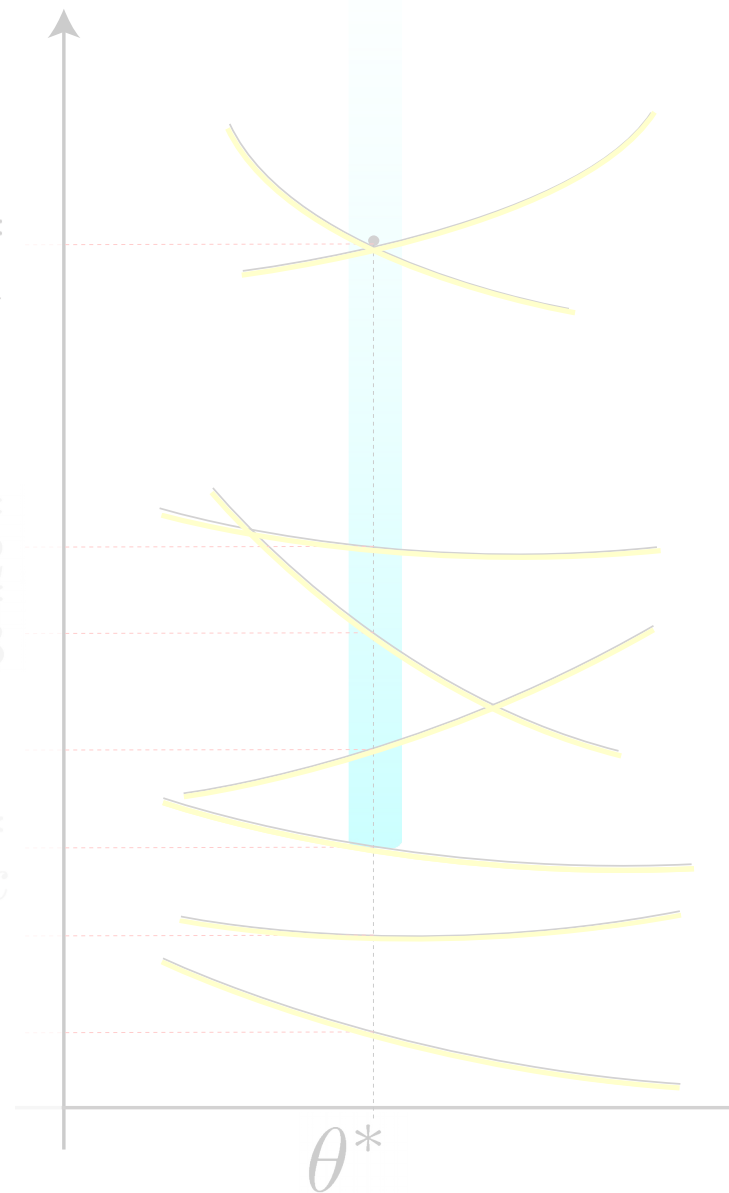
$$R_3 = \mathbb{P}\{\ell(\theta^*, \delta) > c_3^*\}$$

 R_1
 R_2
 R_3
 c_1^*
 c_2^*
 c_3^*
 \vdots
 c_k^*
 \vdots
 θ^*


$$R_k = \mathbb{P}\{\ell(\theta^*, \delta) > c_k^*\}$$

 R_1
 c_1^*
 R_2
 c_2^*
 R_3
 c_3^*
 \vdots
 \vdots
 R_k
 c_k^*
 \vdots
 \vdots


$$R_k = \mathbb{P}\{\ell(\theta^*, \delta) > c_k^*\}$$

 R_1
 c_1^*
 R_2
 c_2^*
 R_3
 c_3^*
 \vdots
 \vdots
 R_k
 c_k^*
 \vdots
 \vdots


$$R_k = \mathbb{P}\{\ell(\theta^*, \delta) > c_k^*\}$$

$$R_1$$

$$R_2$$

$$R_3$$

$$\vdots$$

$$R_k$$

$$\vdots$$

$$R_k = \mathbb{P}\{\ell(\theta^*, \delta) > c_k^*\}$$

R_1

R_2

R_3

\vdots

R_k

\vdots

N and d
are all that
matters

$$R_k = \mathbb{P}\{\ell(\theta^*, \delta) > c_k^*\}$$

$$R_1$$

$$R_2$$

$$R_3$$

$$\vdots$$

$$R_k \in [\underline{\epsilon}_k, \bar{\epsilon}_k]$$

$$R_k$$

$$\vdots$$

N and **d**
are all that
matters

$$R_k = \mathbb{P}\{\ell(\theta^*, \delta) > c_k^*\}$$

$$R_1$$

$$R_2$$

$$R_3$$

$$\vdots$$

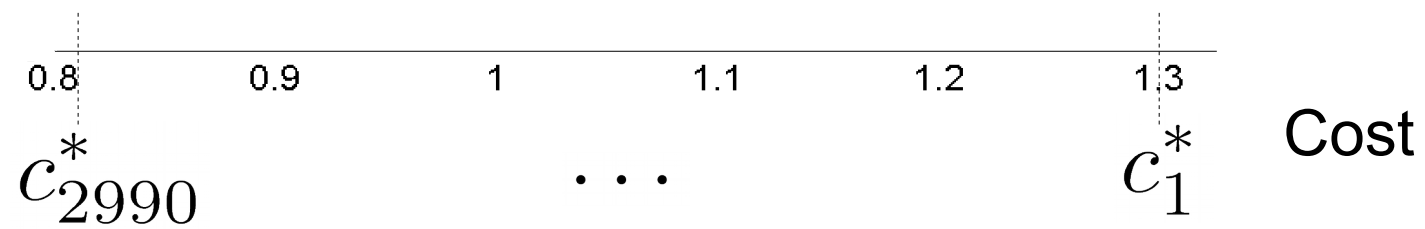
$$R_k \in [\underline{\epsilon}_k, \bar{\epsilon}_k]$$

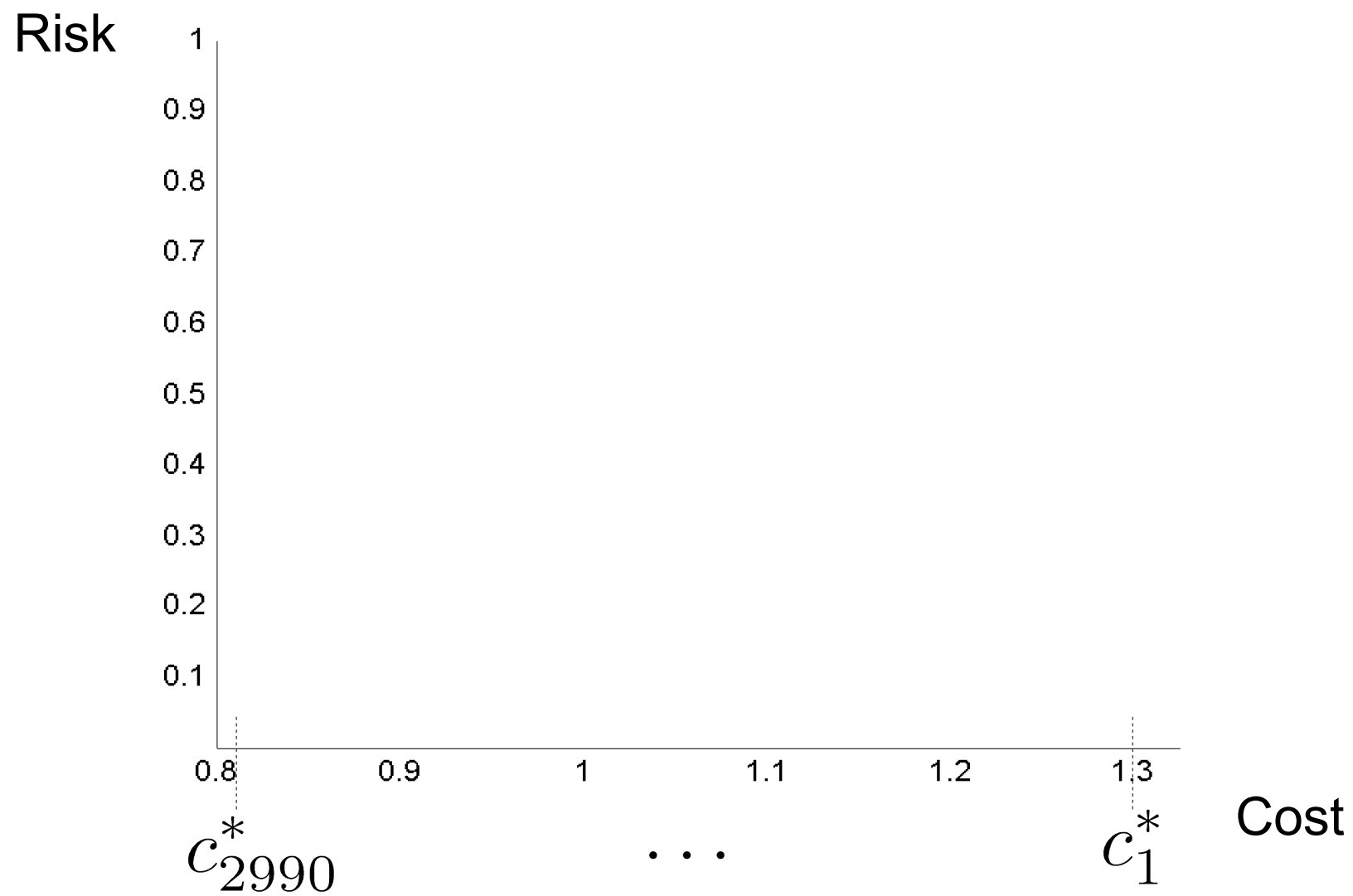
$$R_k$$

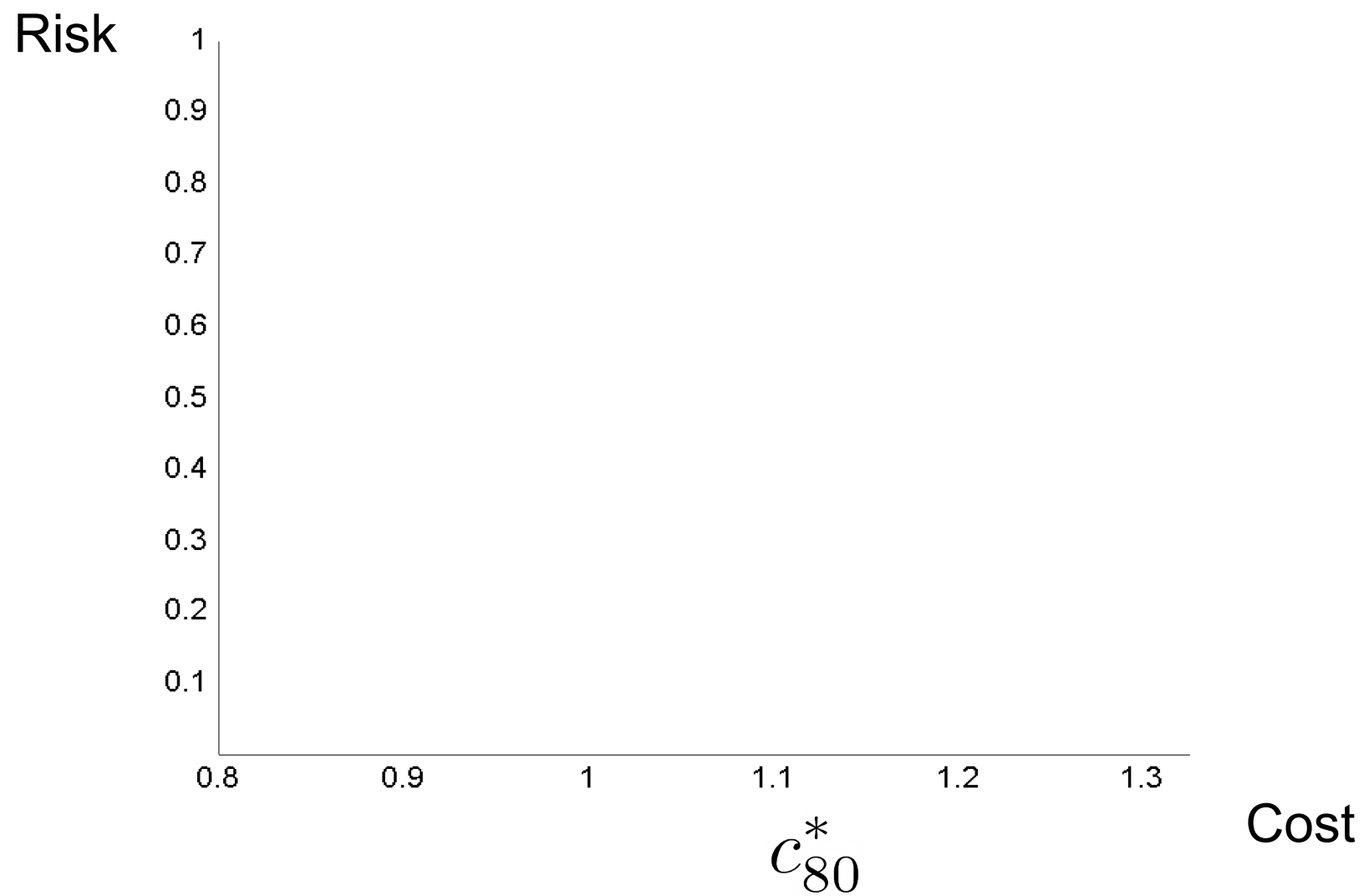
N and d
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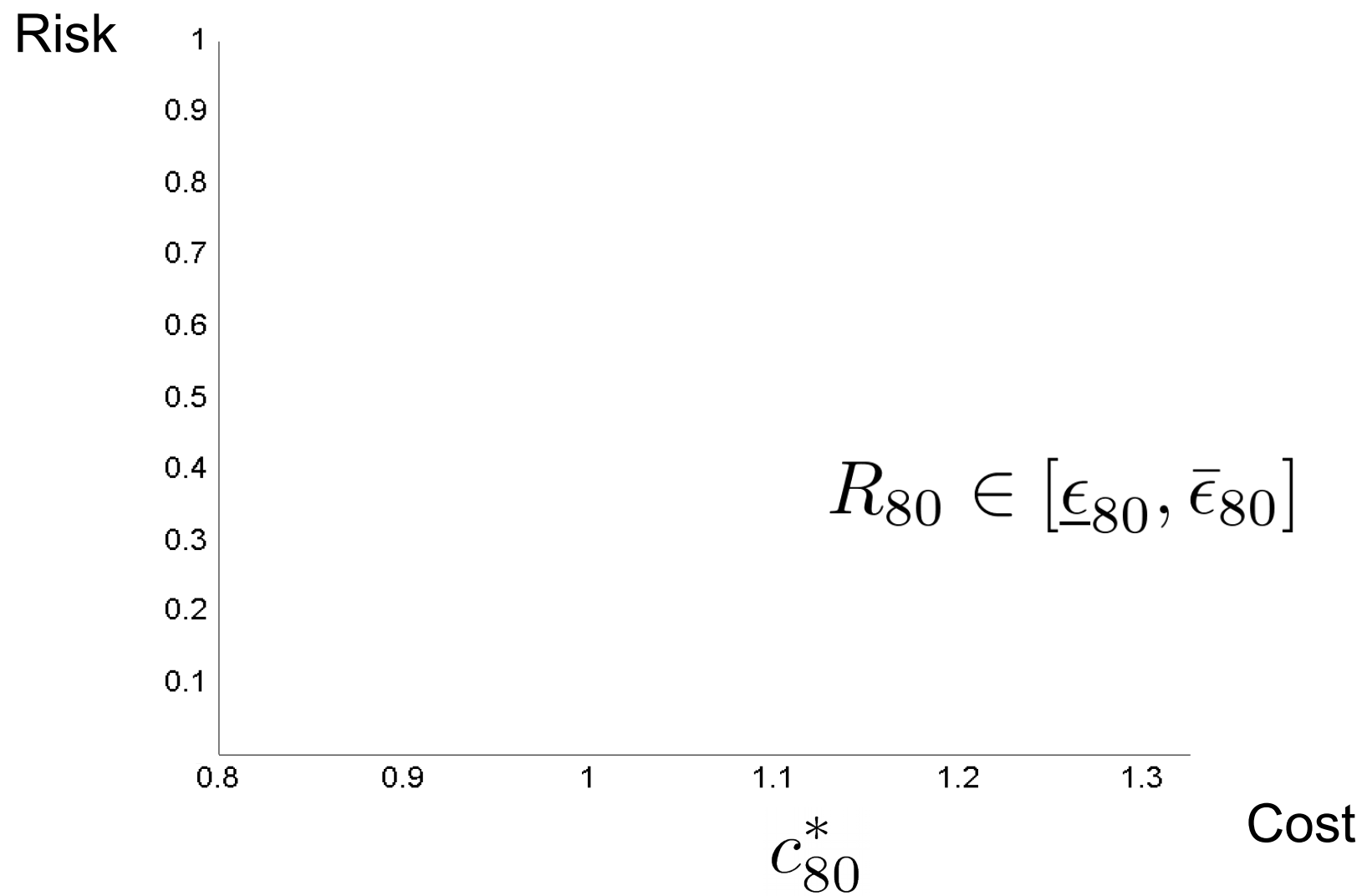
with confidence $1-10^{-6}$

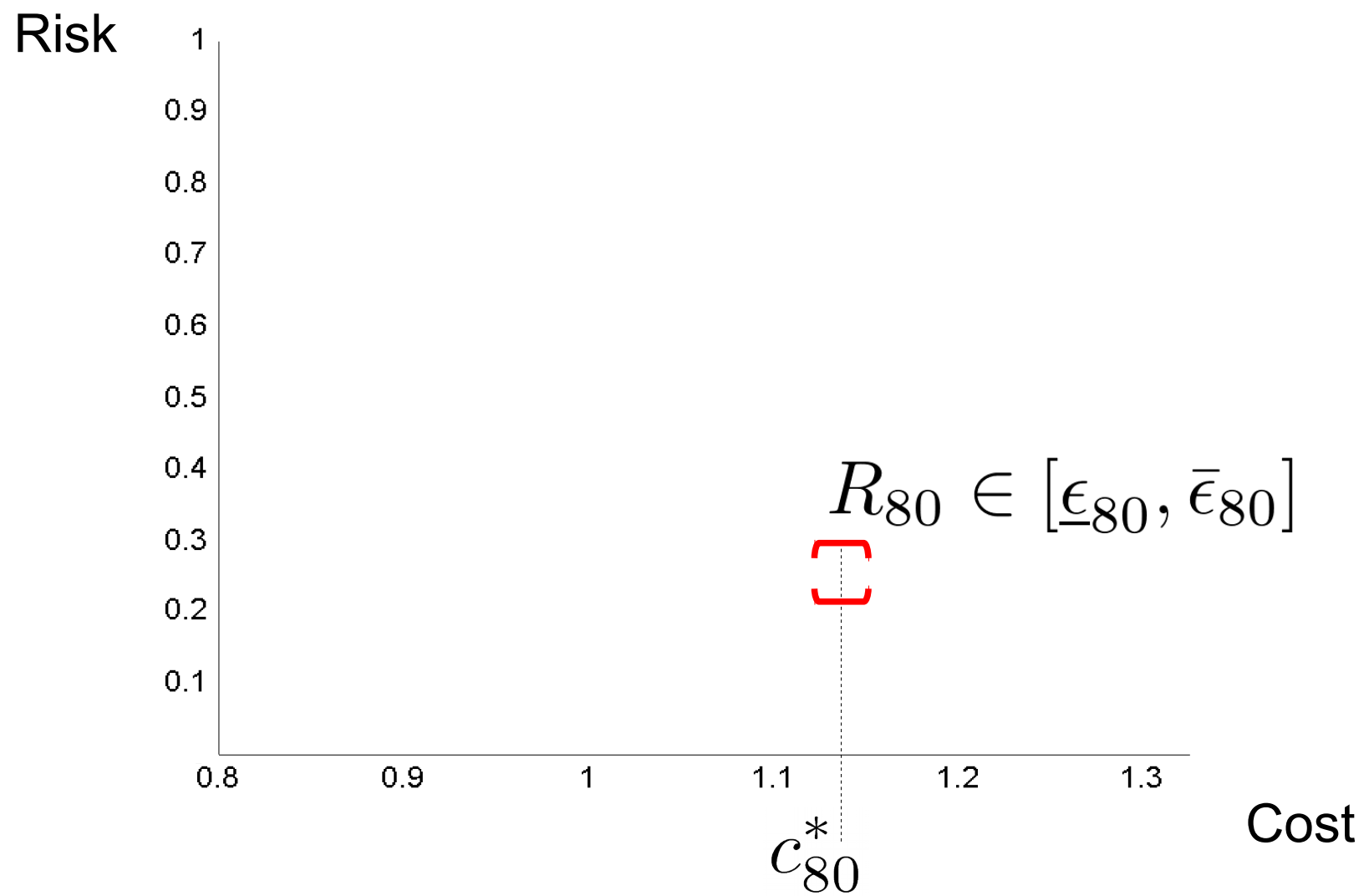
$$\vdots$$

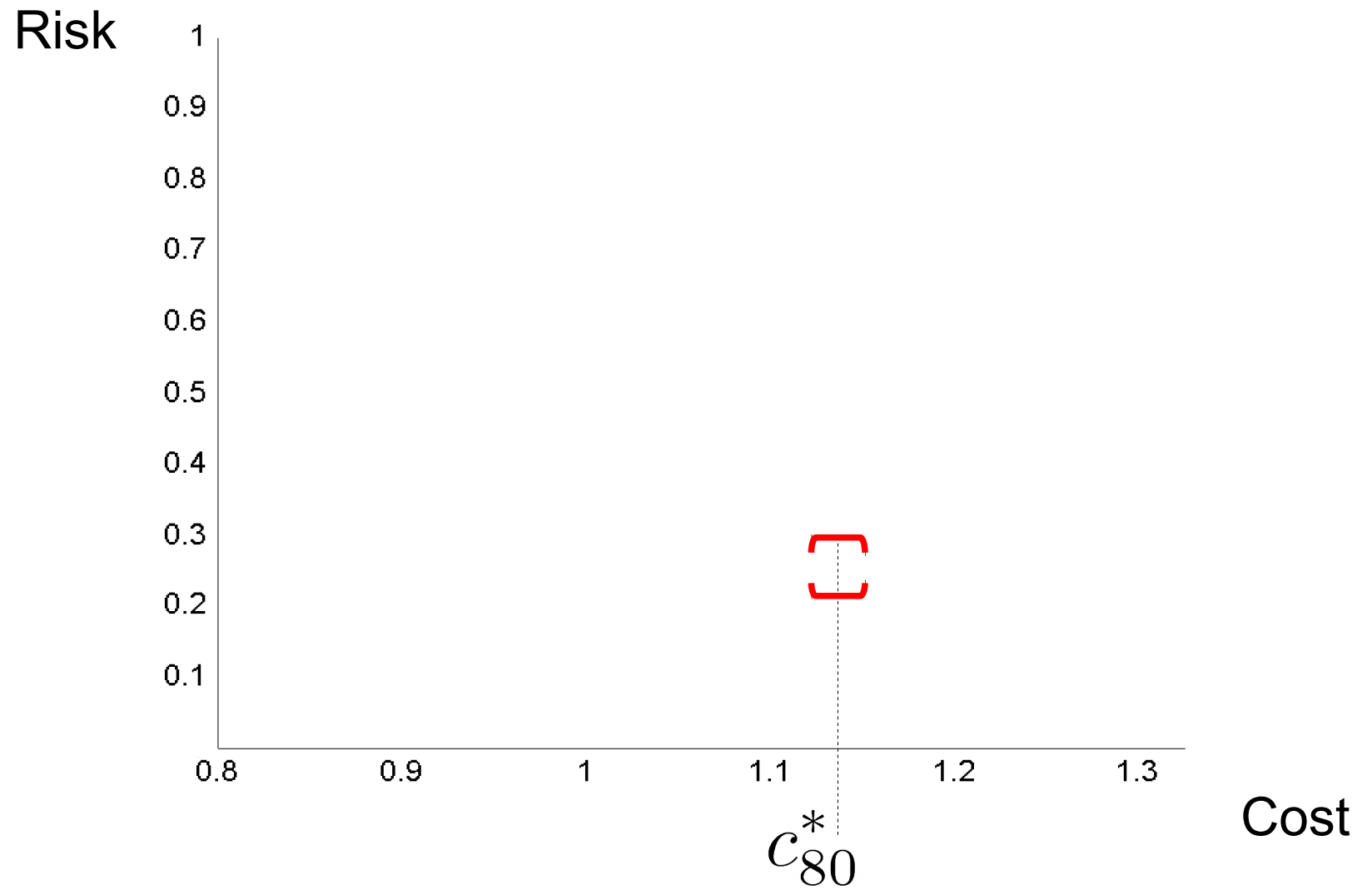


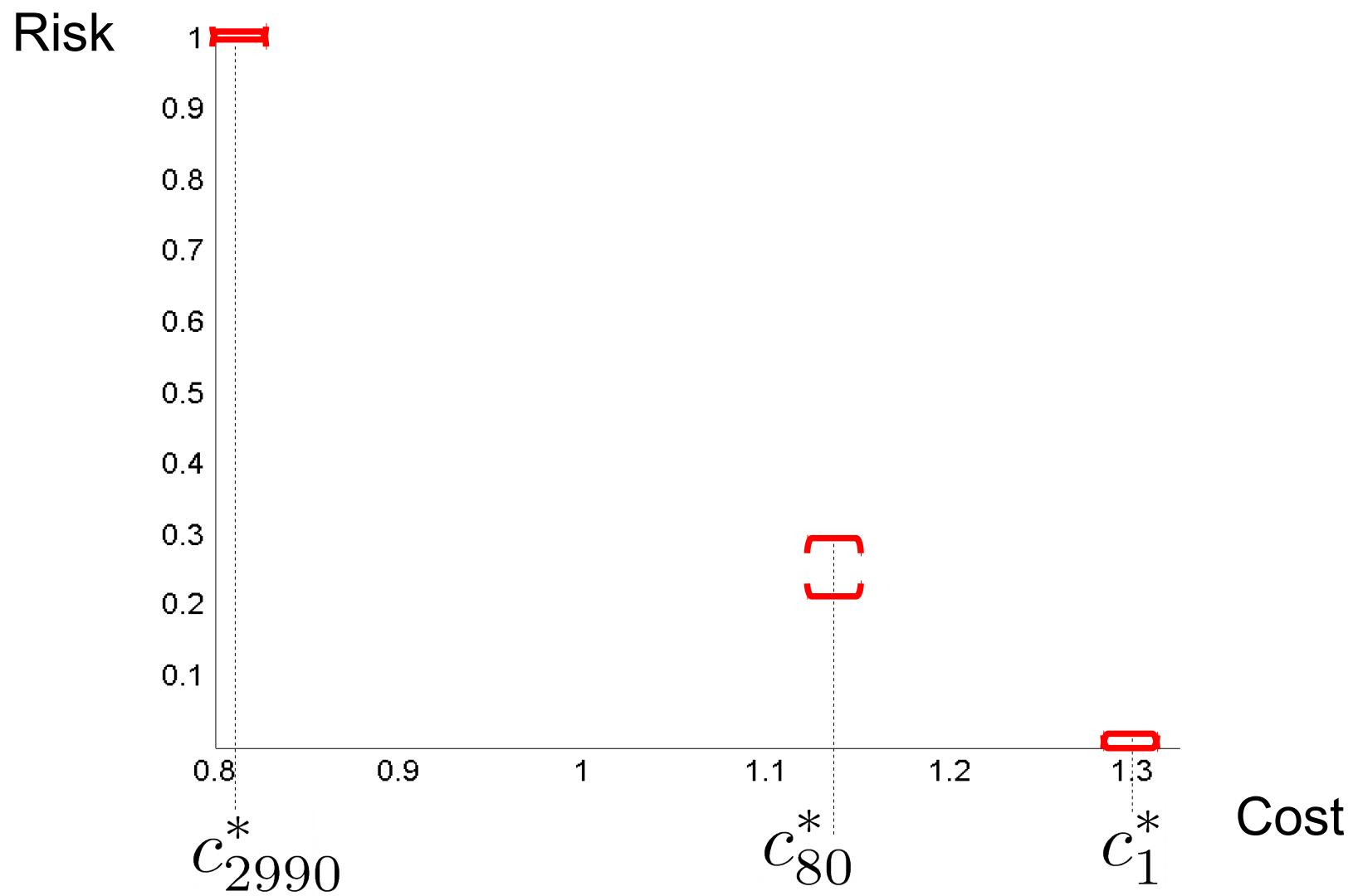


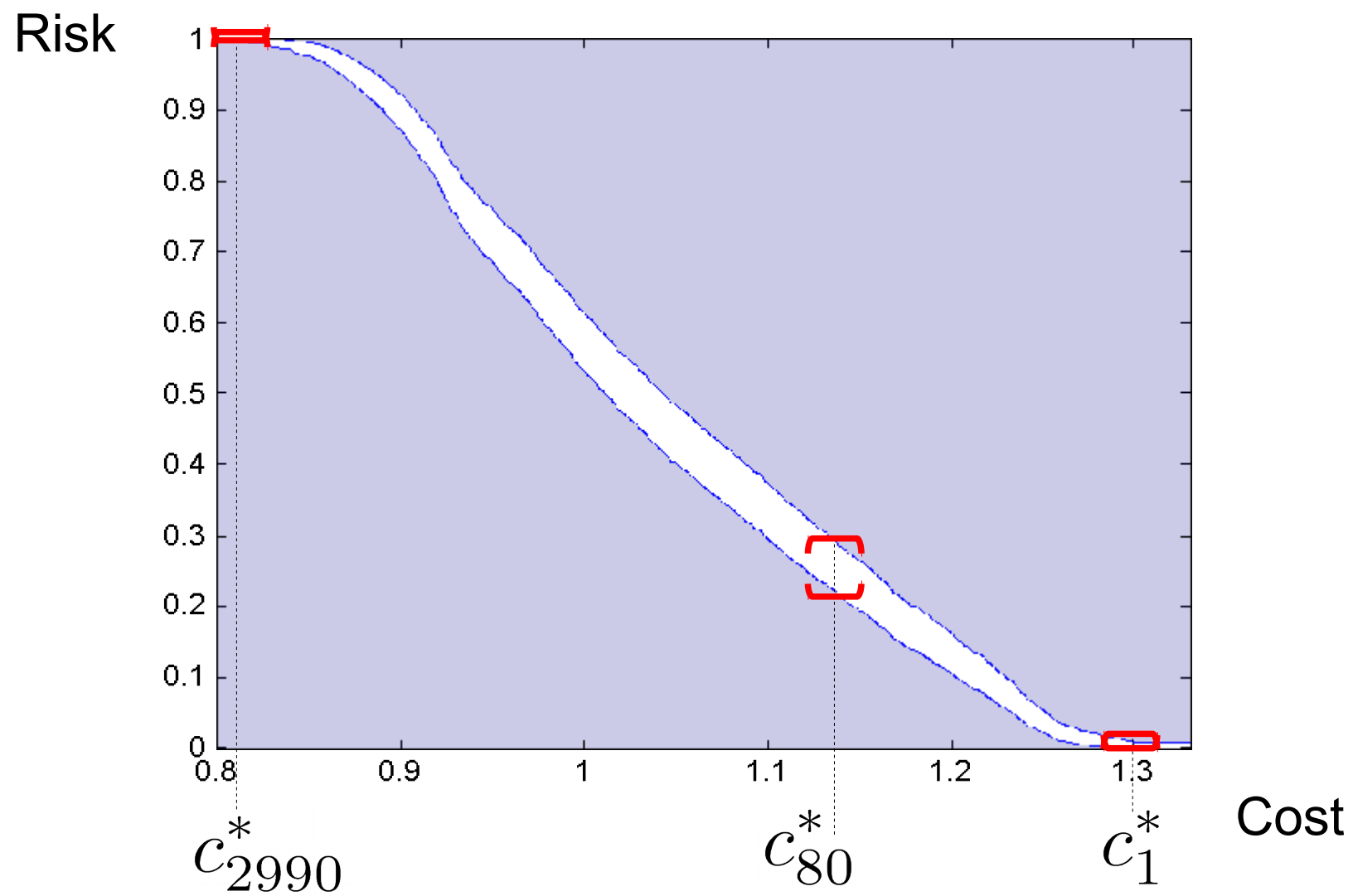




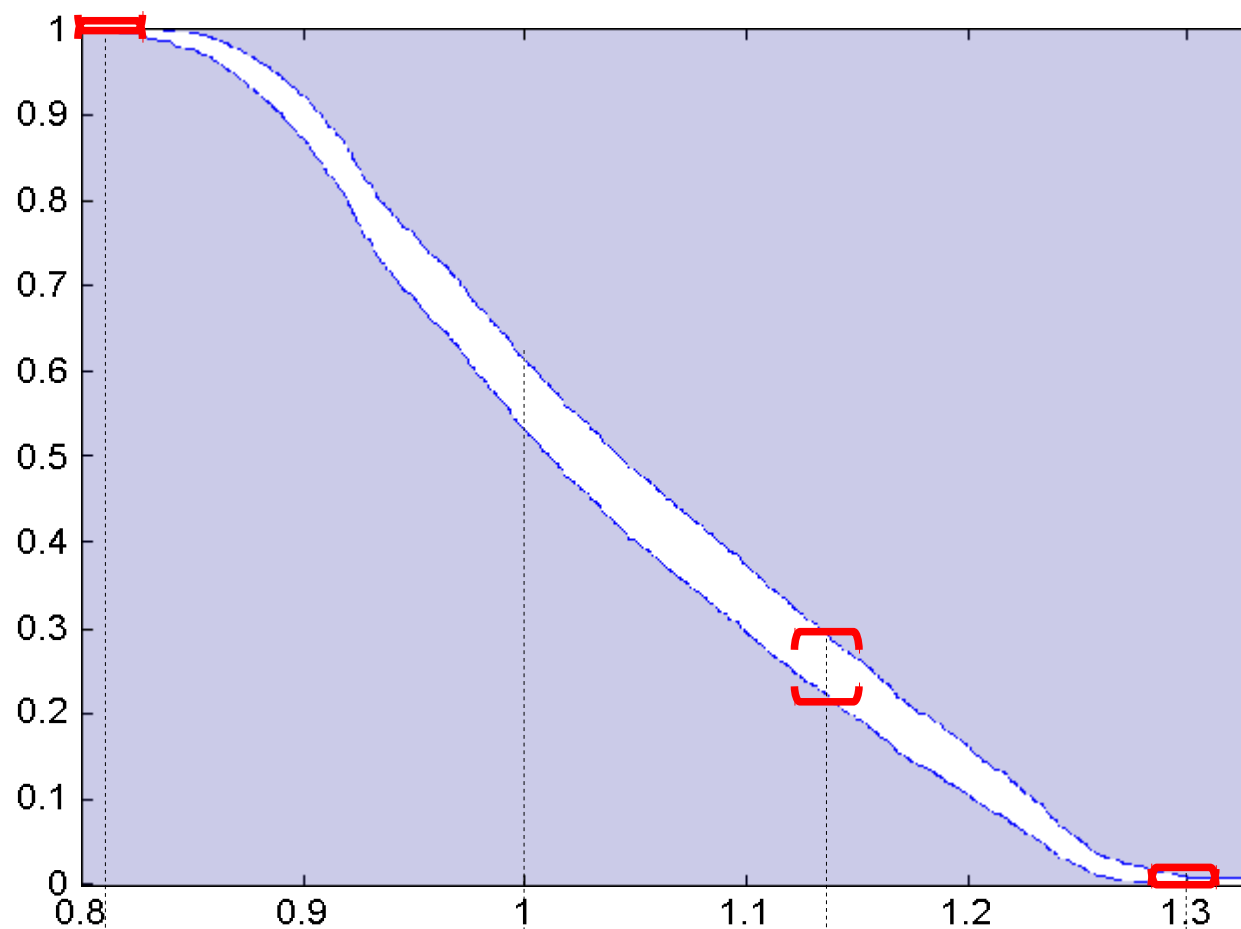






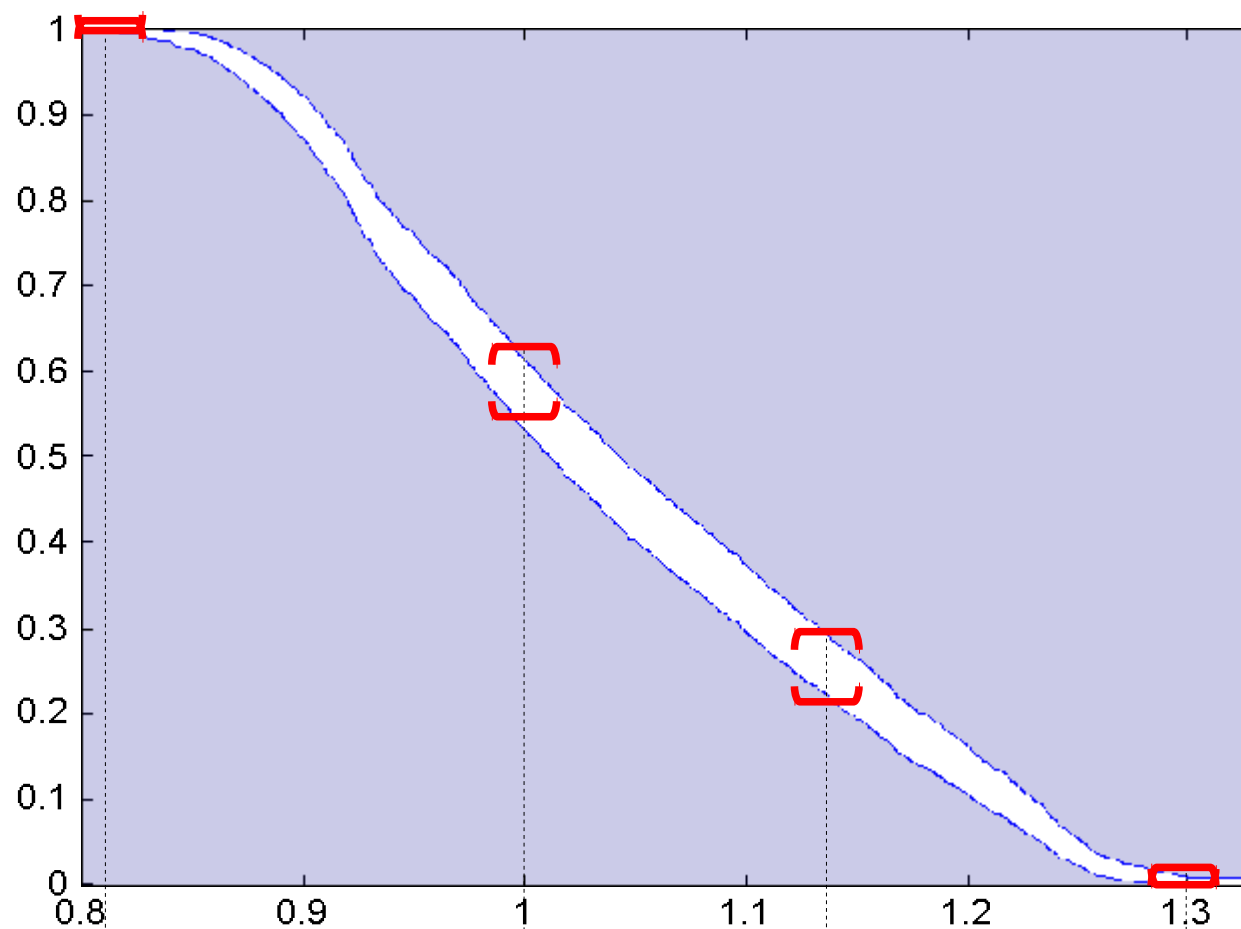


Risk



Cost

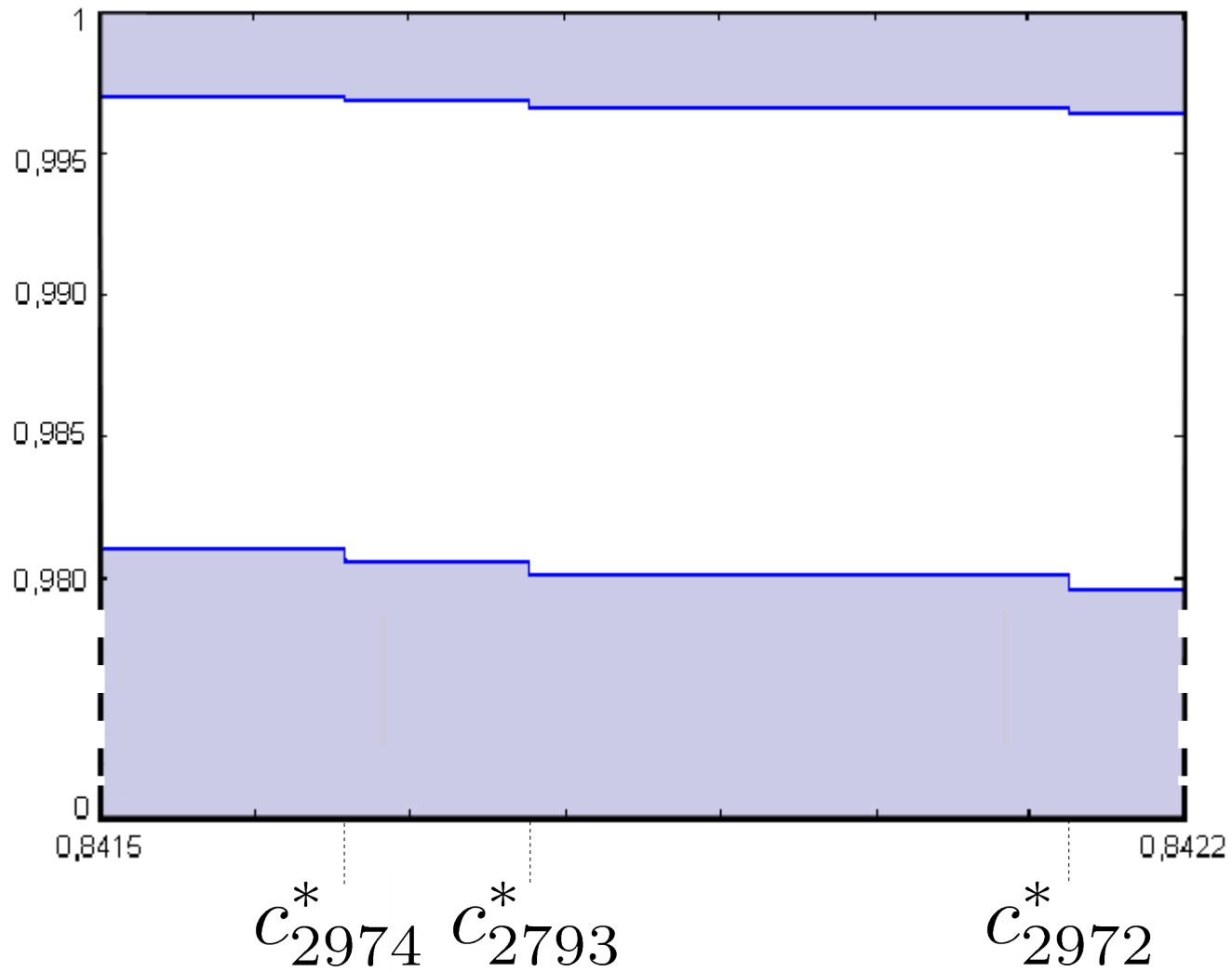
Risk



Cost

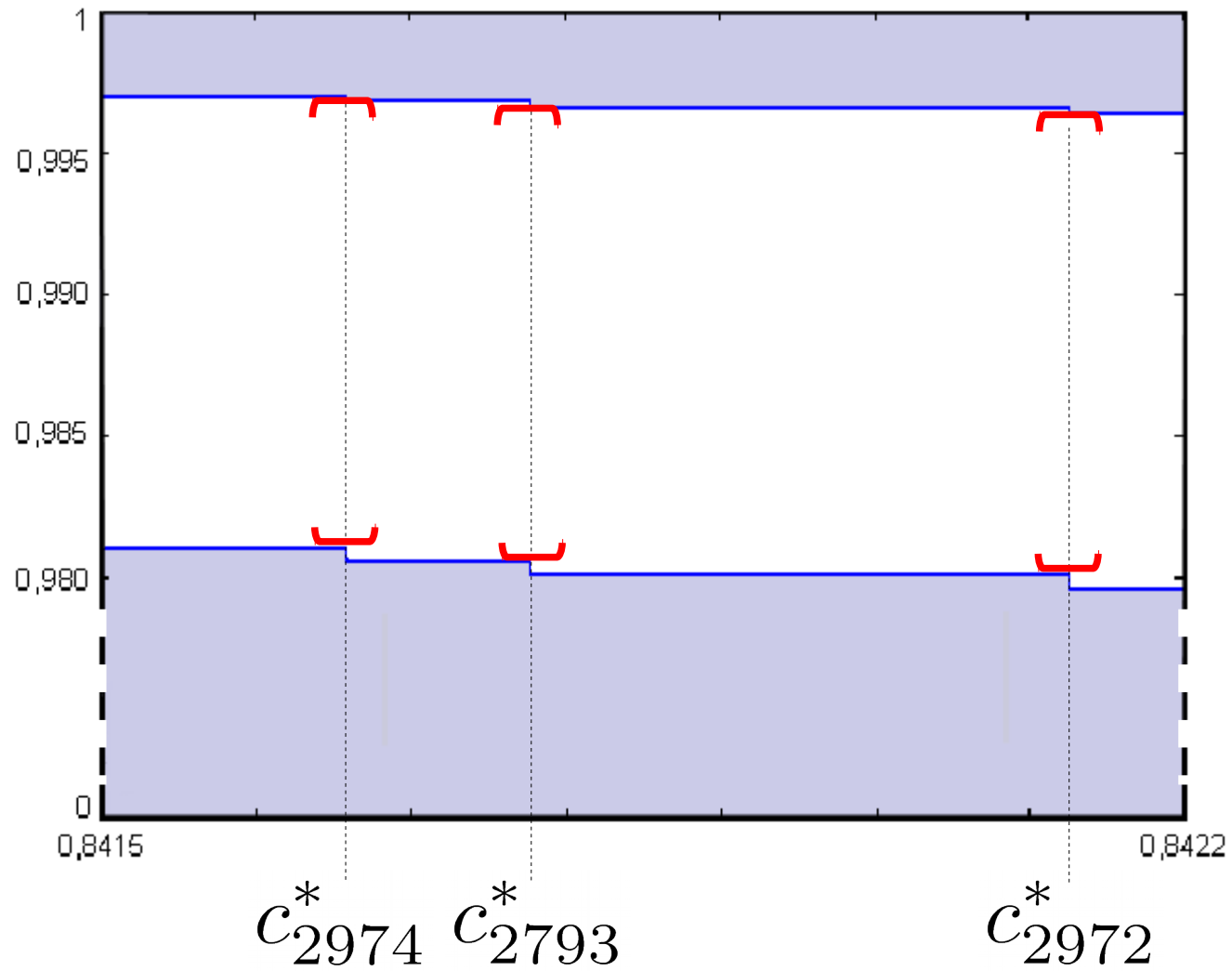
Zoomed detail

Risk



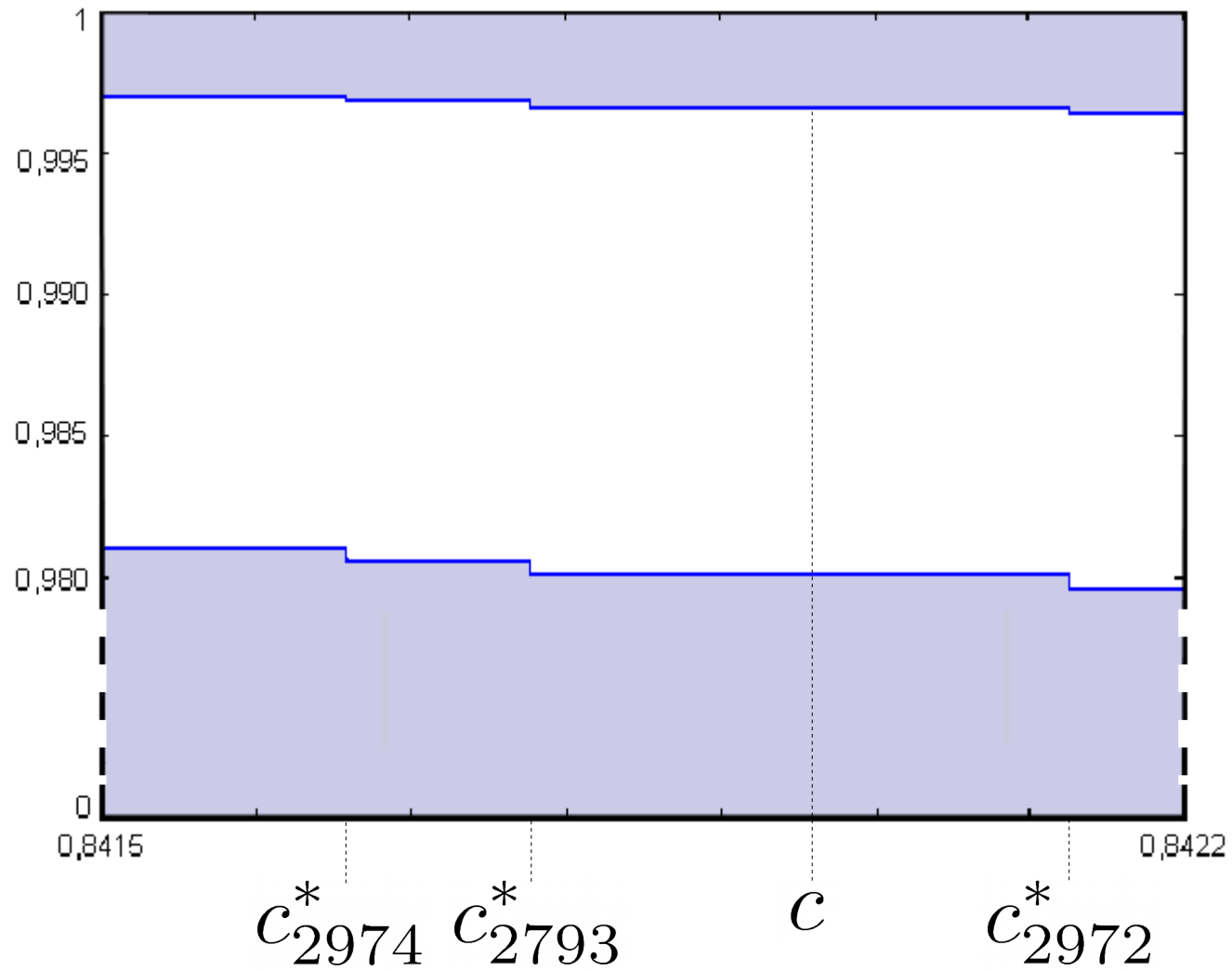
Zoomed detail

Risk



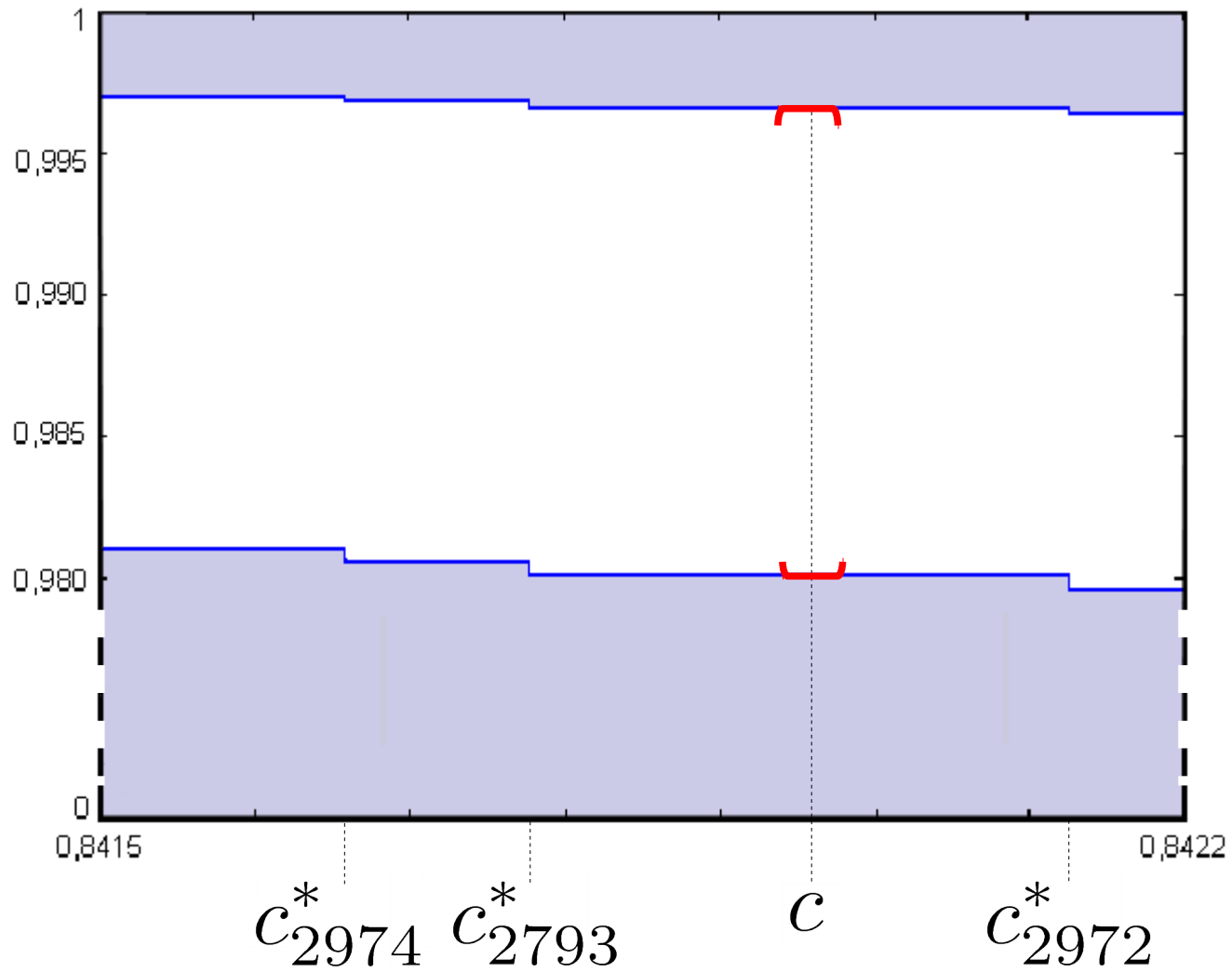
Zoomed detail

Risk



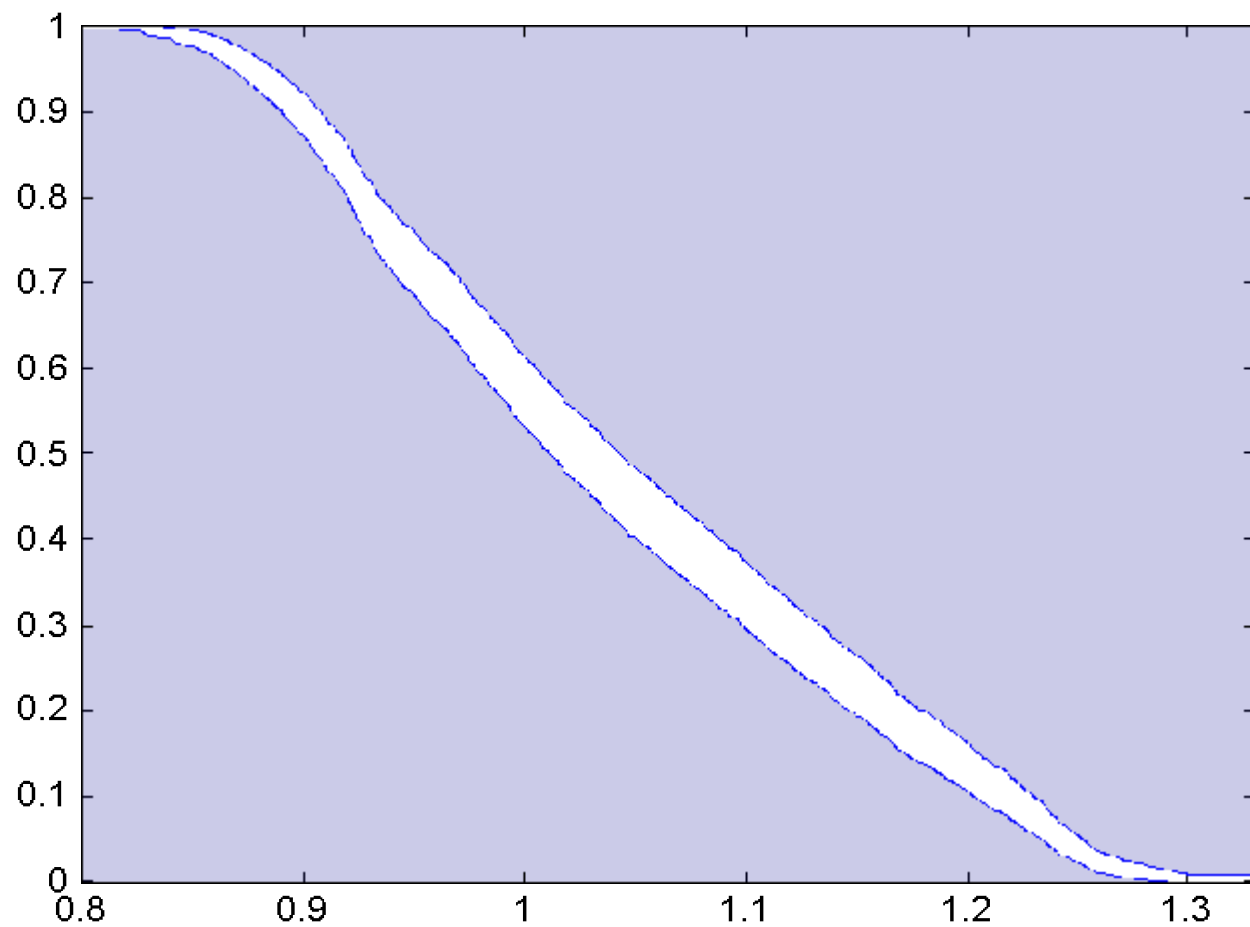
Zoomed detail

Risk



$$(\mathbb{P}\{\ell(\theta^*, \delta) > c\})$$

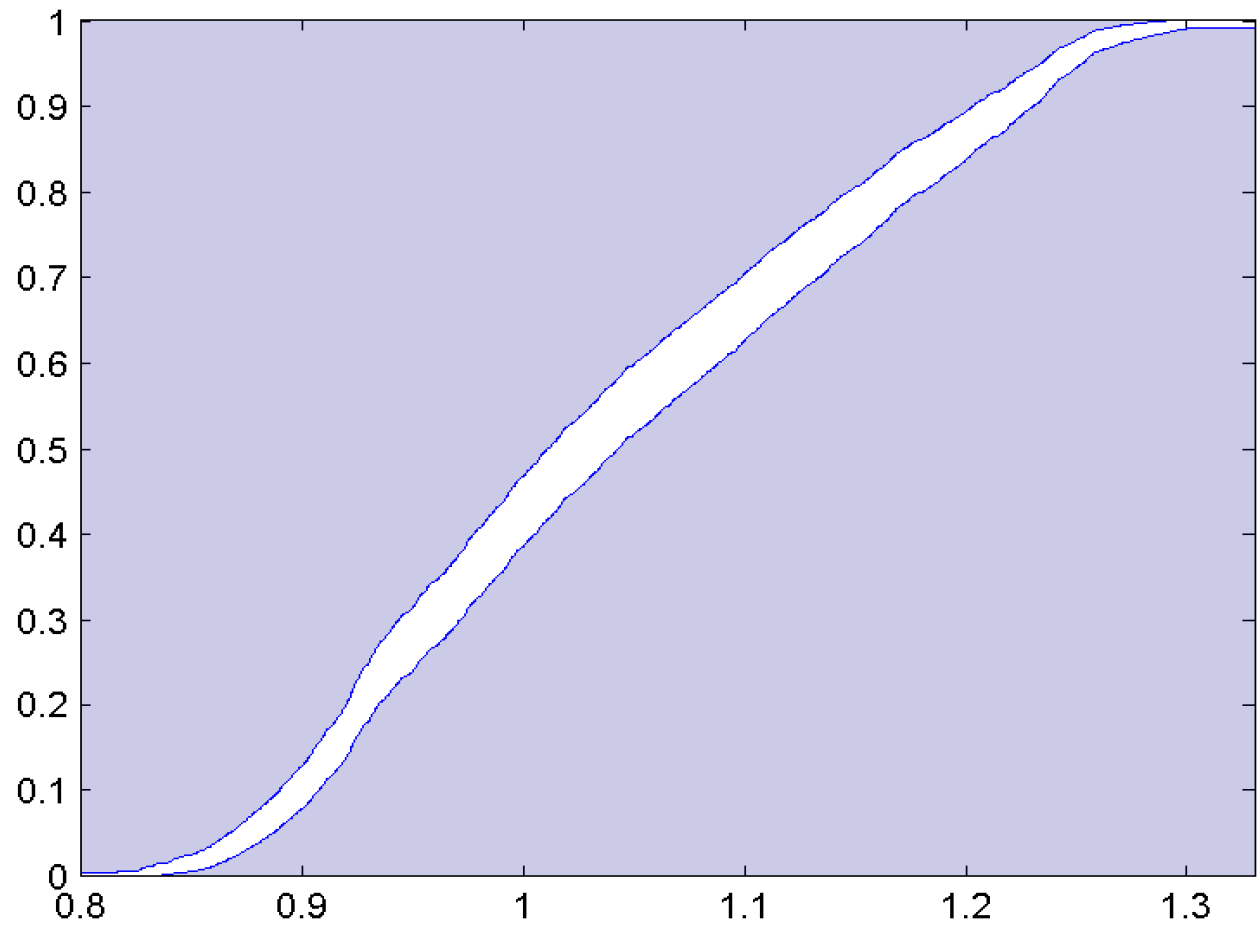
Risk



Cost
(c)

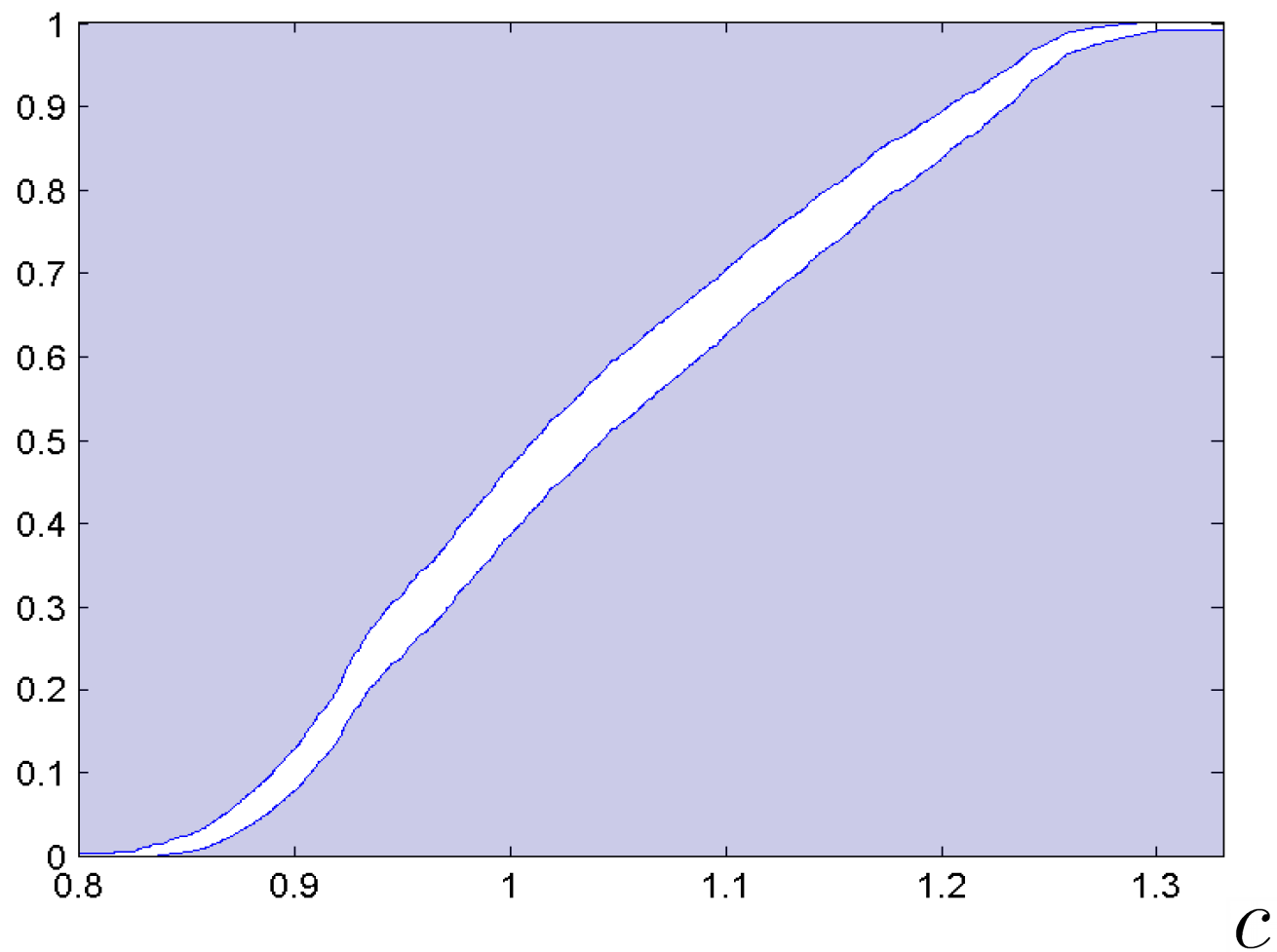
$$(\mathbb{P}\{\ell(\theta^*, \delta) \leq c\})$$

1-Risk

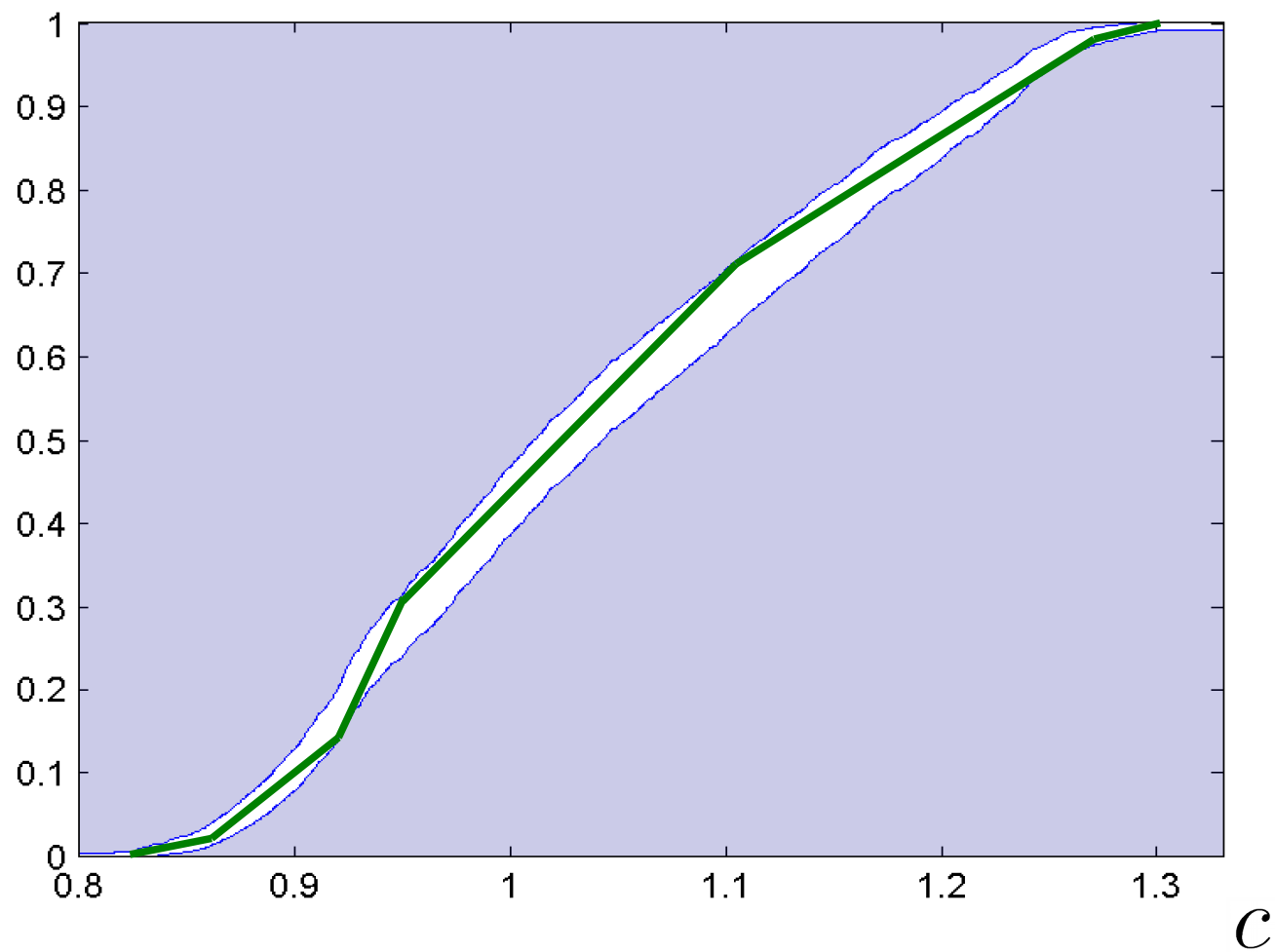


Cost
(c)

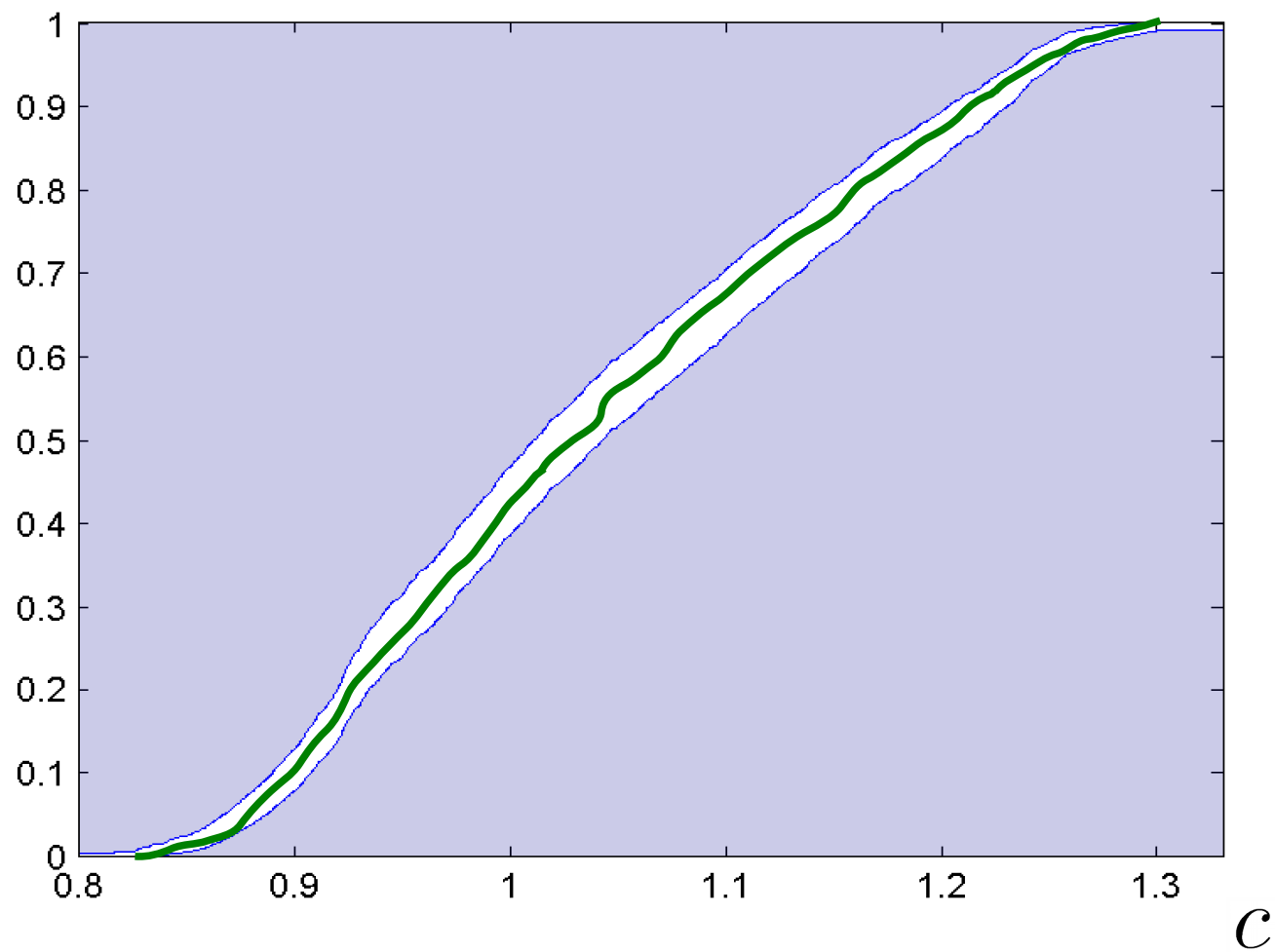
$$\text{CDF}_{\ell(\theta^*, \delta)}(c)$$



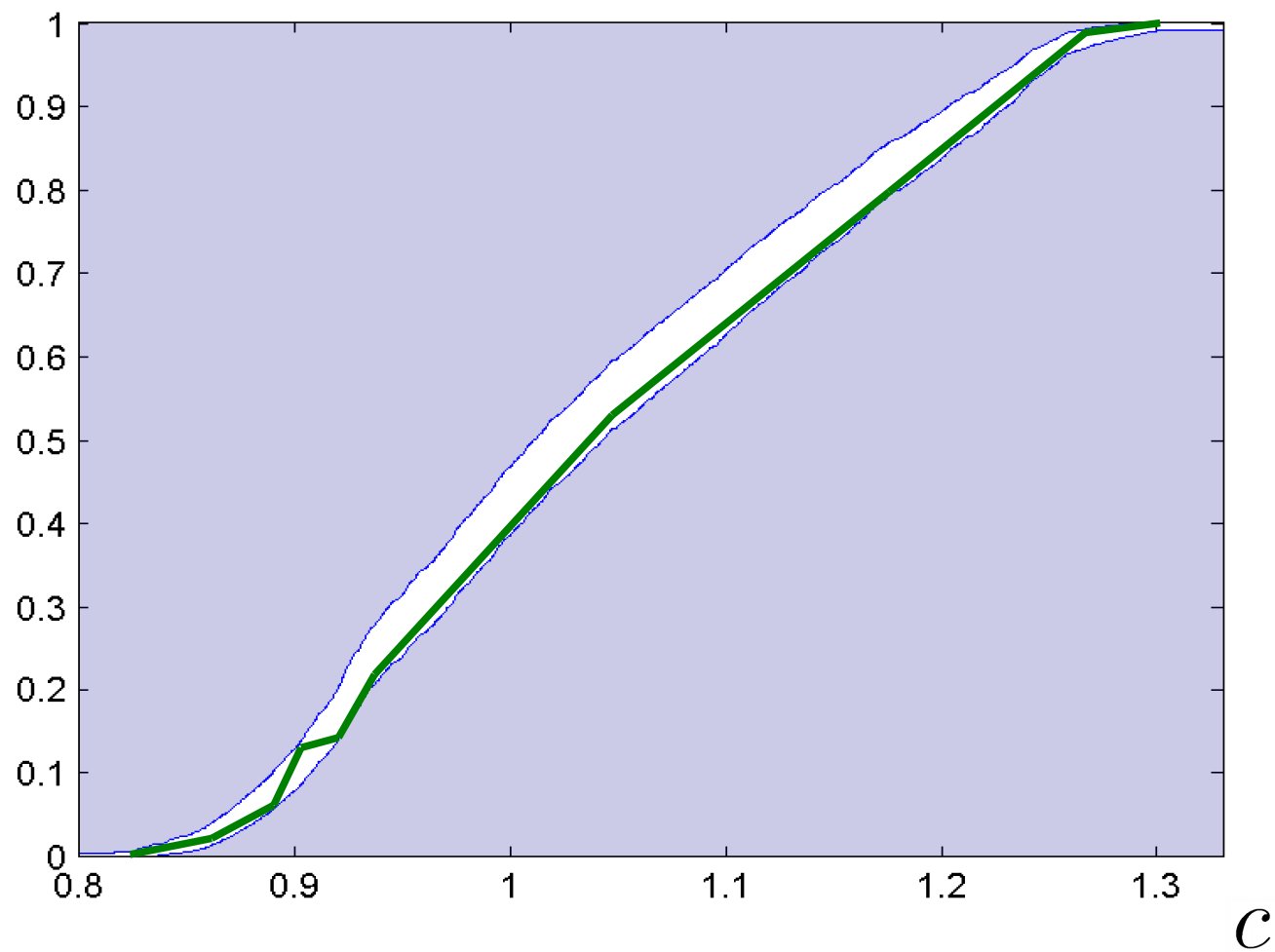
$$\text{CDF}_{\ell(\theta^*, \delta)}(c)$$



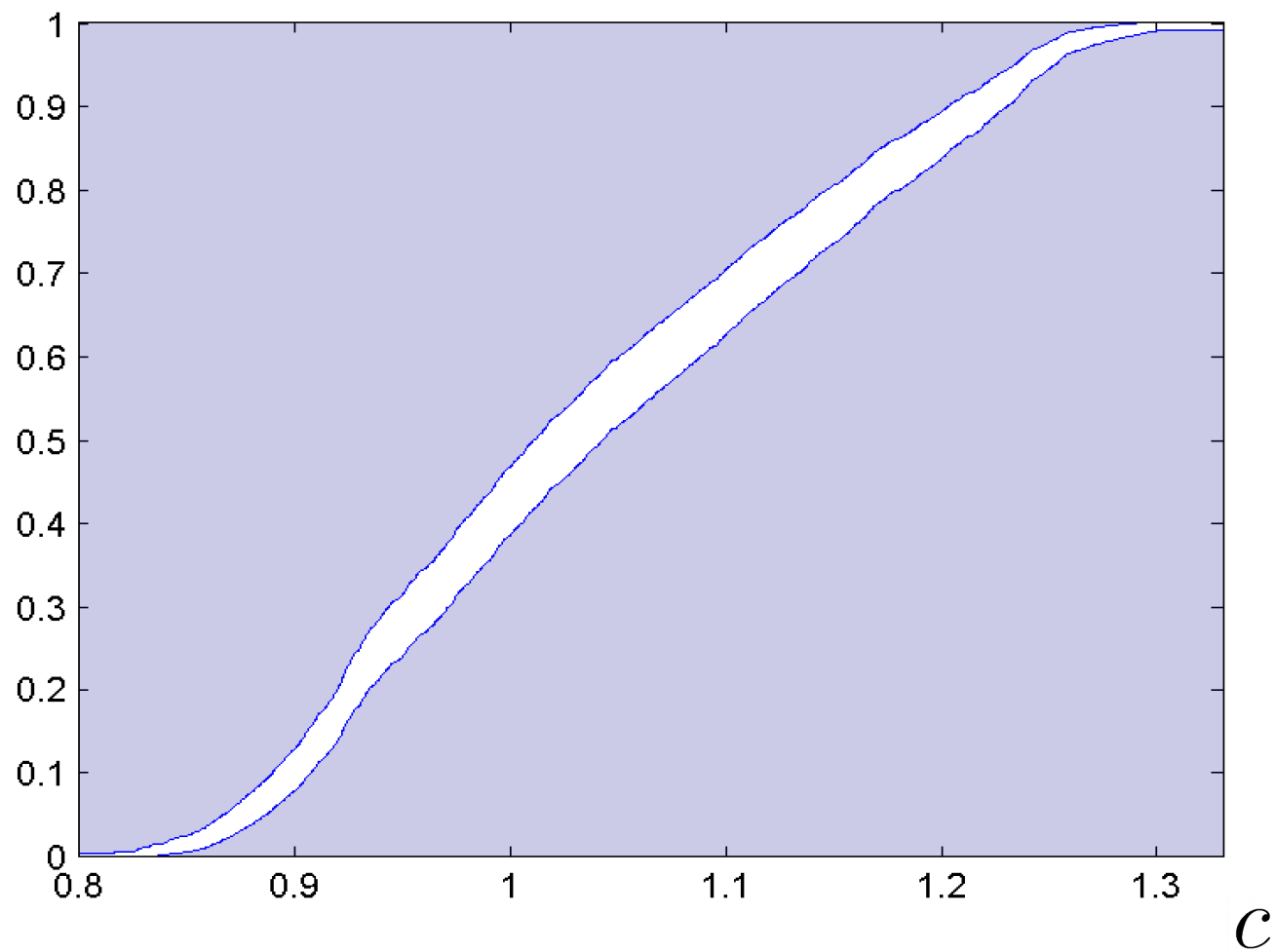
$$\text{CDF}_{\ell(\theta^*, \delta)}(c)$$



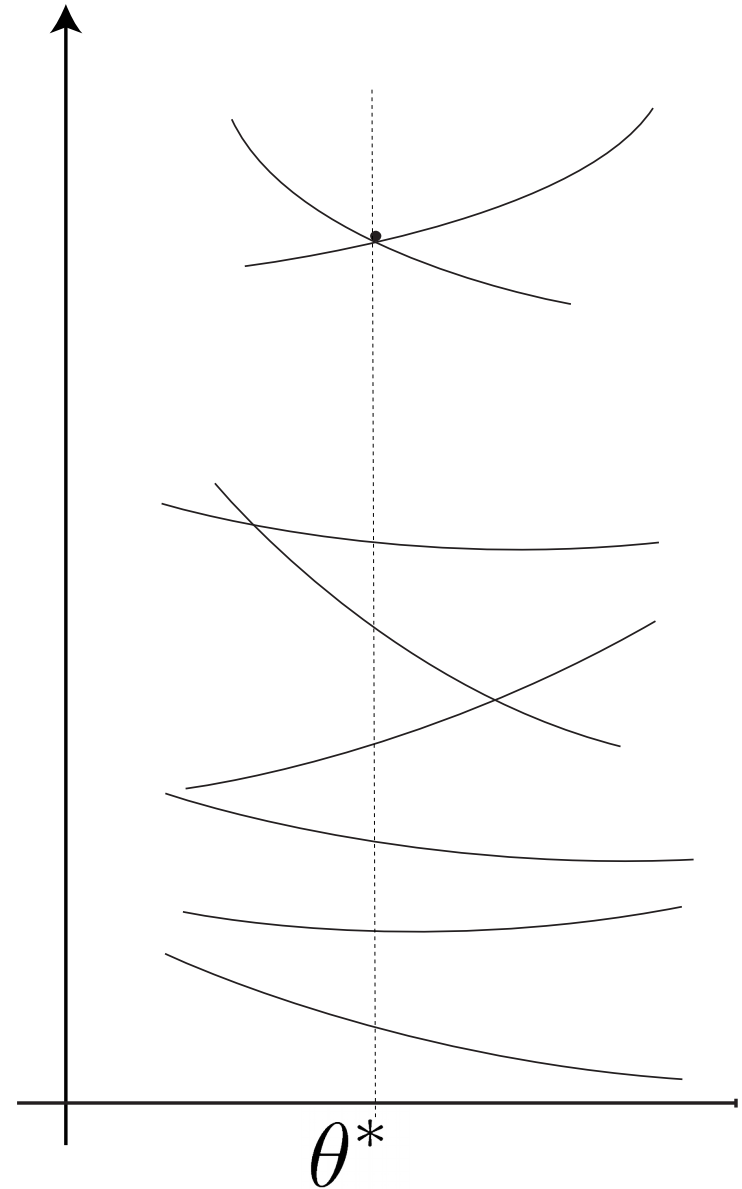
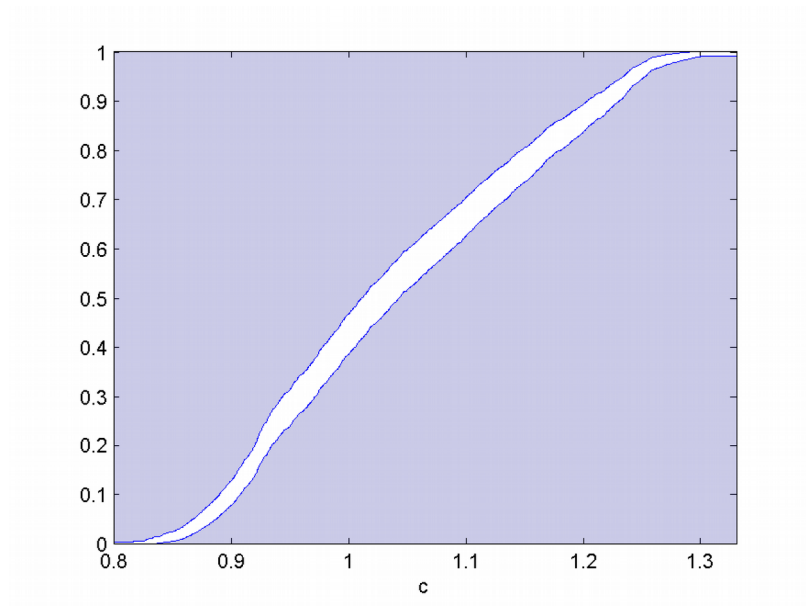
$$\text{CDF}_{\ell(\theta^*, \delta)}(c)$$



$$\text{CDF}_{\ell(\theta^*, \delta)}(c)$$



Probability distribution of $\ell(\theta^*, \delta)$



We have reconstructed (wrapped)
the real distribution of the
cost from data (N scenarios).

No specific knowledge of $\ell(\theta, \delta)$, Δ
and \mathbb{P} has been used.

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Thank you!

REFERENCE

A. Carè, S. Garatti, and M.C. Campi,
Scenario Min–Max Optimization and the Risk of Empirical Costs.
SIAM Journal on Optimization, 25(4):2061–2080, 2015.

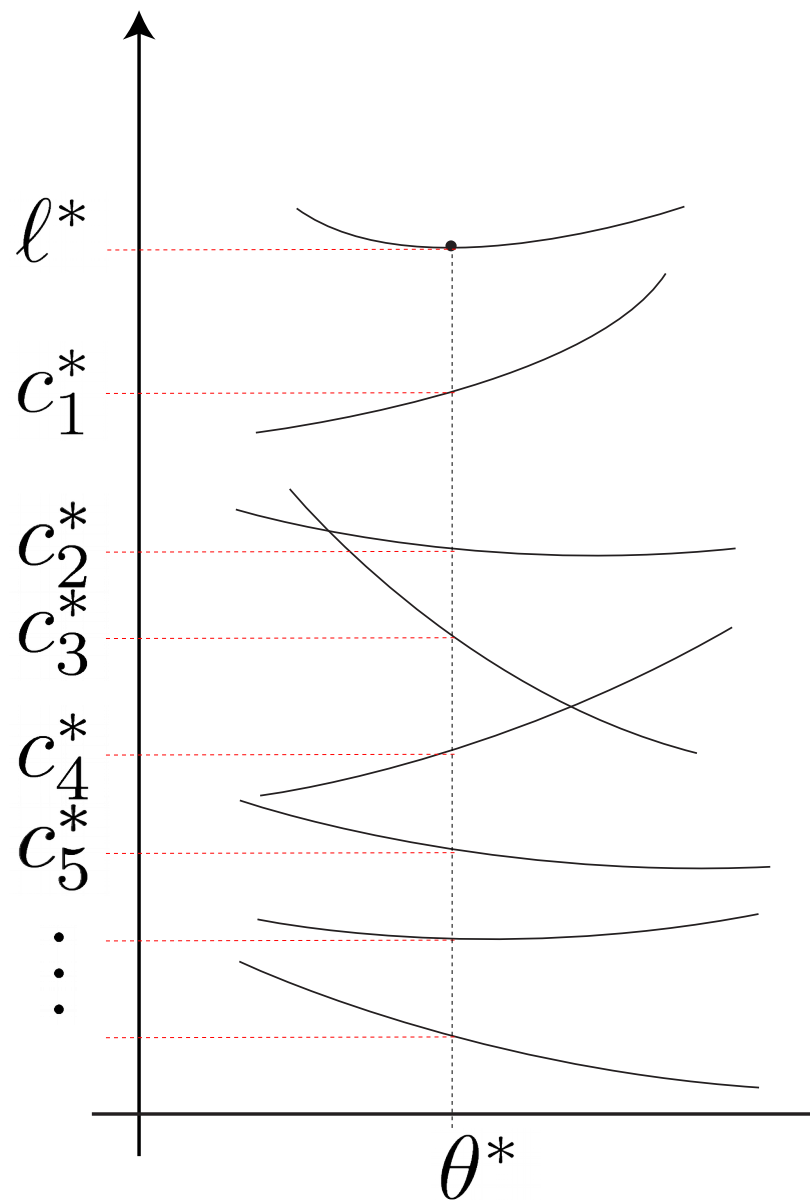
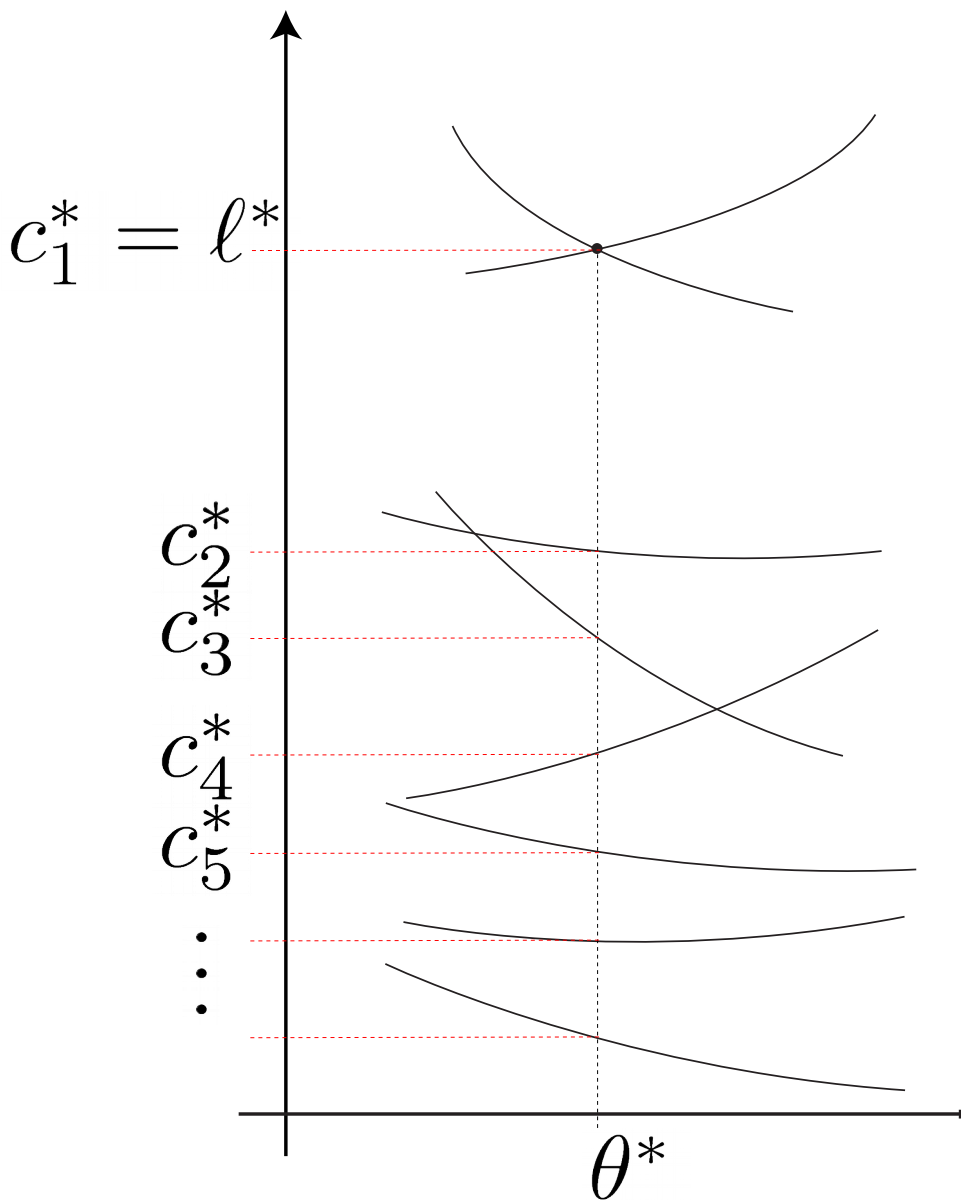
algo.care@gmail.com

Ordered Dirichlet C.D.F.

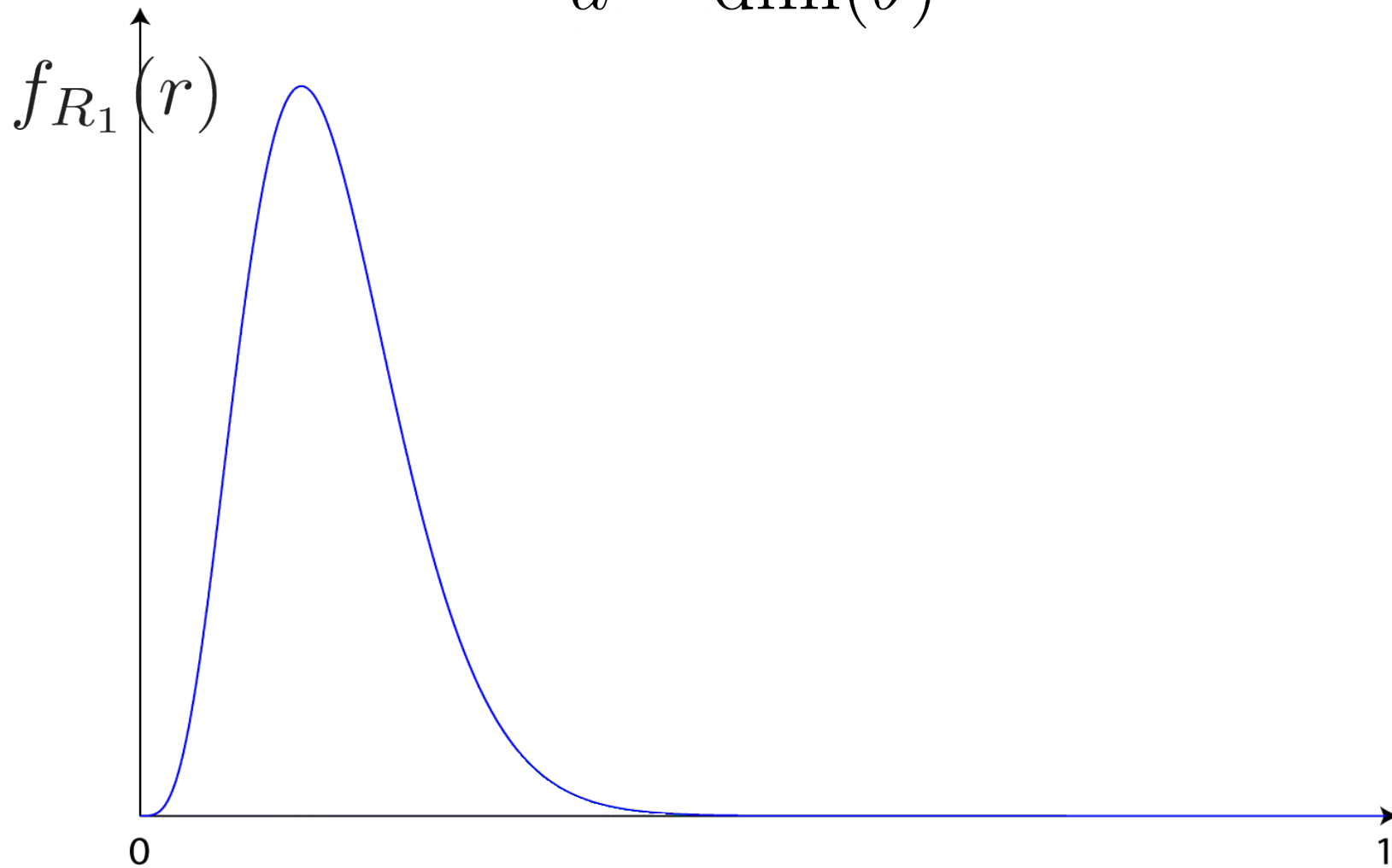
$$\mathbb{P}^N \{R_1 \leq \epsilon_1, R_2 \leq \epsilon_2, \dots, R_{N-d} \leq \epsilon_{N-d}\}$$

$$= \frac{N!}{d!} \int_0^{\epsilon_1} \int_{r_1}^{\epsilon_2} \cdots \int_{r_{N-d-1}}^{\epsilon_{N-d}} r_1^d dr_{N-d} \cdots dr_2 dr_1$$

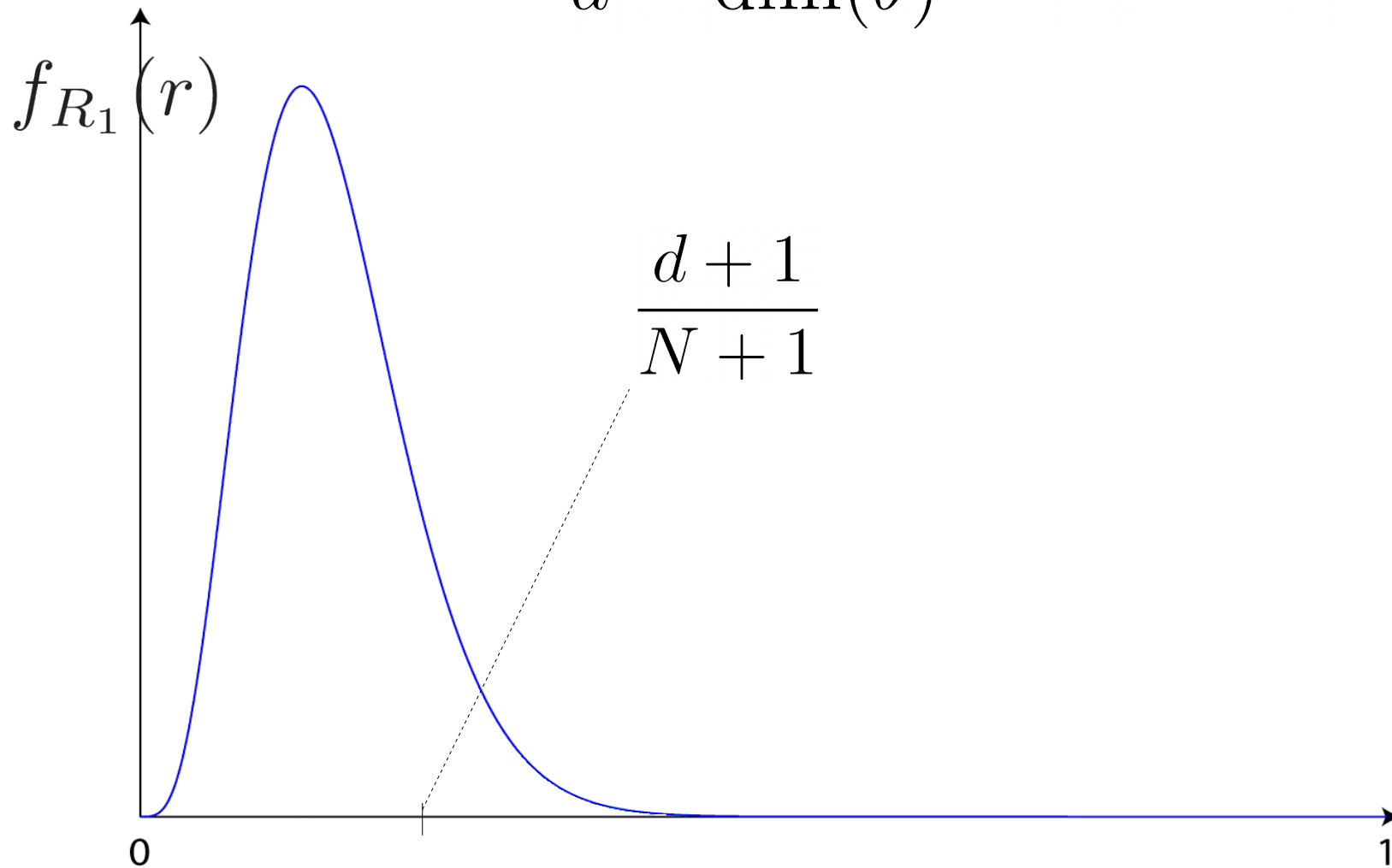
“Fully” vs “non-fully” supported



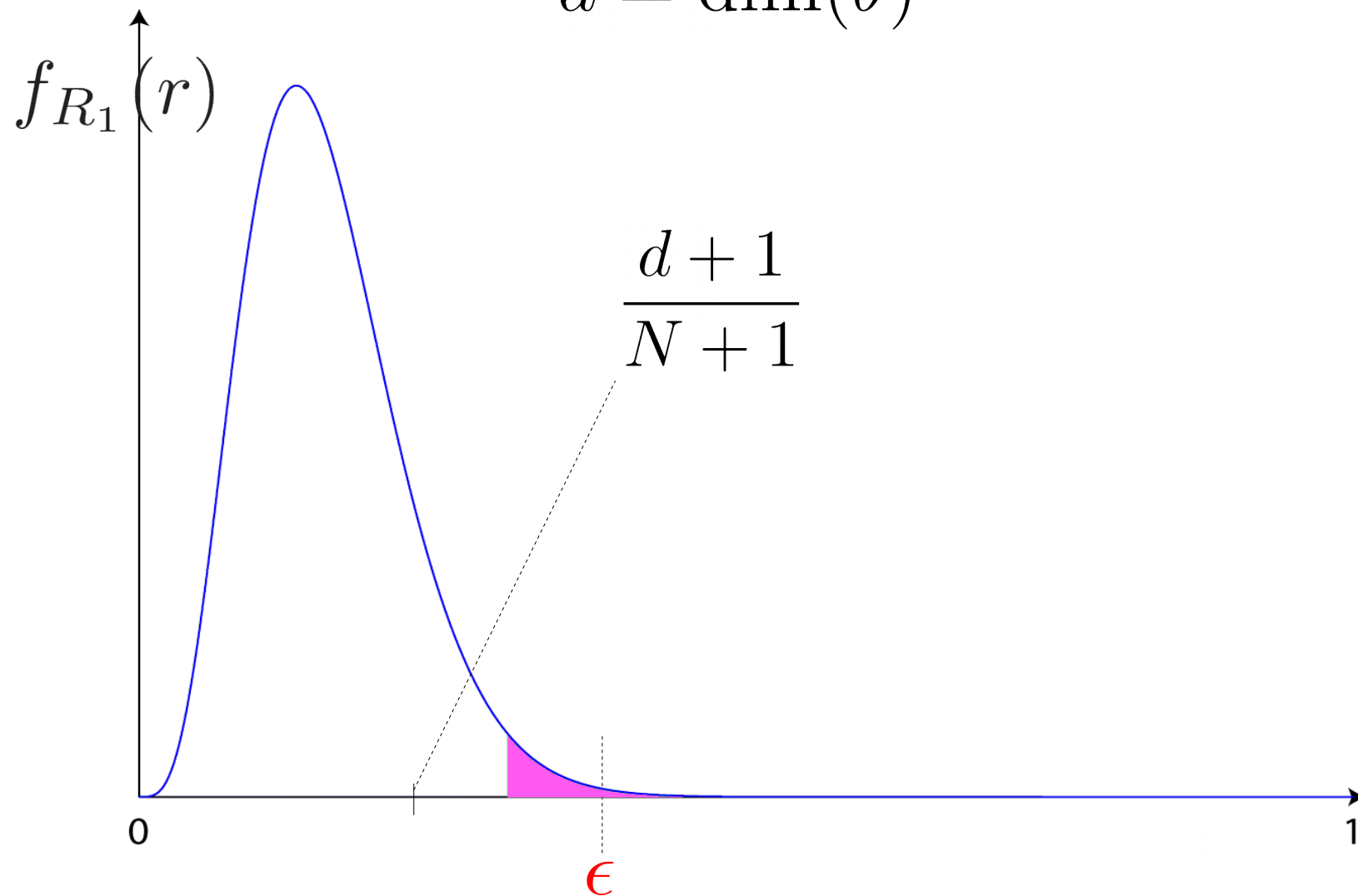
N number of scenarios
 $d = \dim(\theta)$



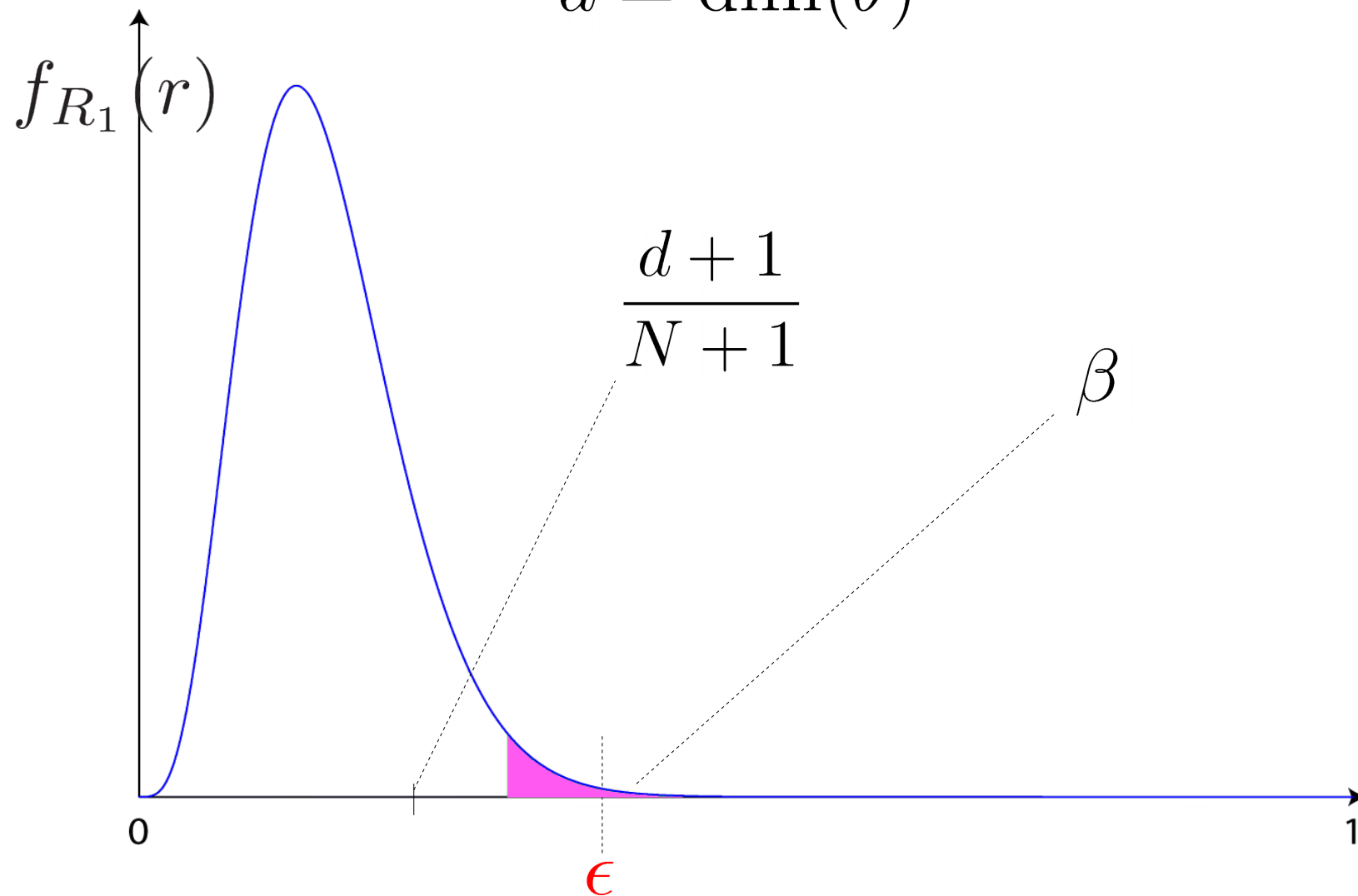
N number of scenarios
 $d = \dim(\theta)$



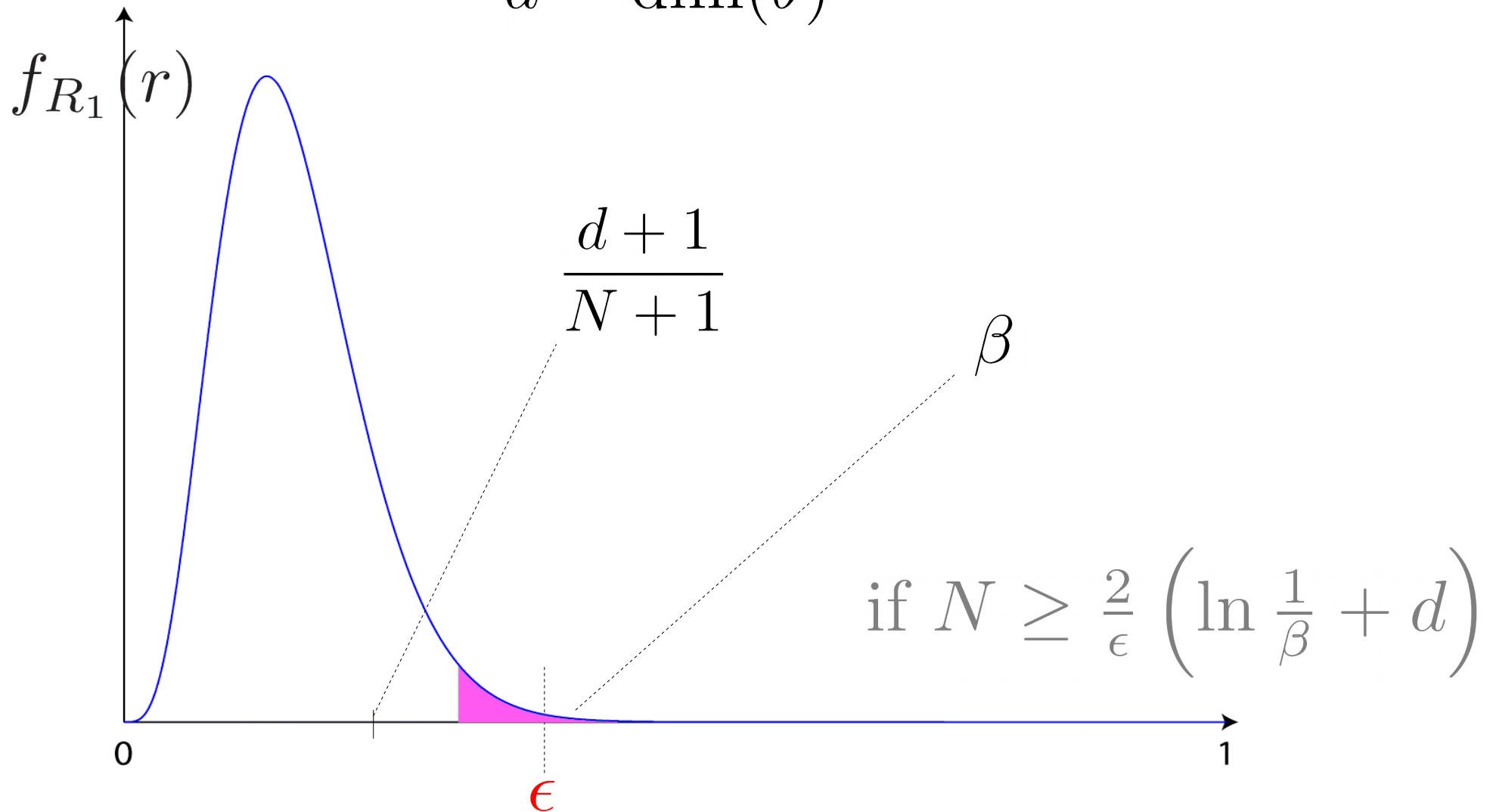
N number of scenarios
 $d = \dim(\theta)$



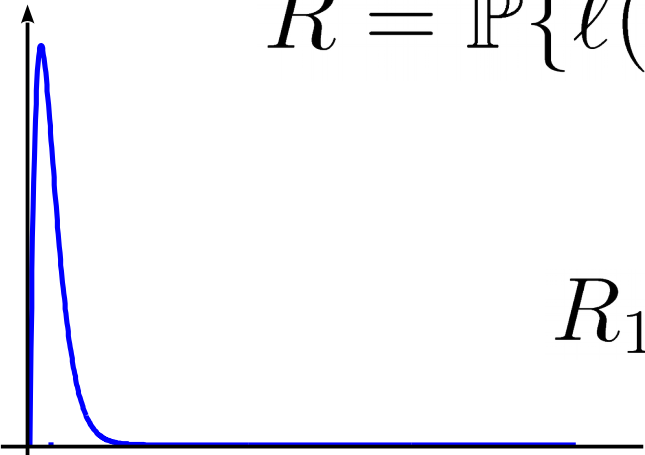
N number of scenarios
 $d = \dim(\theta)$



N number of scenarios
 $d = \dim(\theta)$



$$R = \mathbb{P}\{\ell(\theta^*, \delta) > \ell^*\}$$


 R_1

$$c_1^* = \ell^*$$

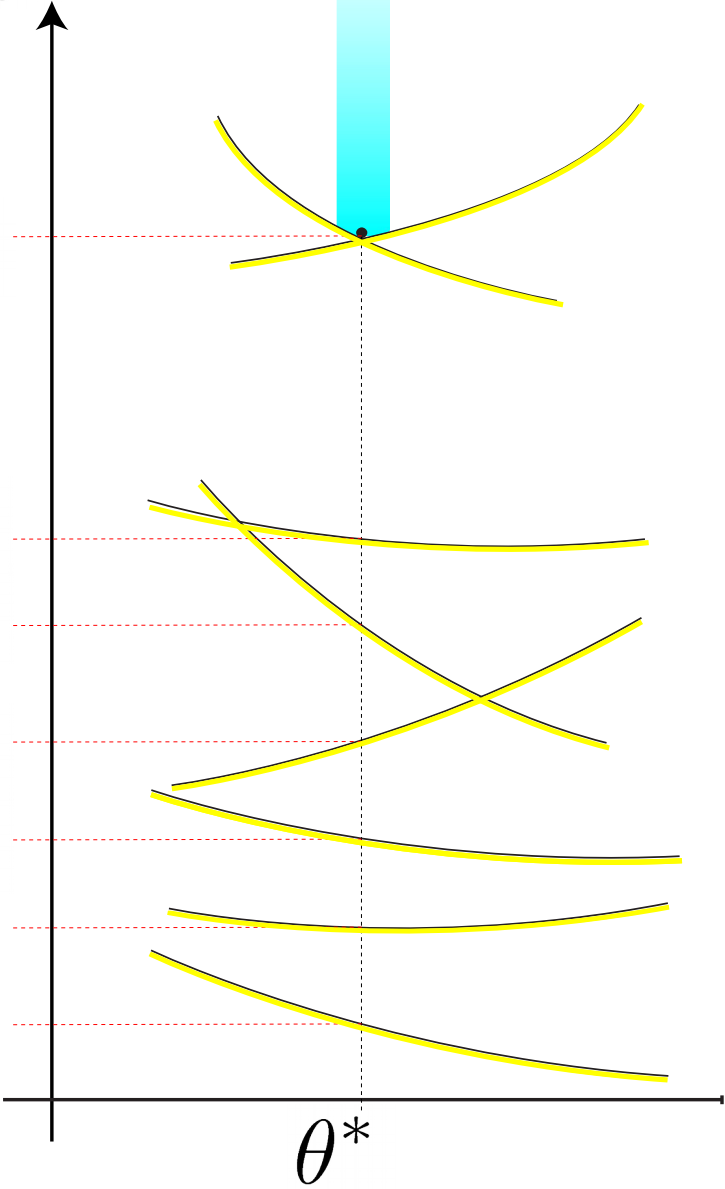
 R_2
 R_3
 R_4
 R_5
 \vdots

c_2^*

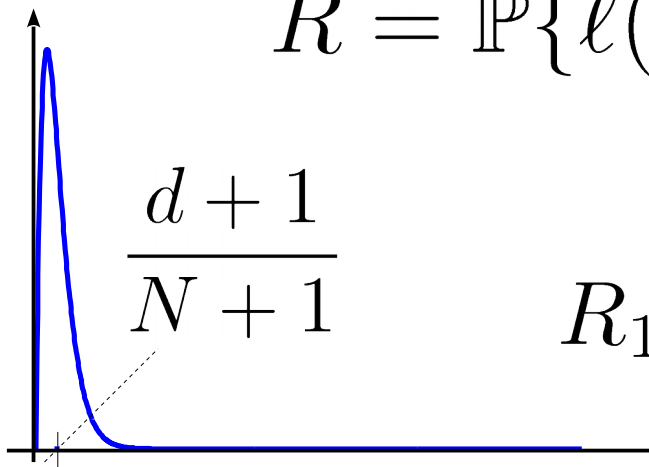
c_3^*

c_4^*

c_5^*

 \vdots

 θ^*

$$R = \mathbb{P}\{\ell(\theta^*, \delta) > \ell^*\}$$



$$c_1^* = \ell^*$$

R_2

R_3

R_4

R_5

\vdots

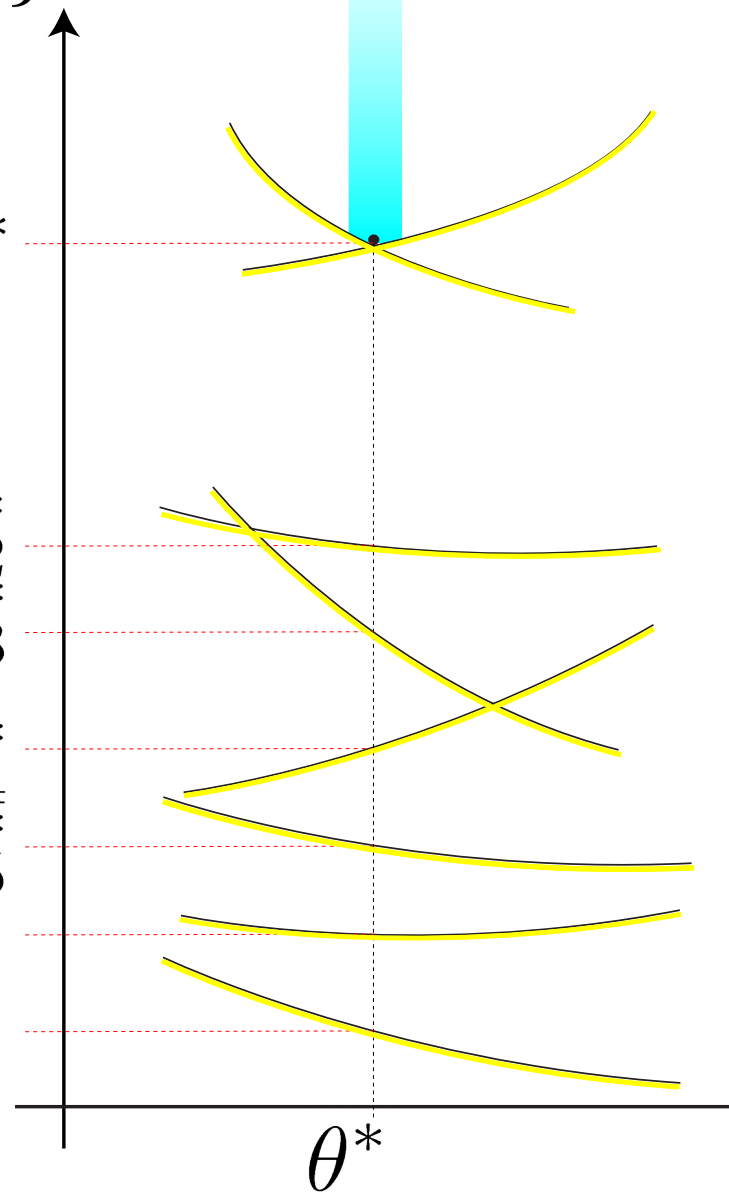
c_2^*

c_3^*

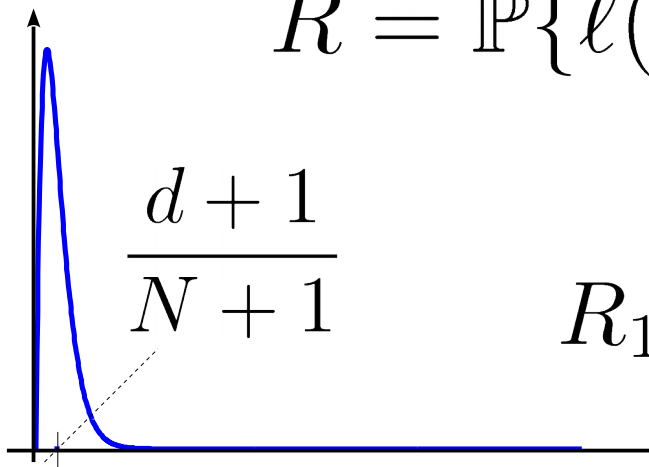
c_4^*

c_5^*

\vdots



$$R = \mathbb{P}\{\ell(\theta^*, \delta) > \ell^*\}$$



$$c_1^* = \ell^*$$

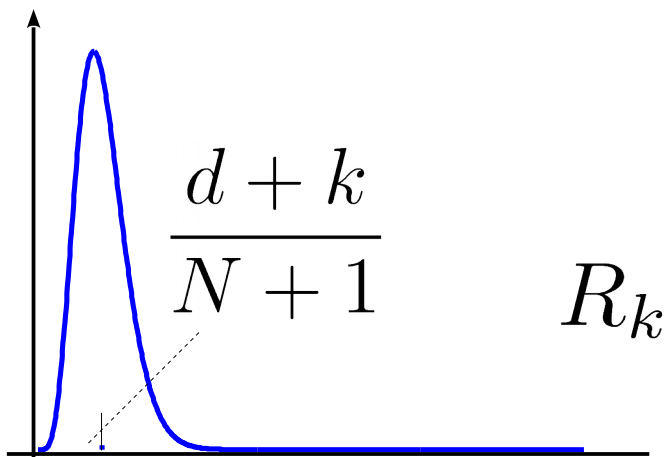
$$R_2$$

$$R_3$$

$$R_4$$

$$R_5$$

$$\vdots$$



$$c_2^*$$

$$c_3^*$$

$$c_4^*$$

$$c_5^*$$

$$\vdots$$

